

# DIPA Flowchart – All you need to know

## 0. Overview of Remote Sensing

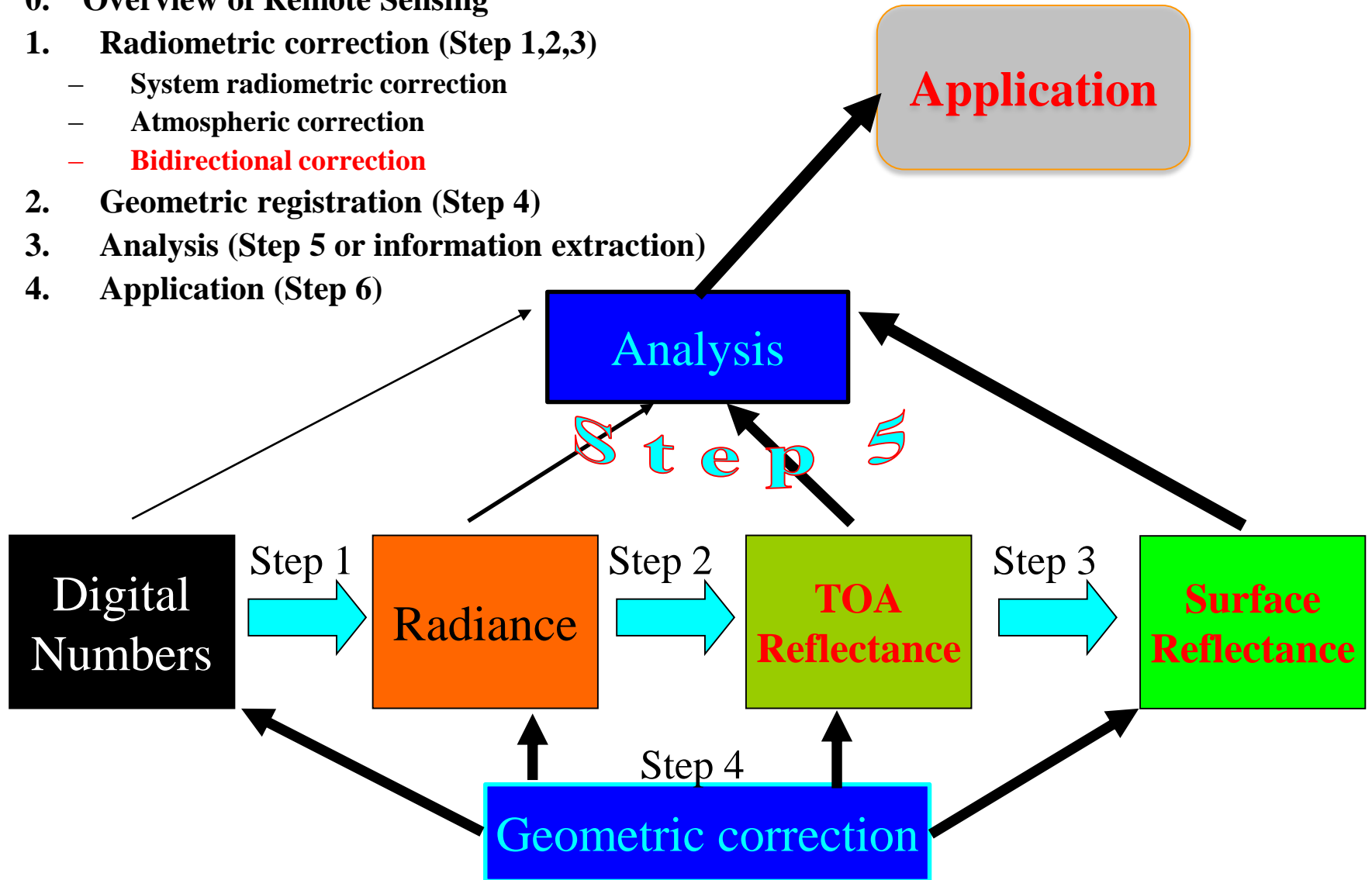
### 1. Radiometric correction (Step 1,2,3)

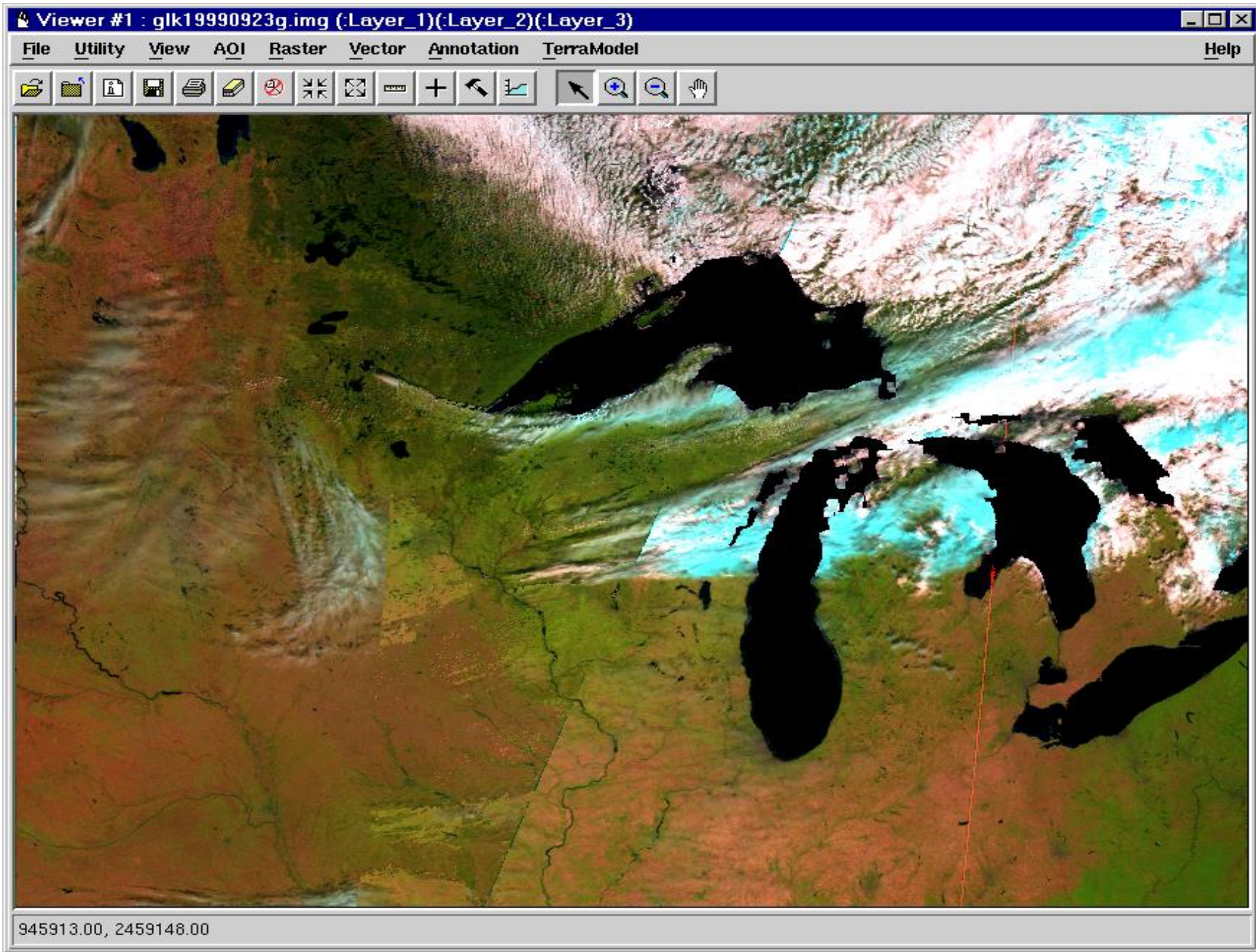
- System radiometric correction
- Atmospheric correction
- **Bidirectional correction**

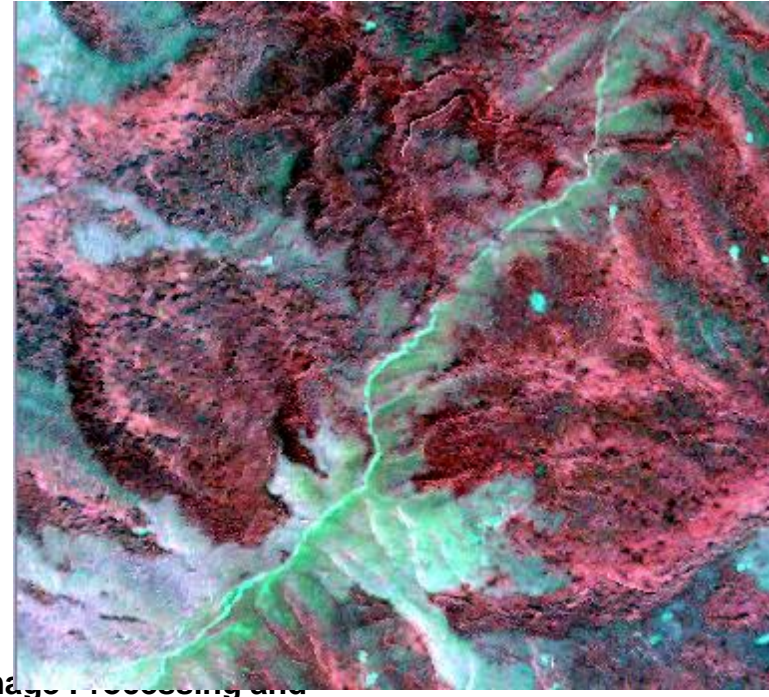
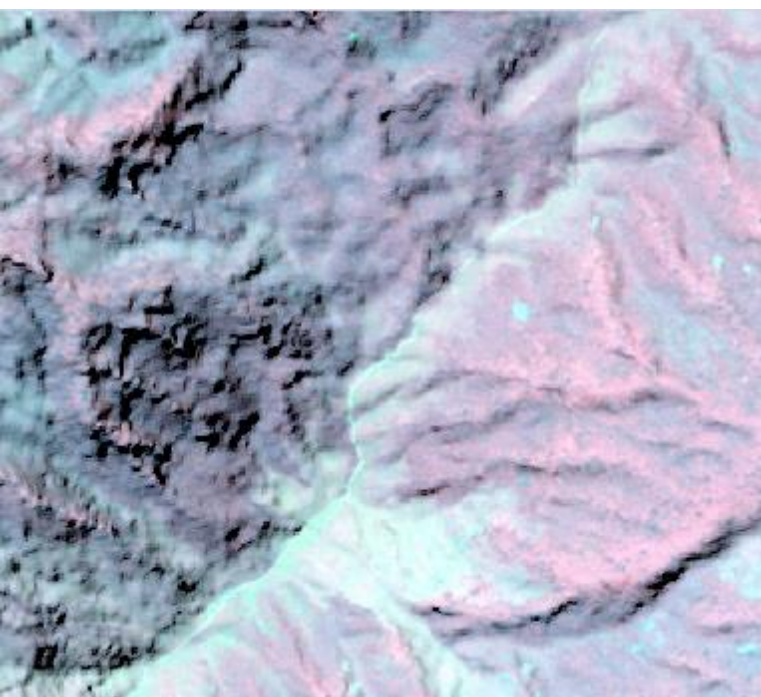
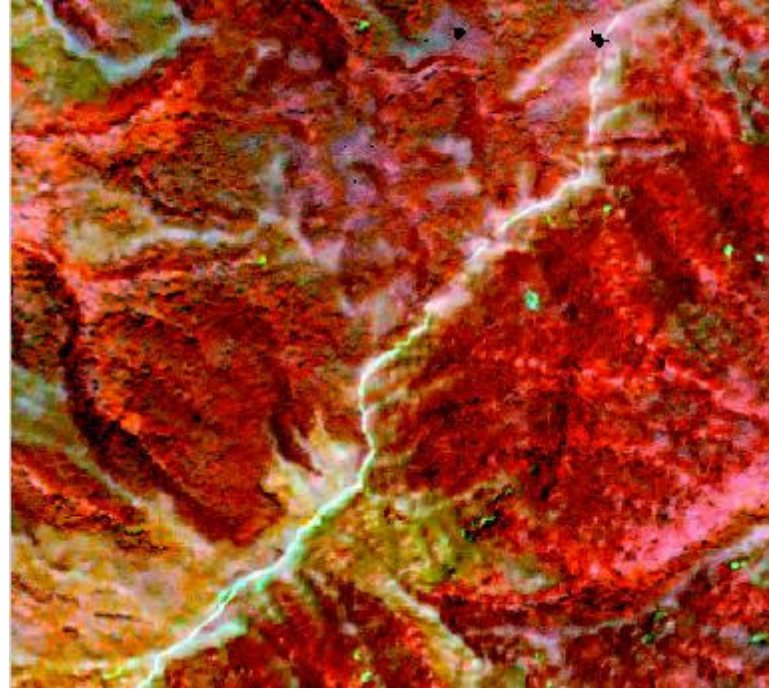
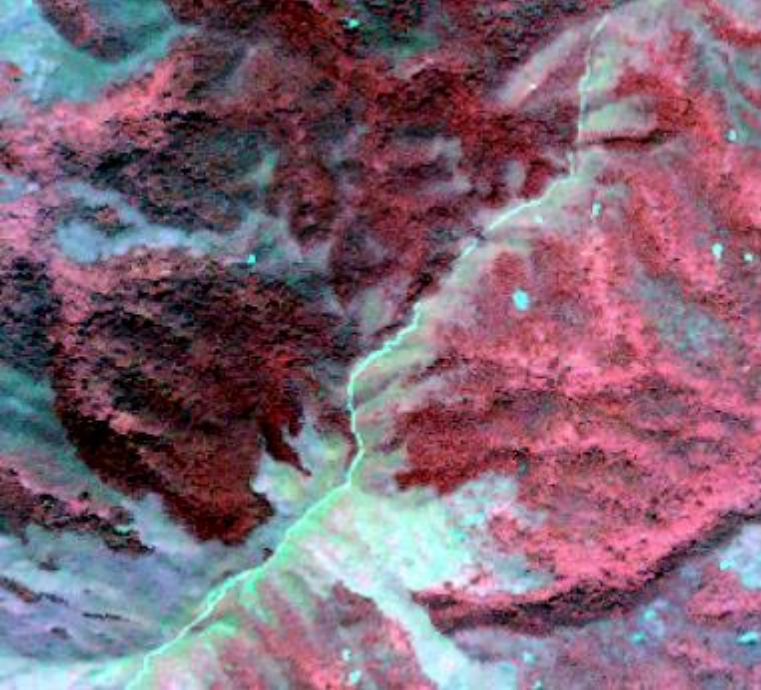
### 2. Geometric registration (Step 4)

### 3. Analysis (Step 5 or information extraction)

### 4. Application (Step 6)



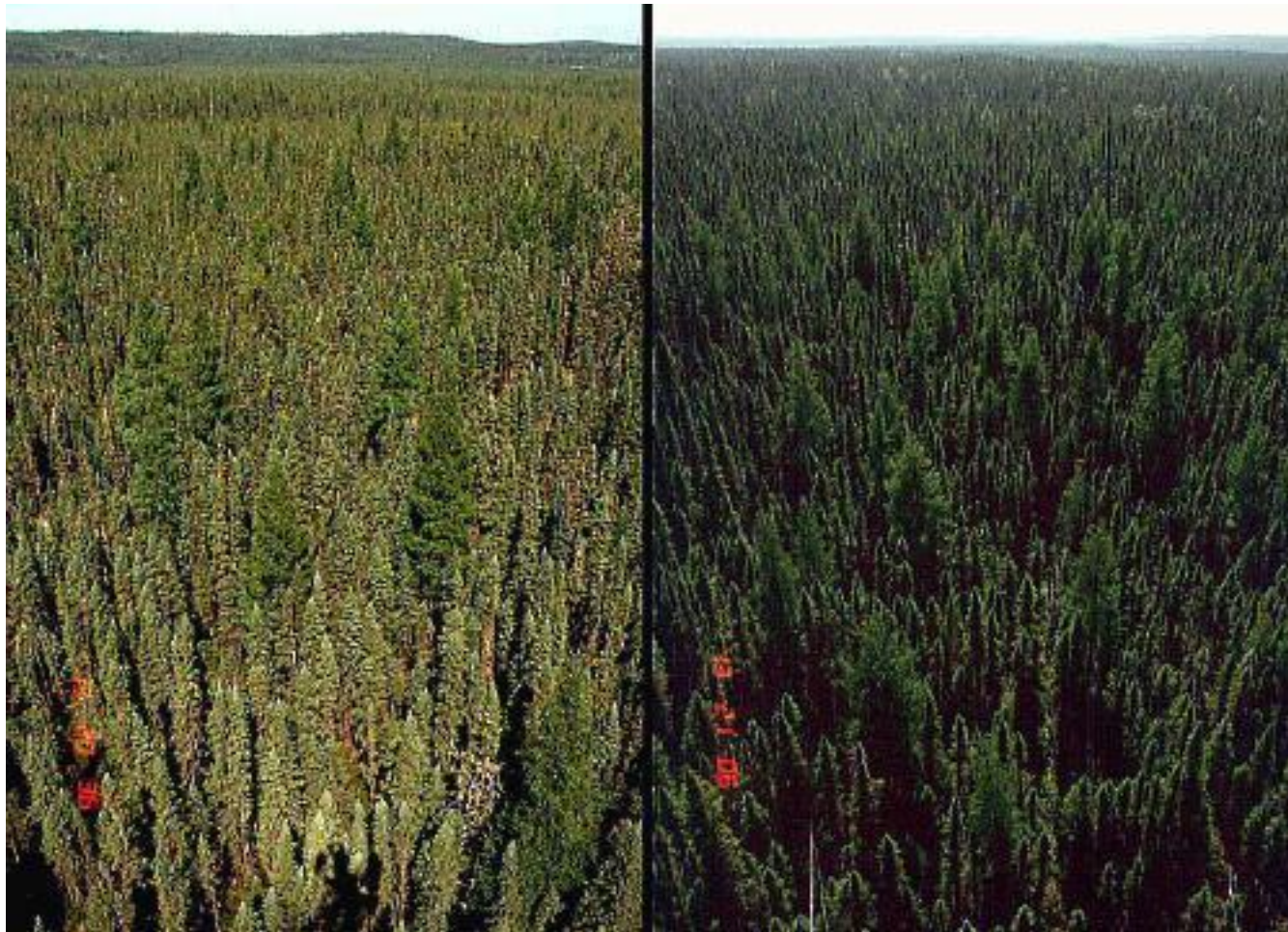




IKONOS False  
Colour Image, 7  
Sept 2002, a  
ridge from top  
right to bottom  
left with sunlight  
coming from the  
bottom  
right, Lam Tseun  
Country Park. (a)  
Original image.  
(b) Result of  
cosine correction.  
(c) Result of  
Minnaert  
correction. (d)  
Result of 2-  
stage  
normalization  
Cosine Minnaert

From  
Law & Nichol

# BRDF



Backscatter direction

Forward scatter direction

# BRDF



Backscatter direction

Forward scatter direction

# BRDF



Backscatter direction

Forward scatter direction

# Bidirectional Effect, Modeling and Correction

## Topics:

- Directional effect
- Modeling
- Correction

# BRDF

## BRDF: Bidirectional Reflectance Distribution Function

1. Illumination and viewing geometry
2. Wavelength
3. Structural and optical properties of the surface (shadow-casting, multiple scattering, mutual shadowing, transmission, reflection, absorption and emission by surface elements, facet orientation distribution and facet density).

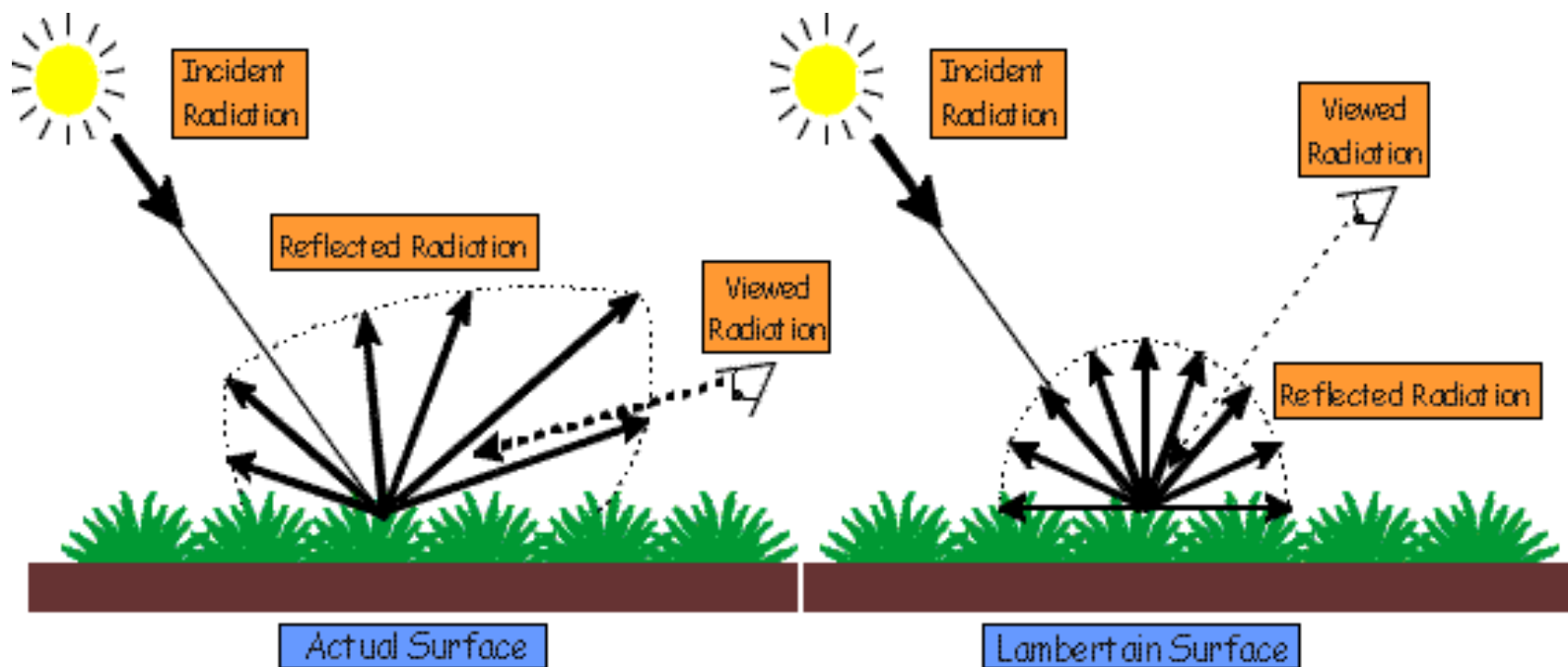
BRDF is needed in remote sensing for the correction of view and illumination angle effects, for deriving albedo, for land cover classification, for cloud detection, for atmospheric correction and other applications.

It should not be overlooked that the BRDF simply describes what we all observe every day: that objects look differently when viewed from different angles, and when illuminated from different directions. For that reasons painters and photographers have for centuries explored the appearance of trees and urban areas under a variety of conditions, accumulating knowledge about "how things look", knowledge that today we'd call BRDF-related knowledge.



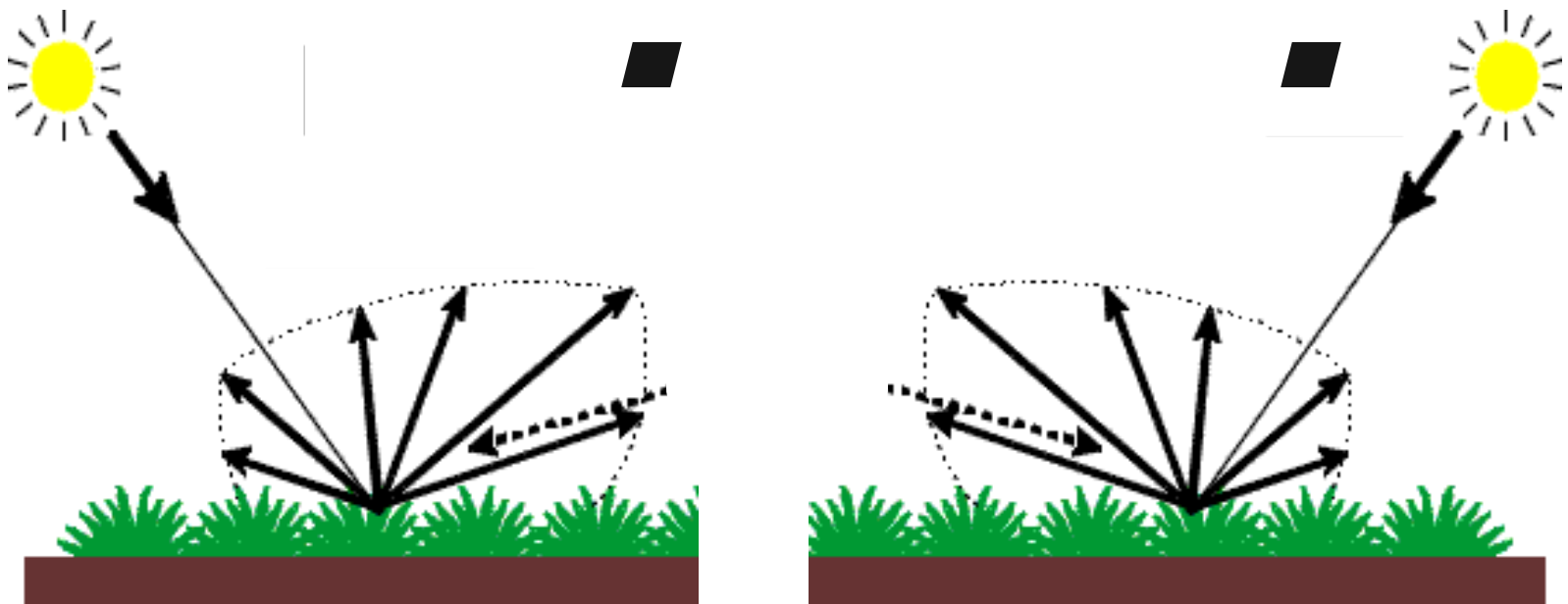
# Bi-directional Reflectance Distribution Function (BRDF)

Light reflecting off of a surface is rarely isotropic. Most surfaces exhibit anisotropic reflectance (reflectance amount varies with direction).



# Bi-directional Reflectance Distribution Function (BRDF)

Light reflecting off of a surface is rarely isotropic. Most surfaces exhibit anisotropic reflectance (reflectance amount varies with direction).



Cotton field at ~80% cover  
(Shadows)

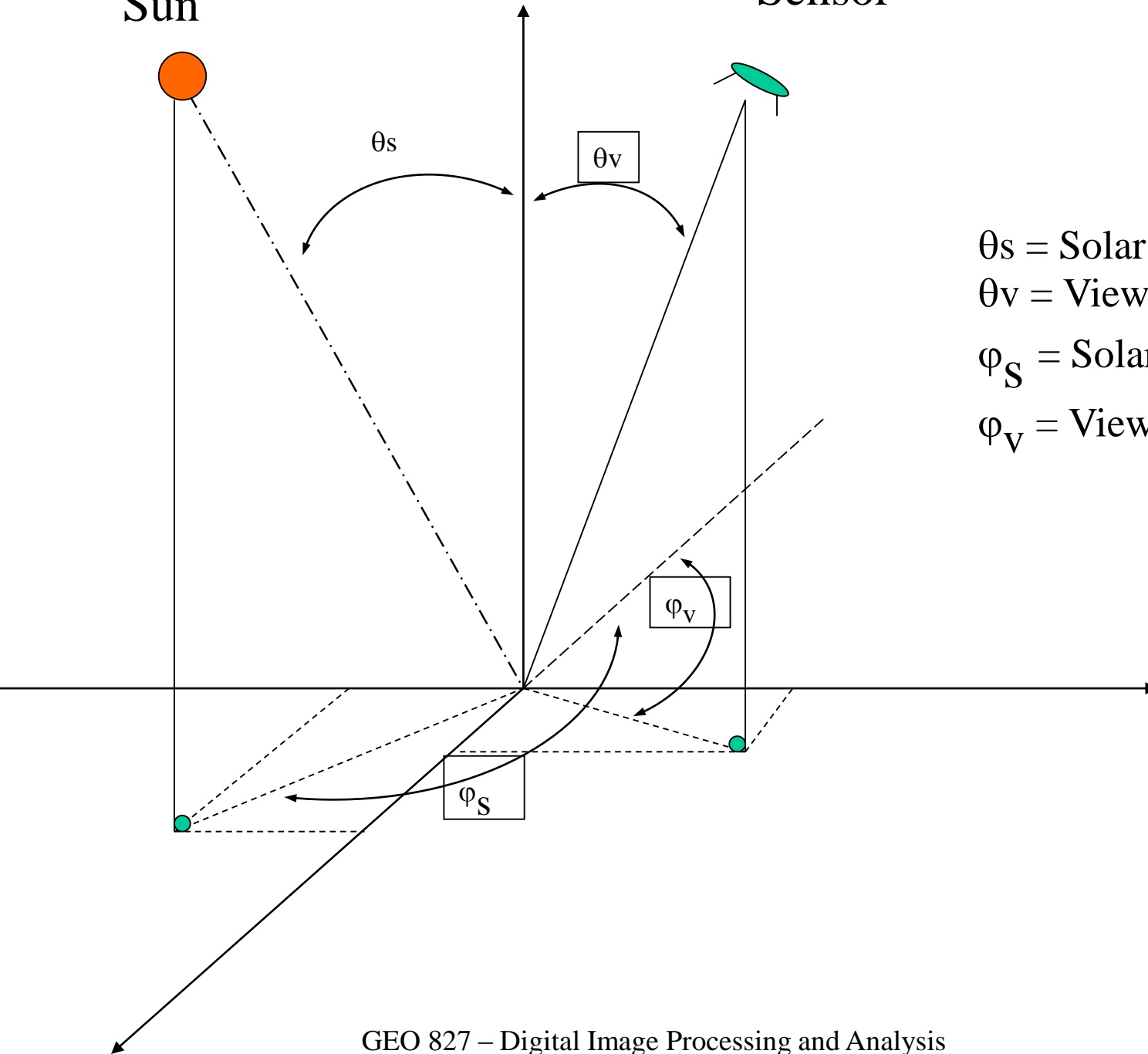


# How to Measure BRDF?

- Practically impossible to measure!
  - Would have to measure EVERY possible angle
- But can be approximated by discrete measurements,
- With BRDF models, bidirectional effect can be normalized.
- Every different surface/landscape should have a different BRDF

Sun

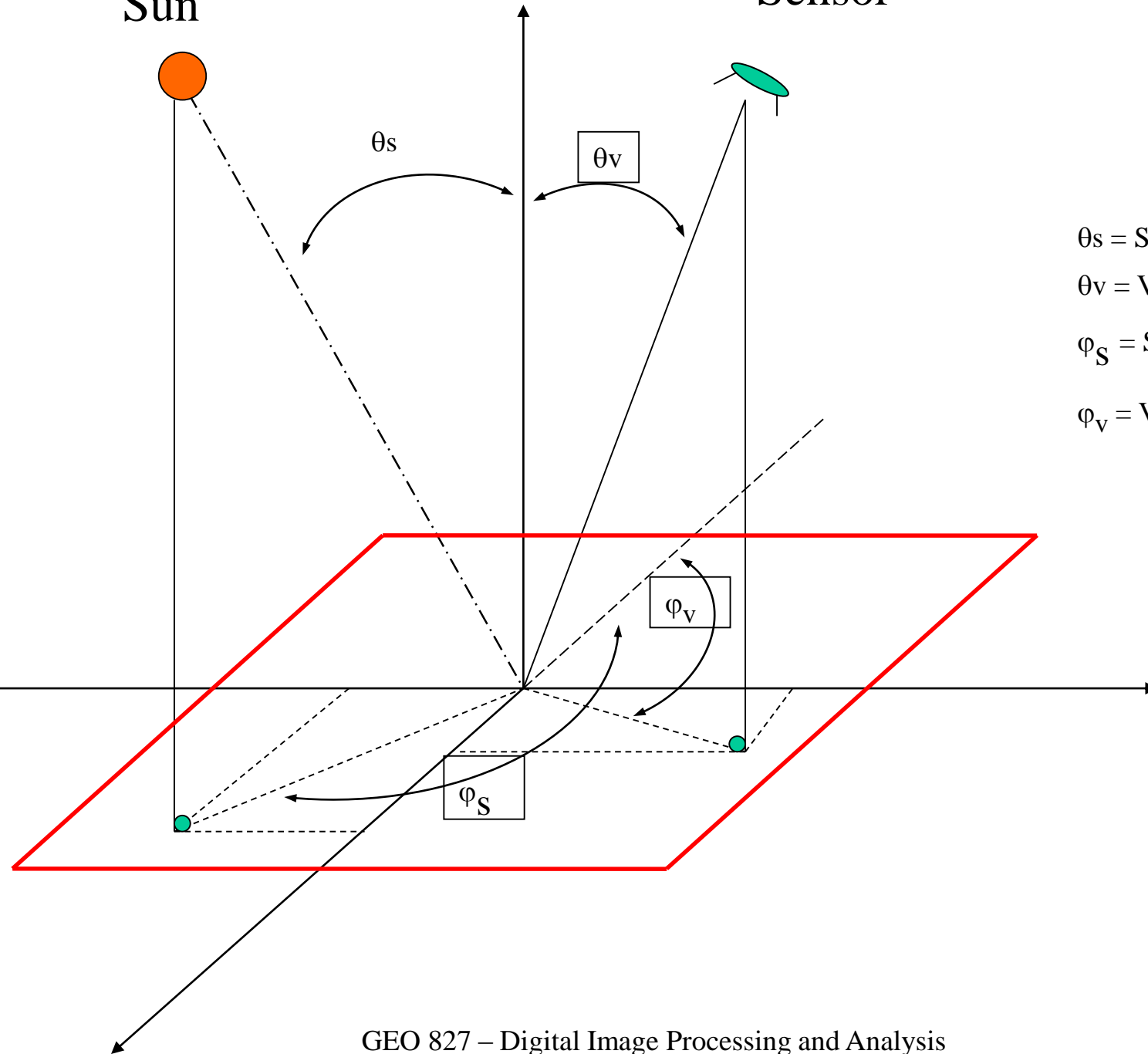
Sensor



$\theta_s$  = Solar zenith angle  
 $\theta_v$  = View zenith angle  
 $\varphi_s$  = Solar azimuth angle  
 $\varphi_v$  = View azimuth angle

Sun

Sensor



$\theta_s$  = Solar zenith angle

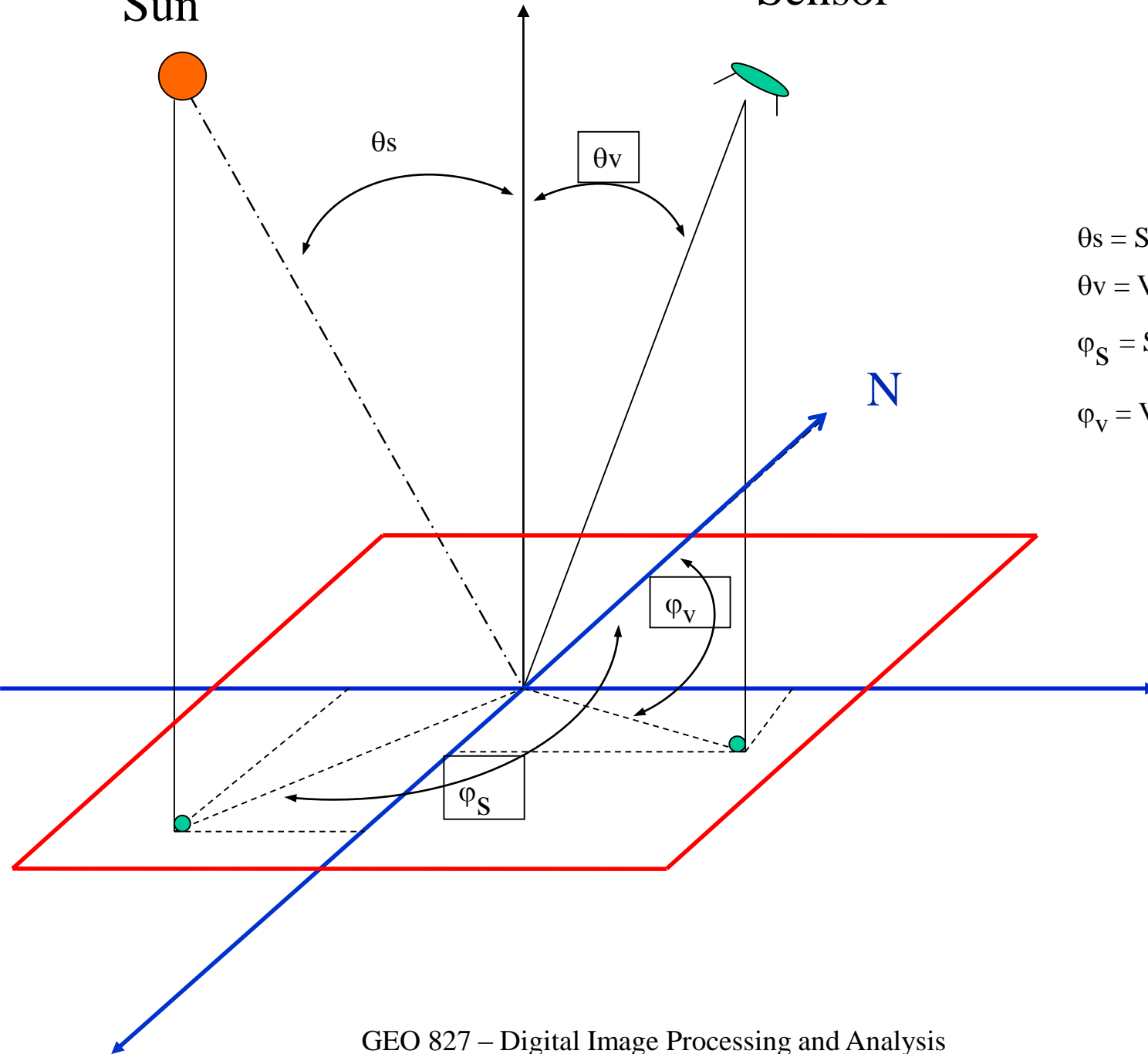
$\theta_v$  = View zenith angle

$\varphi_s$  = Solar azimuth angle

$\varphi_v$  = View azimuth angle

Sun

Sensor



$\theta_s$  = Solar zenith angle

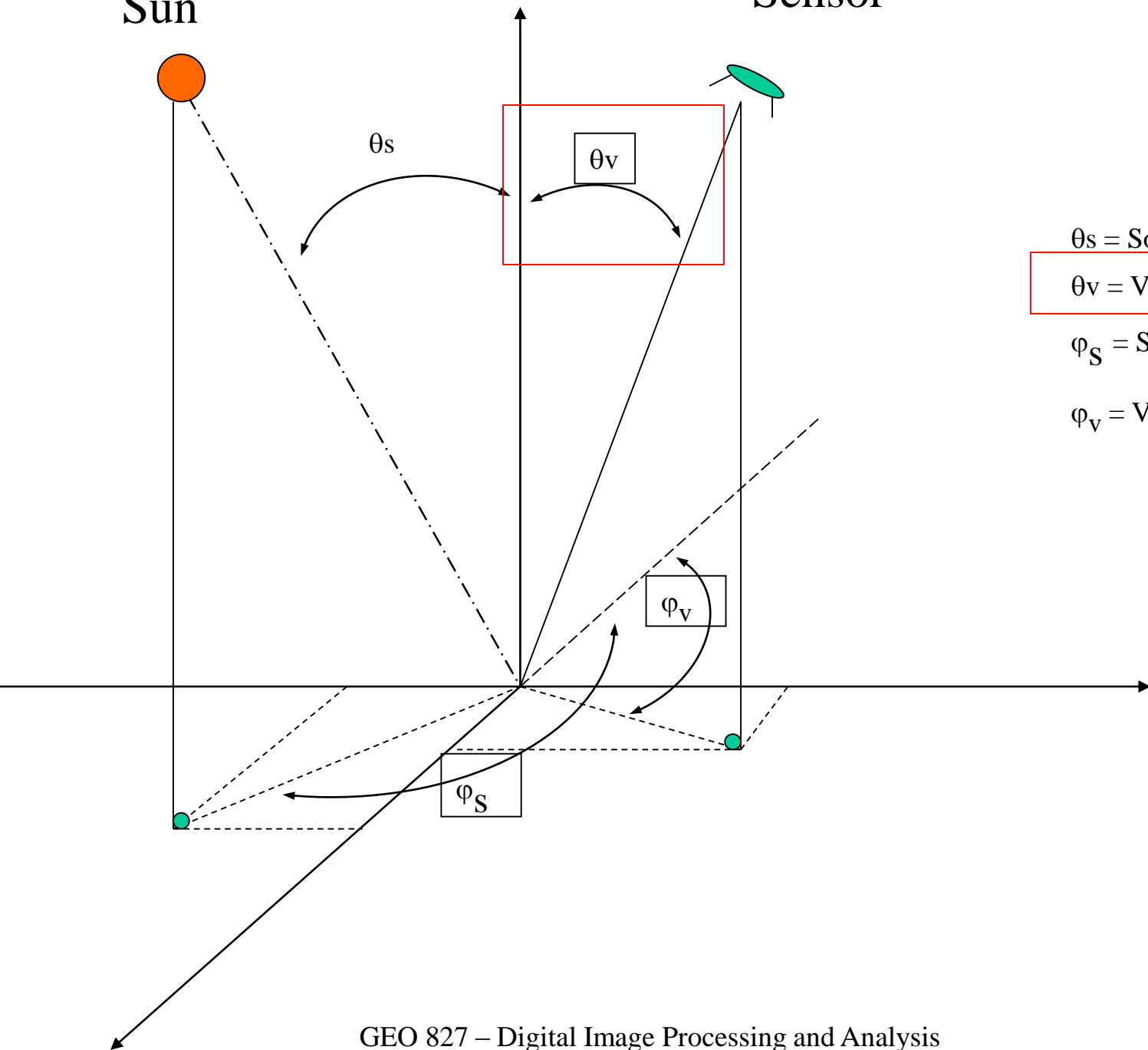
$\theta_v$  = View zenith angle

$\phi_s$  = Solar azimuth angle

$\phi_v$  = View azimuth angle

Sun

Sensor

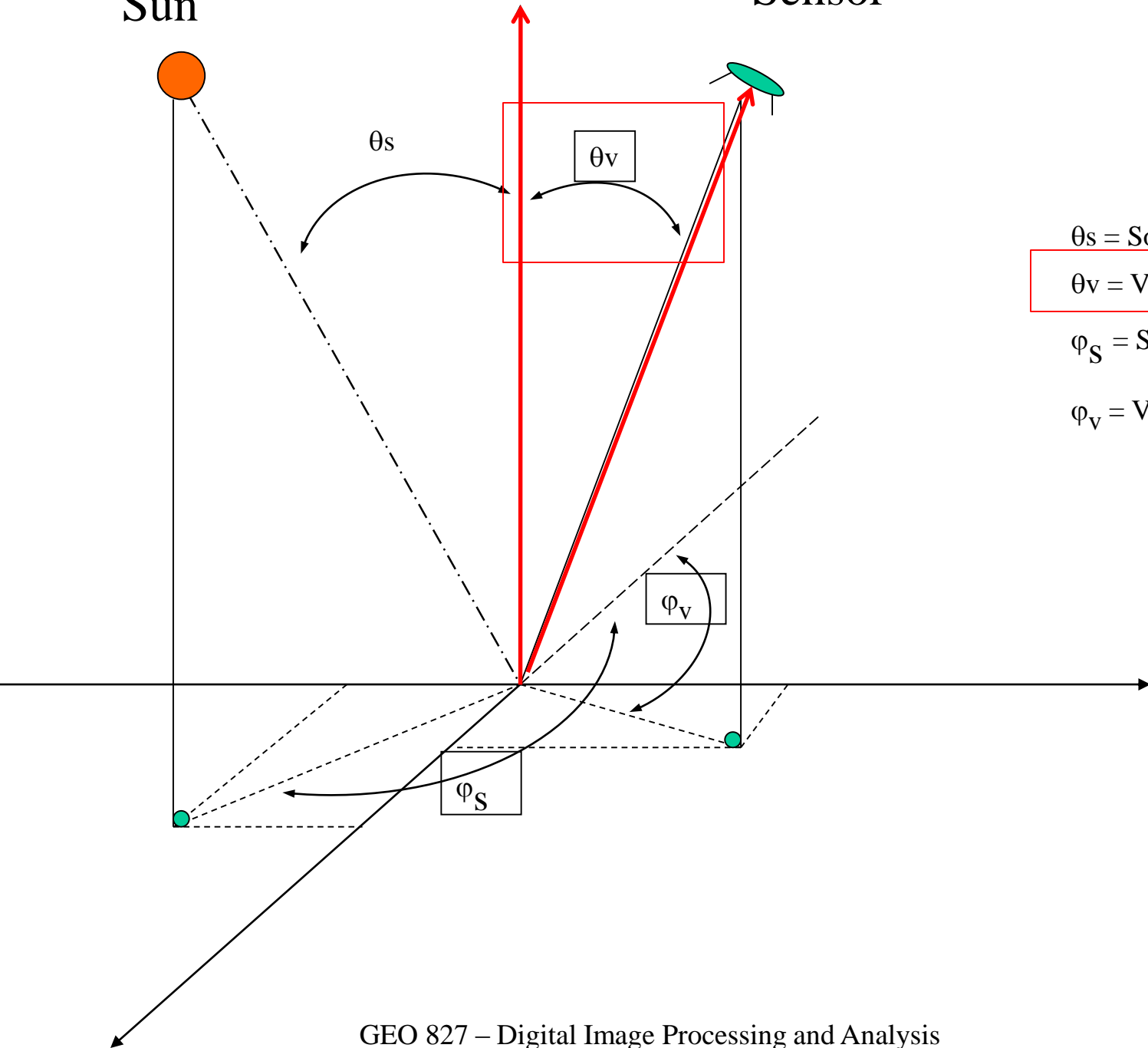


- $\theta_s$  = Solar zenith angle
- $\theta_v$  = View zenith angle
- $\phi_s$  = Solar azimuth angle
- $\phi_v$  = View azimuth angle



Sun

Sensor



$\theta_s$  = Solar zenith angle

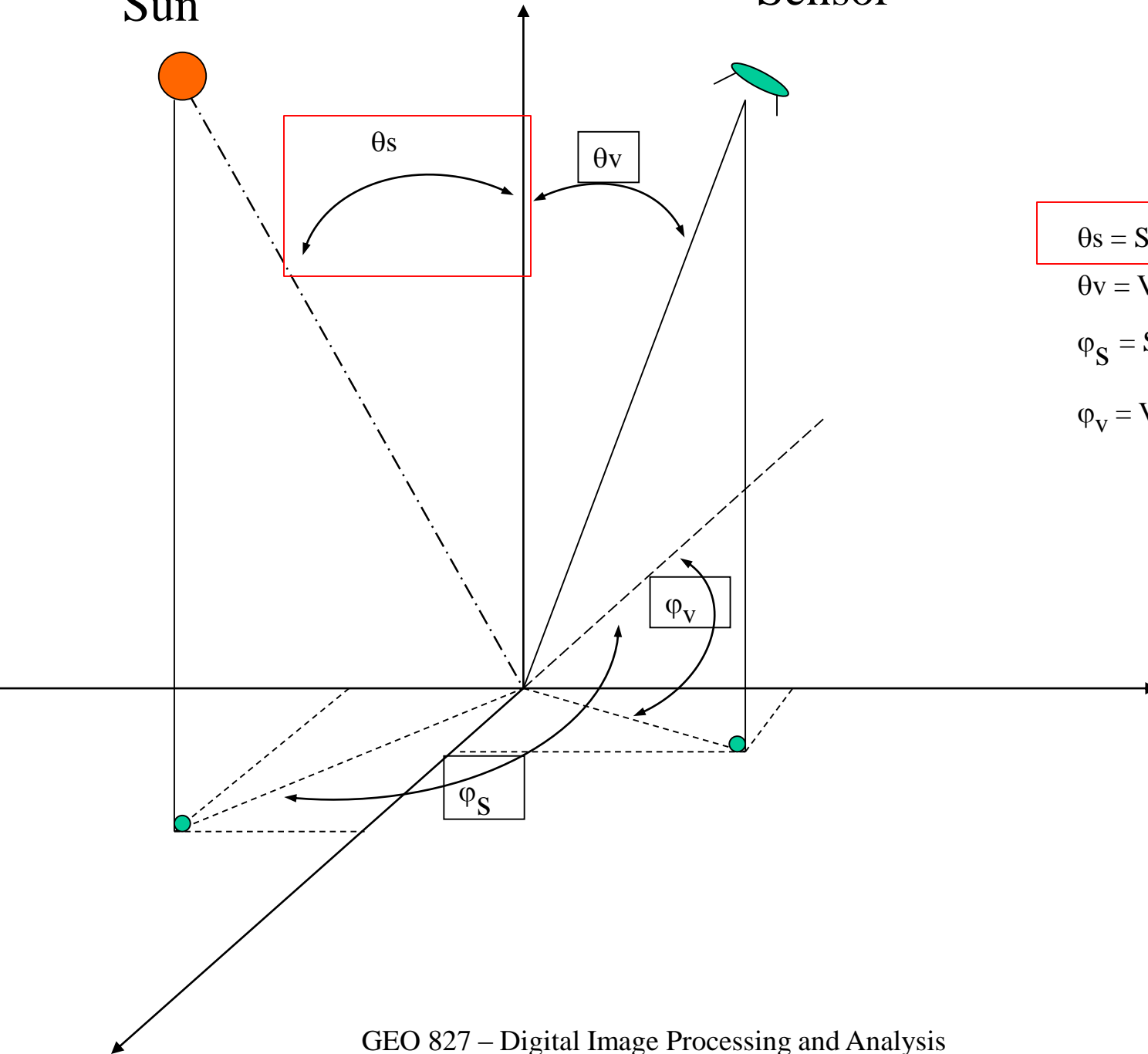
$\theta_v$  = View zenith angle

$\phi_s$  = Solar azimuth angle

$\phi_v$  = View azimuth angle

Sun

Sensor



$\theta_s$  = Solar zenith angle

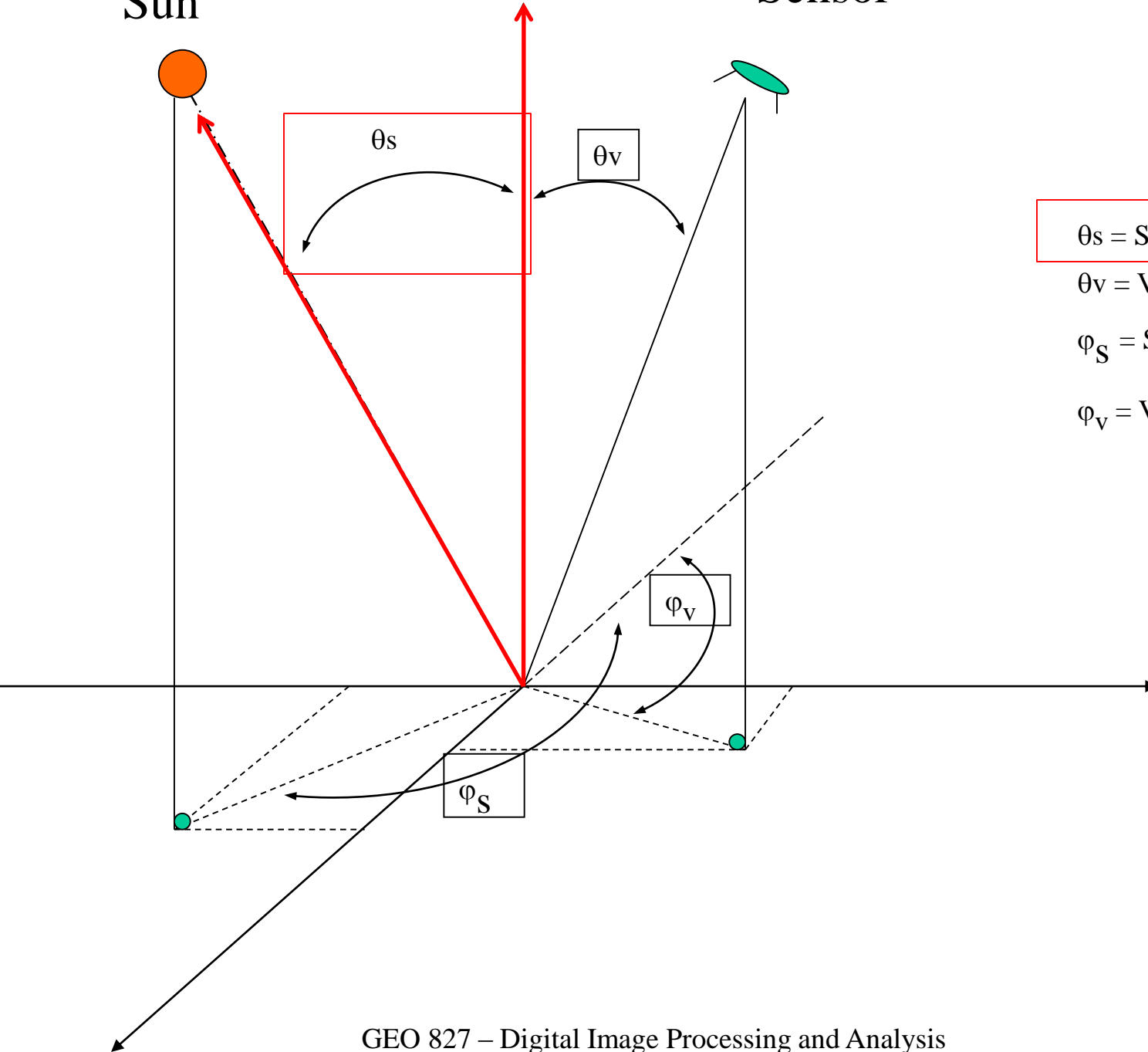
$\theta_v$  = View zenith angle

$\varphi_s$  = Solar azimuth angle

$\varphi_v$  = View azimuth angle

Sun

Sensor



$\theta_s$  = Solar zenith angle

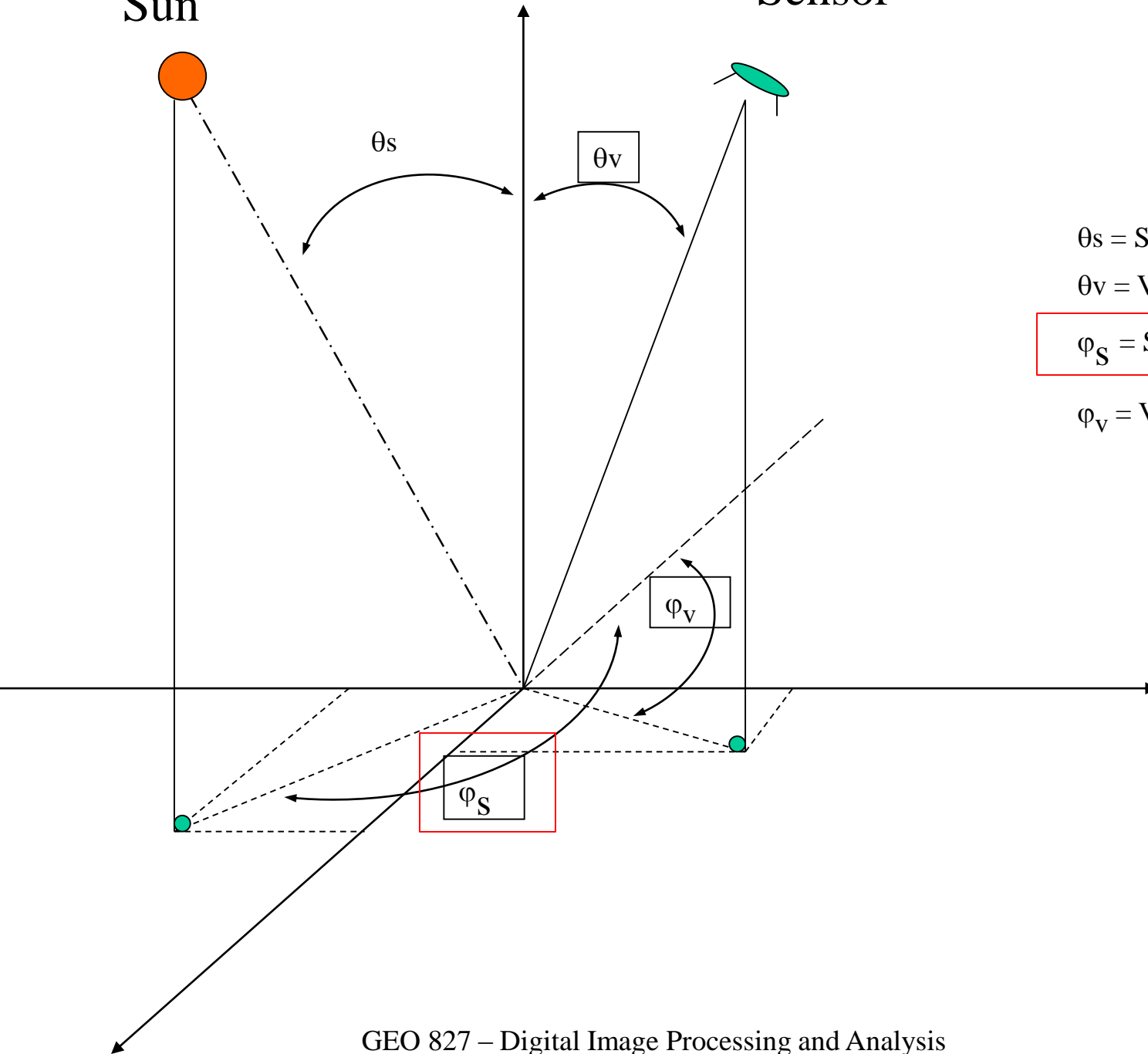
$\theta_v$  = View zenith angle

$\phi_s$  = Solar azimuth angle

$\phi_v$  = View azimuth angle

Sun

Sensor



$\theta_s$  = Solar zenith angle

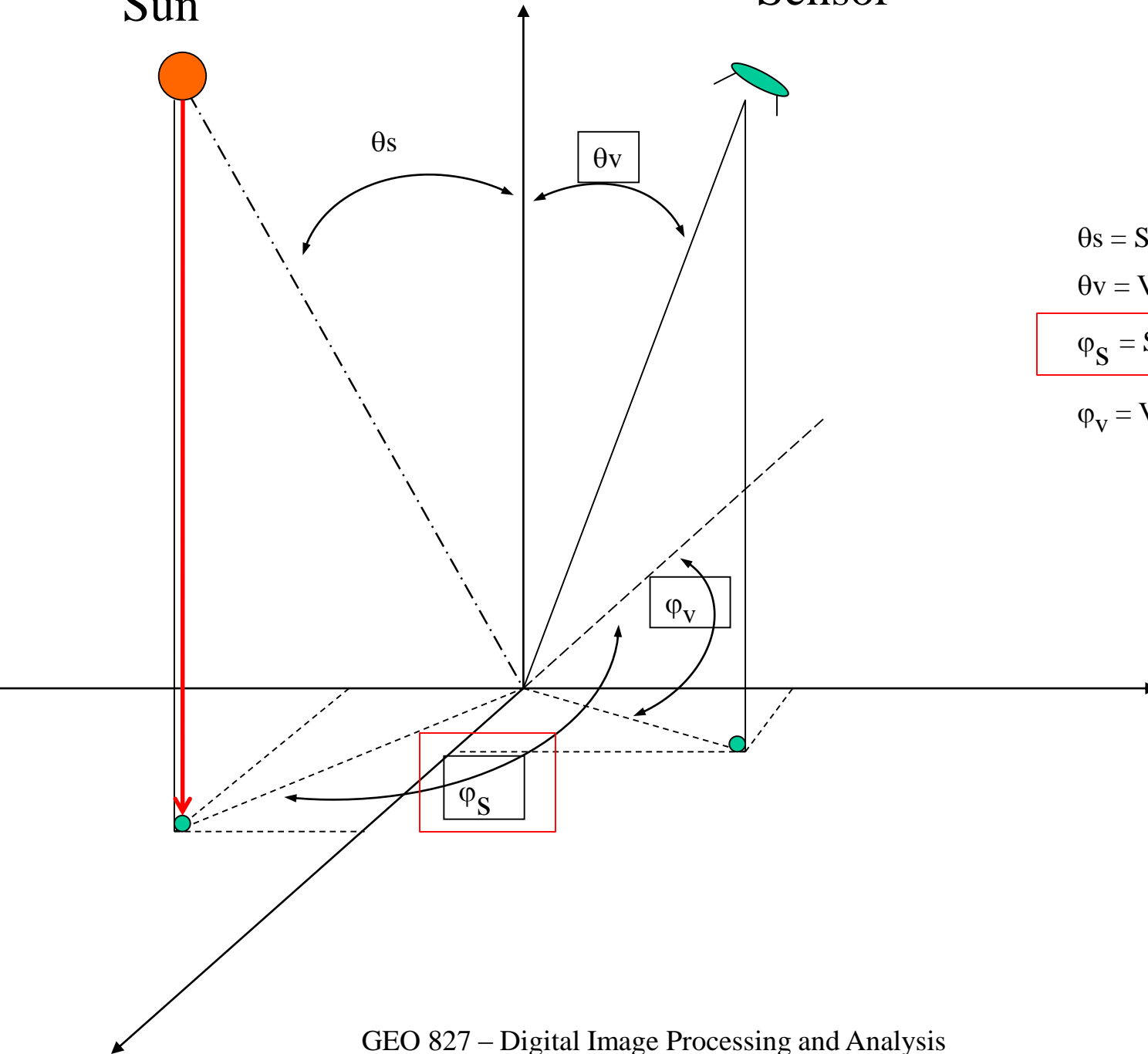
$\theta_v$  = View zenith angle

$\varphi_s$  = Solar azimuth angle

$\varphi_v$  = View azimuth angle

Sun

Sensor



$\theta_s$  = Solar zenith angle

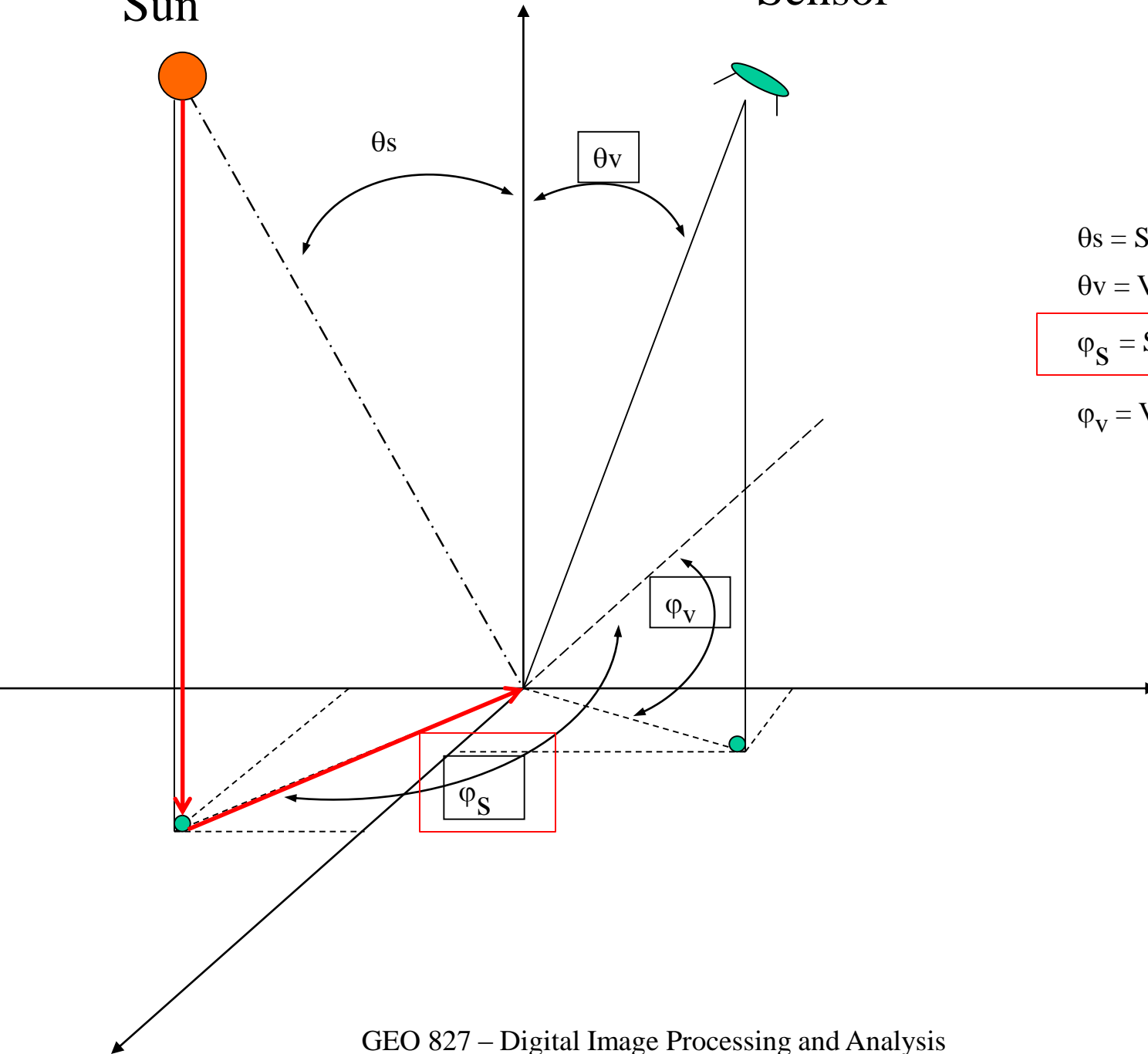
$\theta_v$  = View zenith angle

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$\varphi_v$  = View azimuth angle

Sun

Sensor



$\theta_s$  = Solar zenith angle

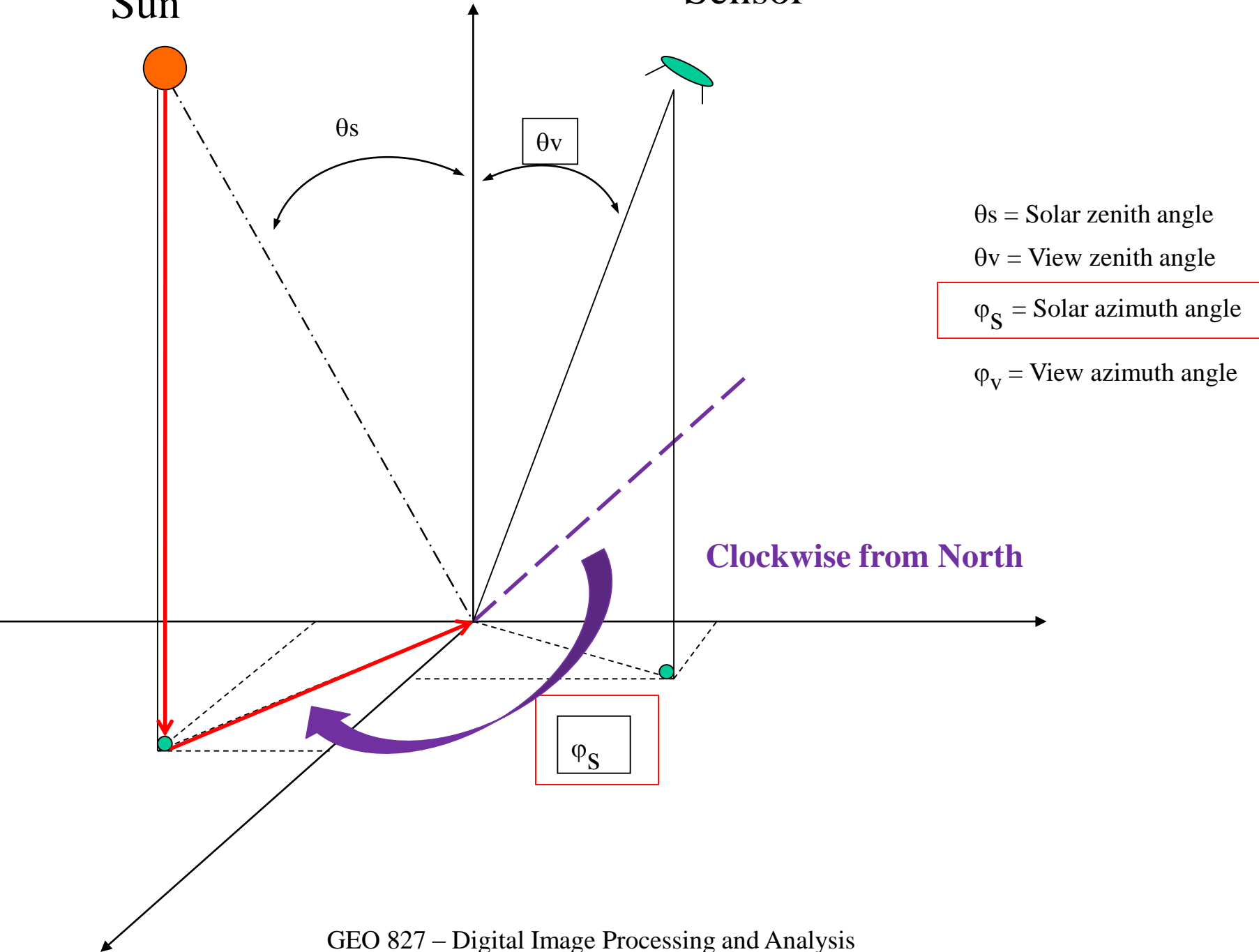
$\theta_v$  = View zenith angle

$\phi_s$  = Solar azimuth angle

$\phi_v$  = View azimuth angle

Sun

Sensor



$\theta_s = \text{Solar zenith angle}$

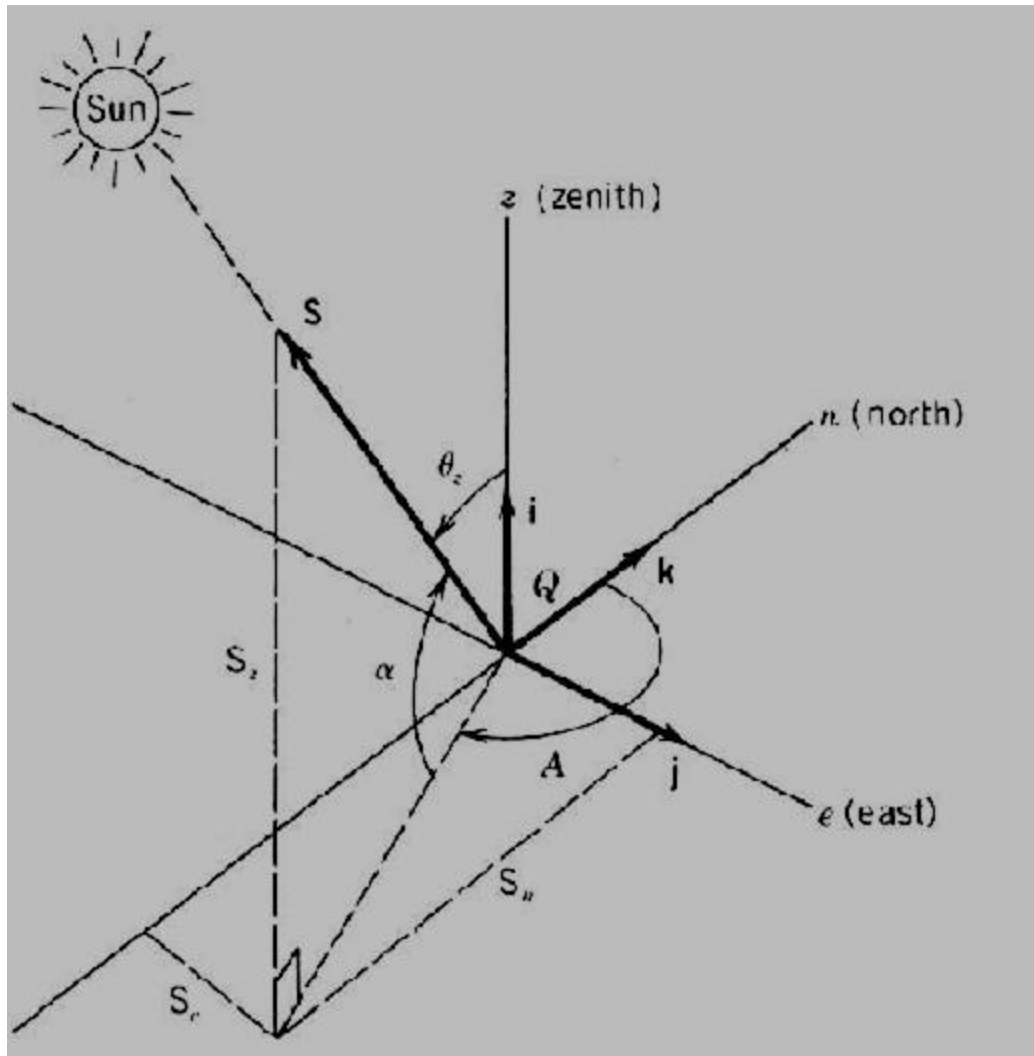
$\theta_v = \text{View zenith angle}$

$\varphi_S = \text{Solar azimuth angle}$

$\varphi_v = \text{View azimuth angle}$

Clockwise from North

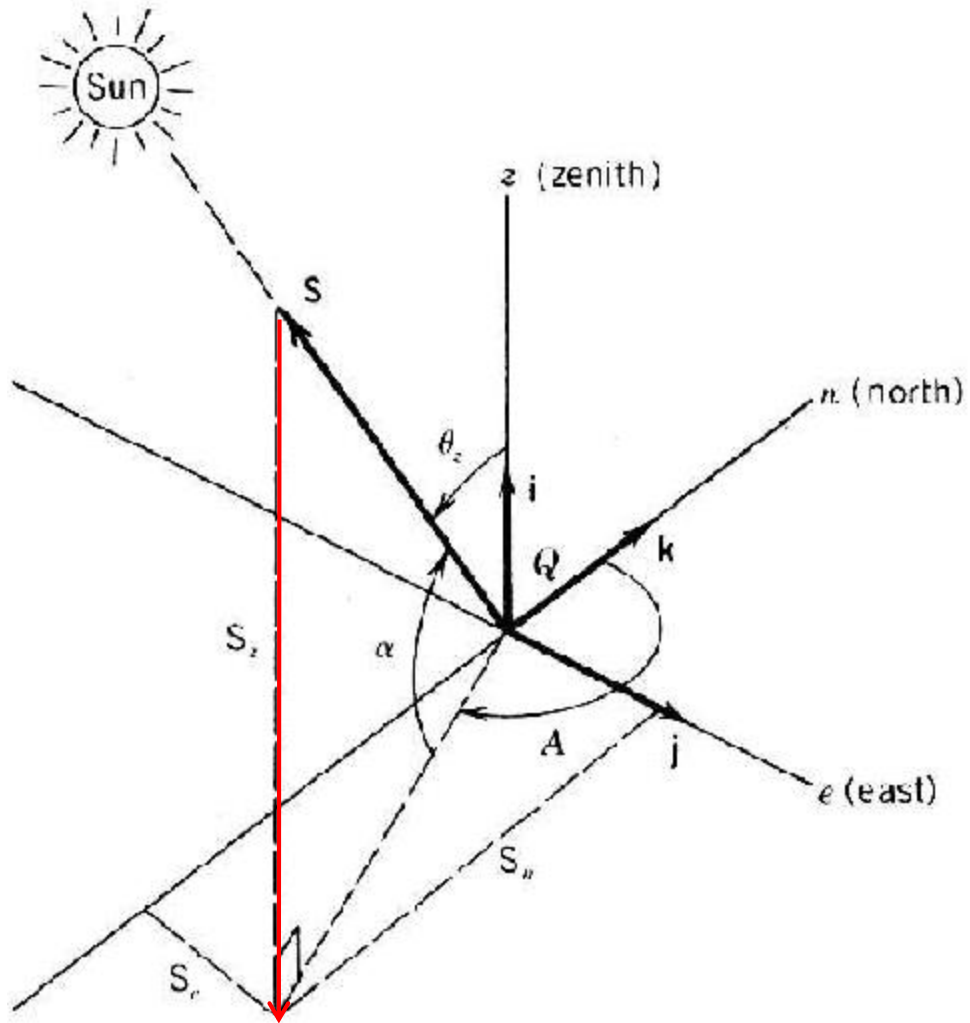
$\varphi_S$



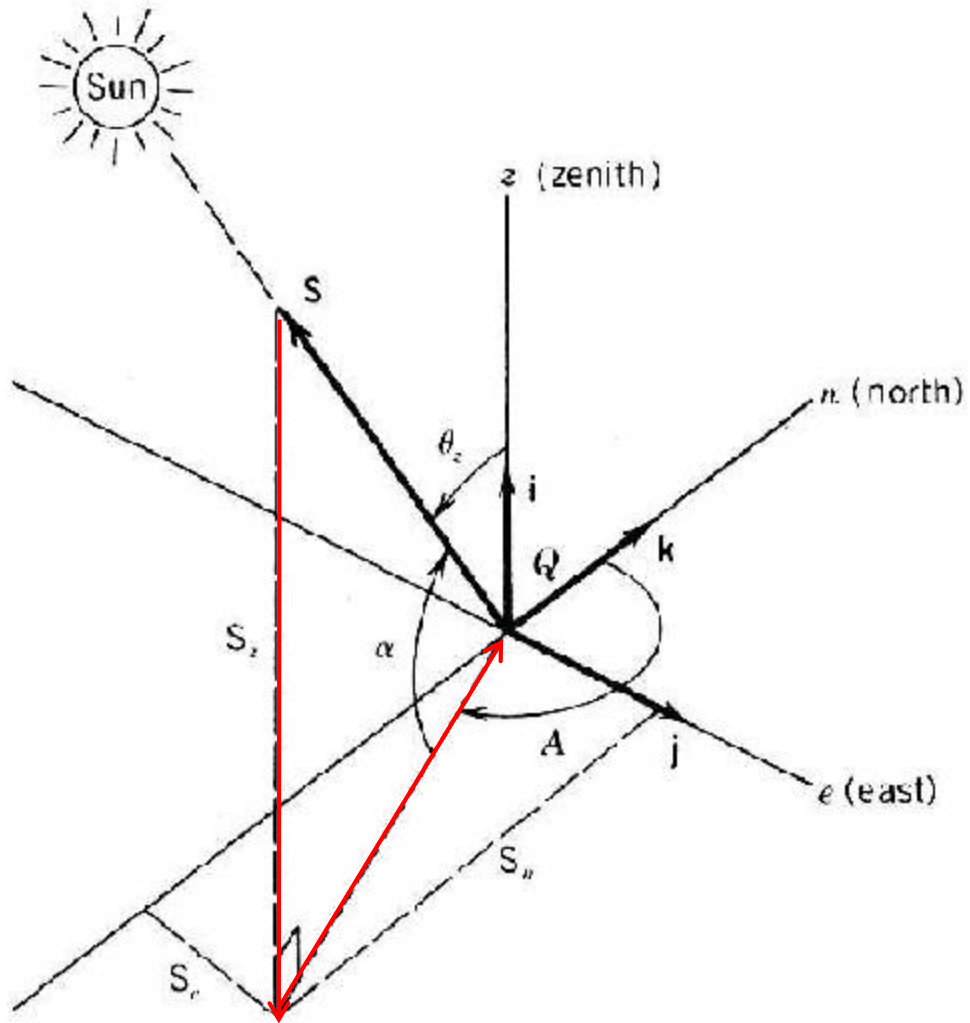
<http://www.powerfromthesun.net/chapter3/Image61.jpg>

GEO 827 – Digital Image Processing and Analysis

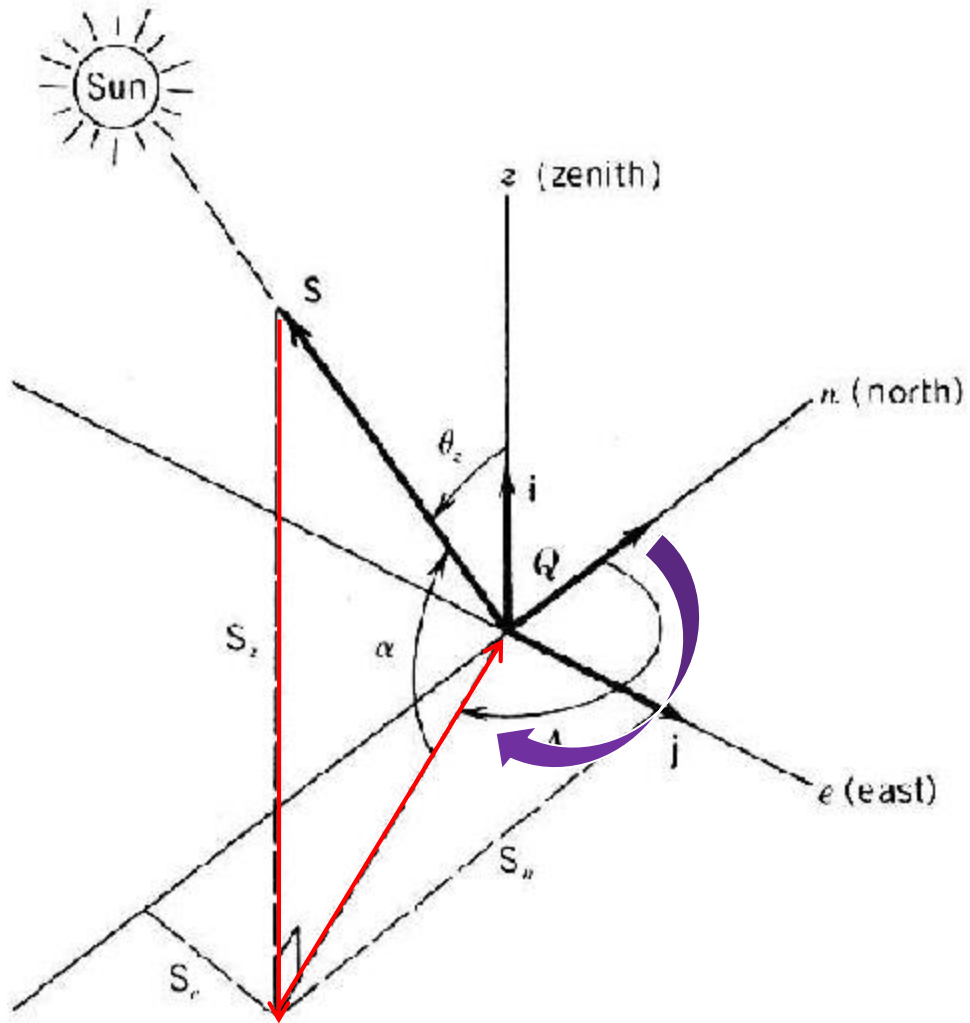




<http://www.powerfromthesun.net/chapter3/Image61.jpg>



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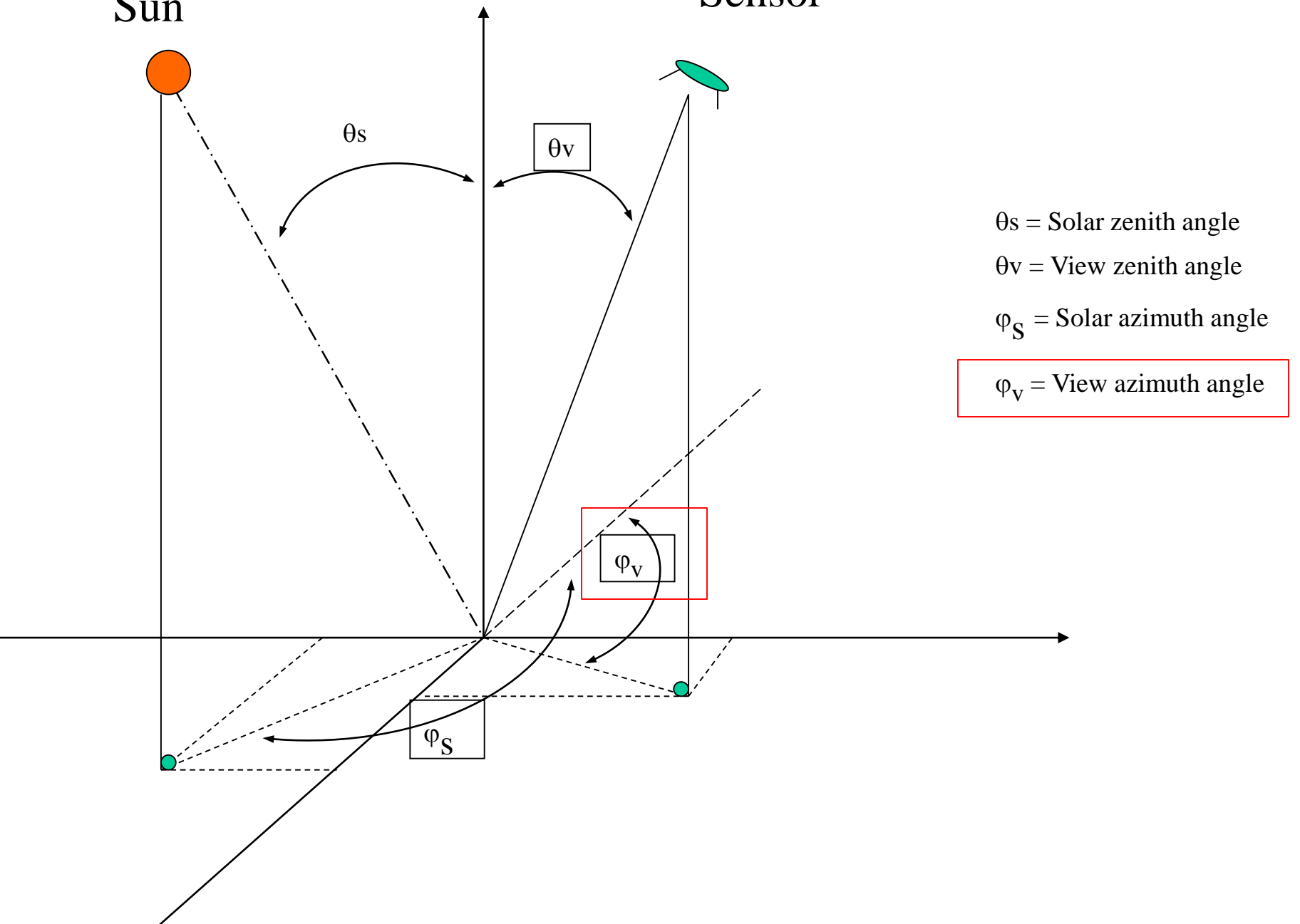


<http://www.powerfromthesun.net/chapter3/Image61.jpg>

GEO 827 – Digital Image Processing and Analysis

Sun

Sensor



$\theta_s$  = Solar zenith angle

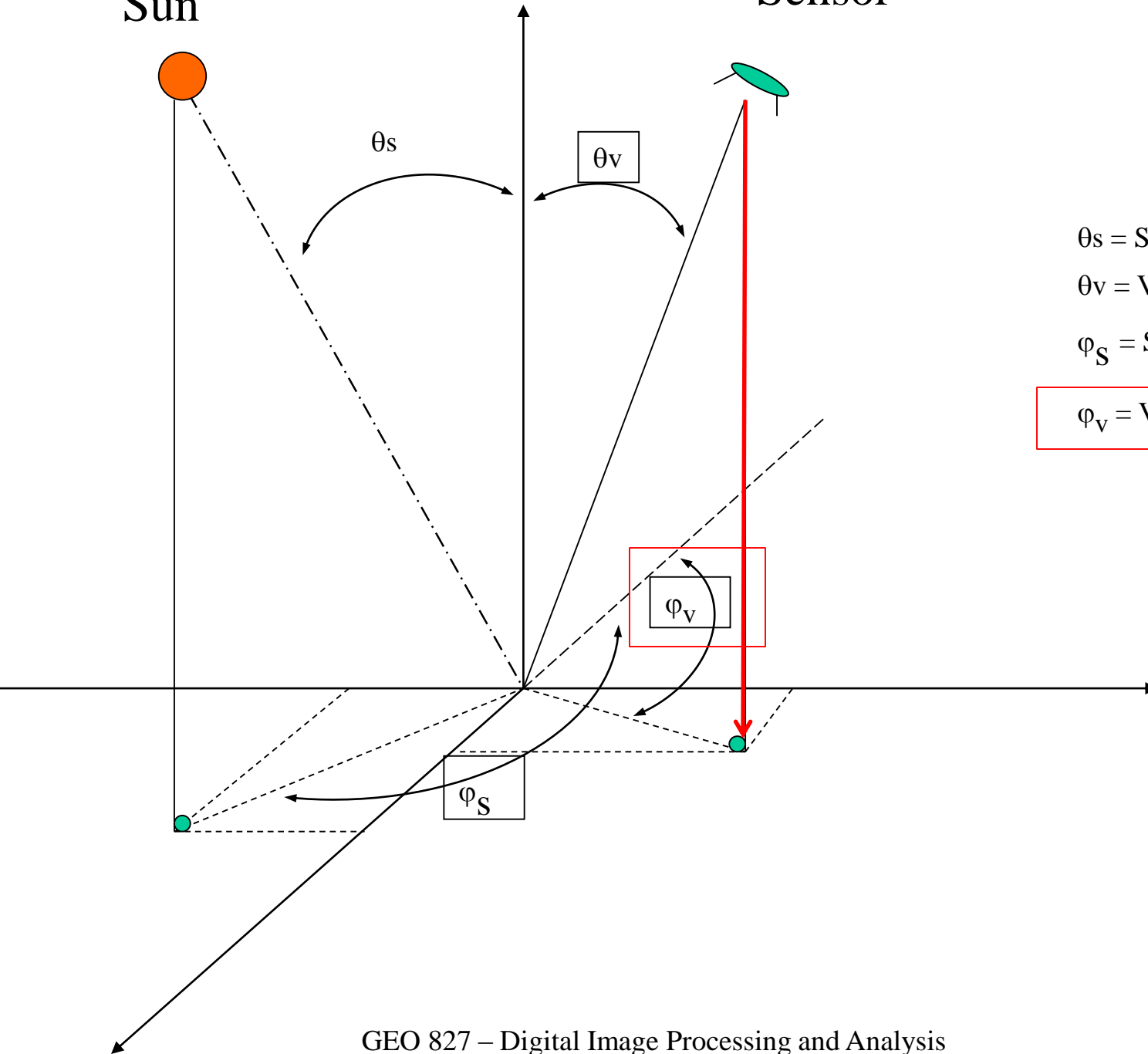
$\theta_v$  = View zenith angle

$\phi_s$  = Solar azimuth angle

$\phi_v$  = View azimuth angle

Sun

Sensor



$\theta_s$  = Solar zenith angle

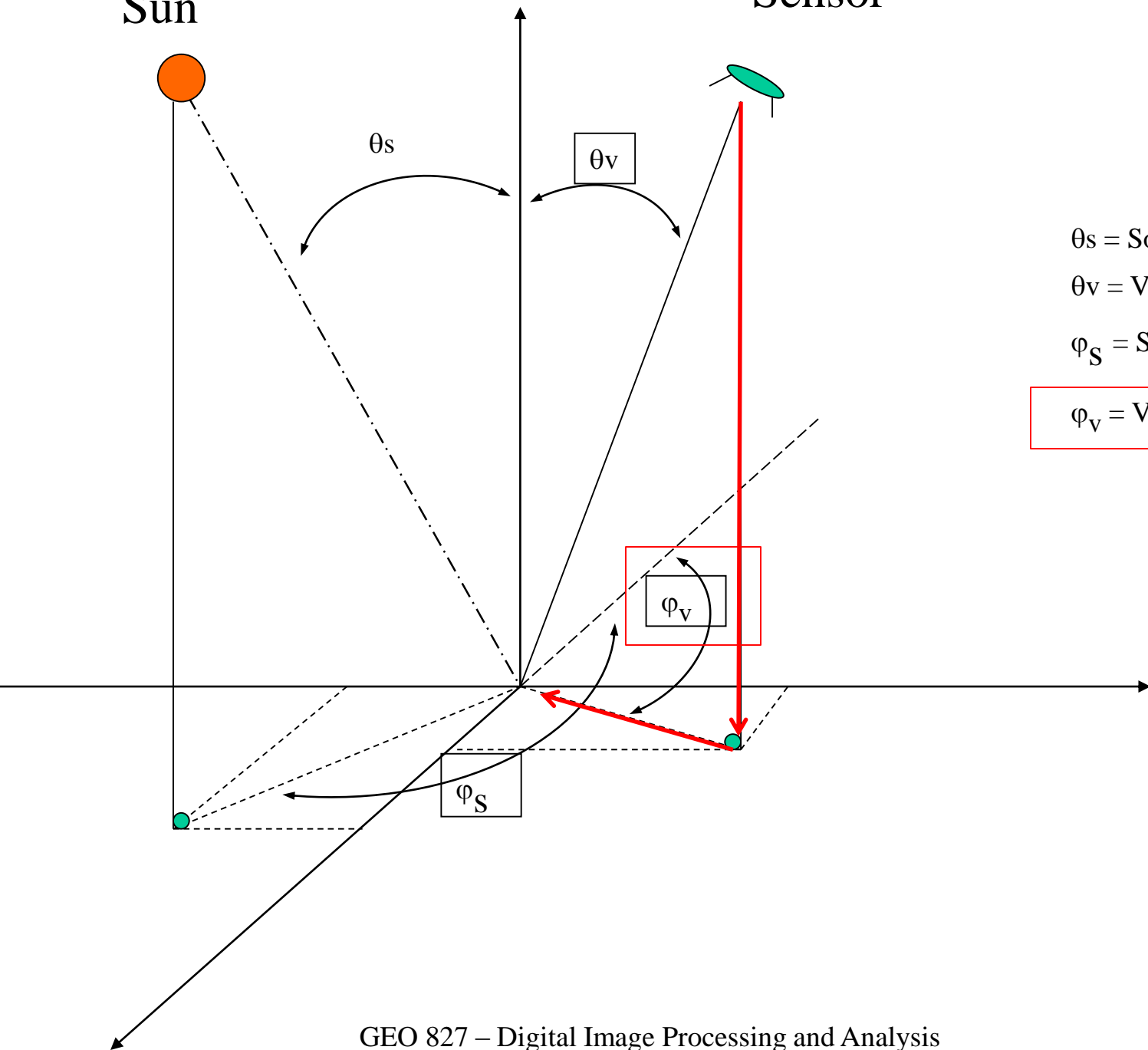
$\theta_v$  = View zenith angle

$\varphi_s$  = Solar azimuth angle

$\varphi_v$  = View azimuth angle

Sun

Sensor



$\theta_s$  = Solar zenith angle

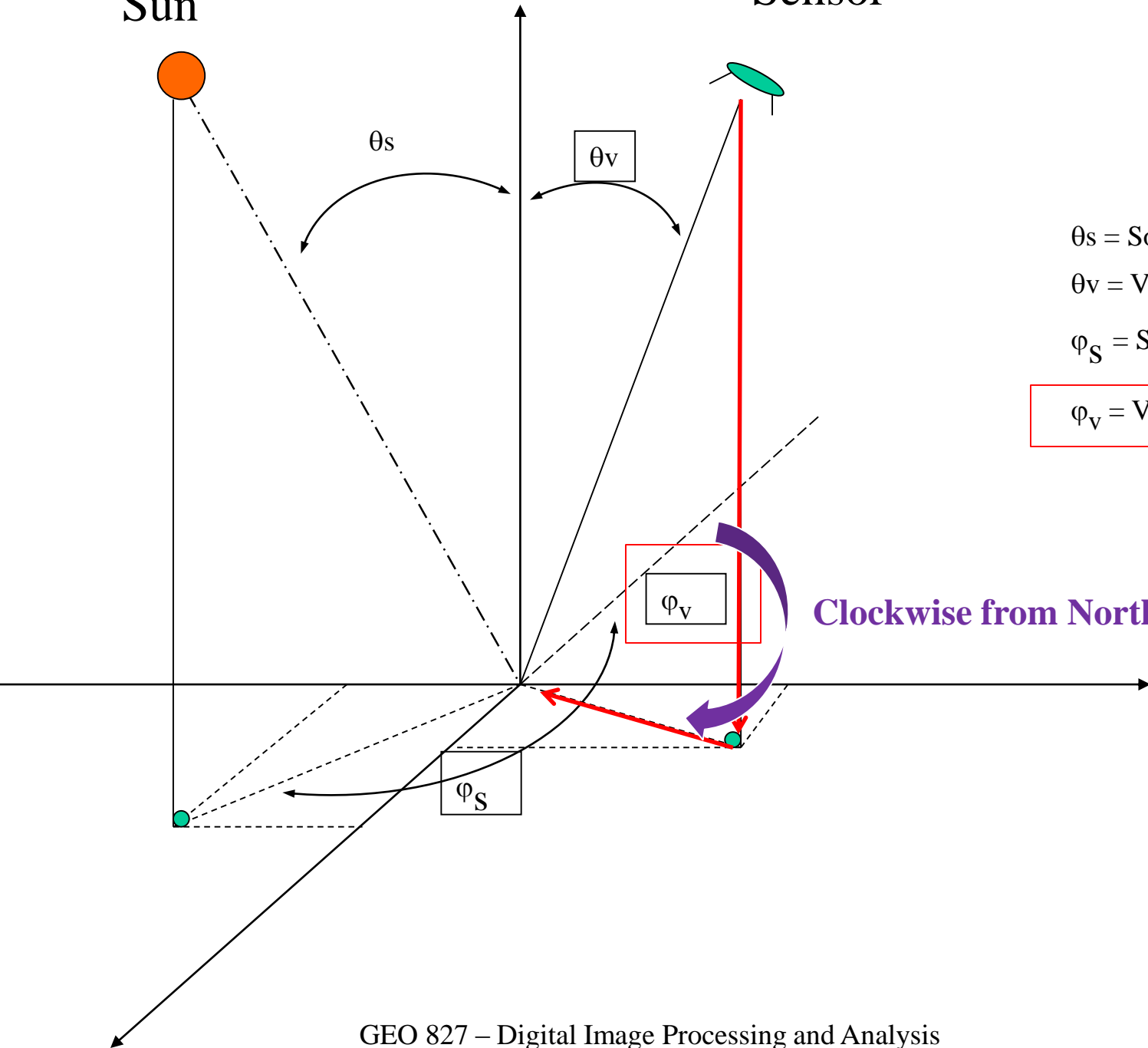
$\theta_v$  = View zenith angle

$\varphi_s$  = Solar azimuth angle

$\varphi_v$  = View azimuth angle

Sun

Sensor



$\theta_s$  = Solar zenith angle

$\theta_v$  = View zenith angle

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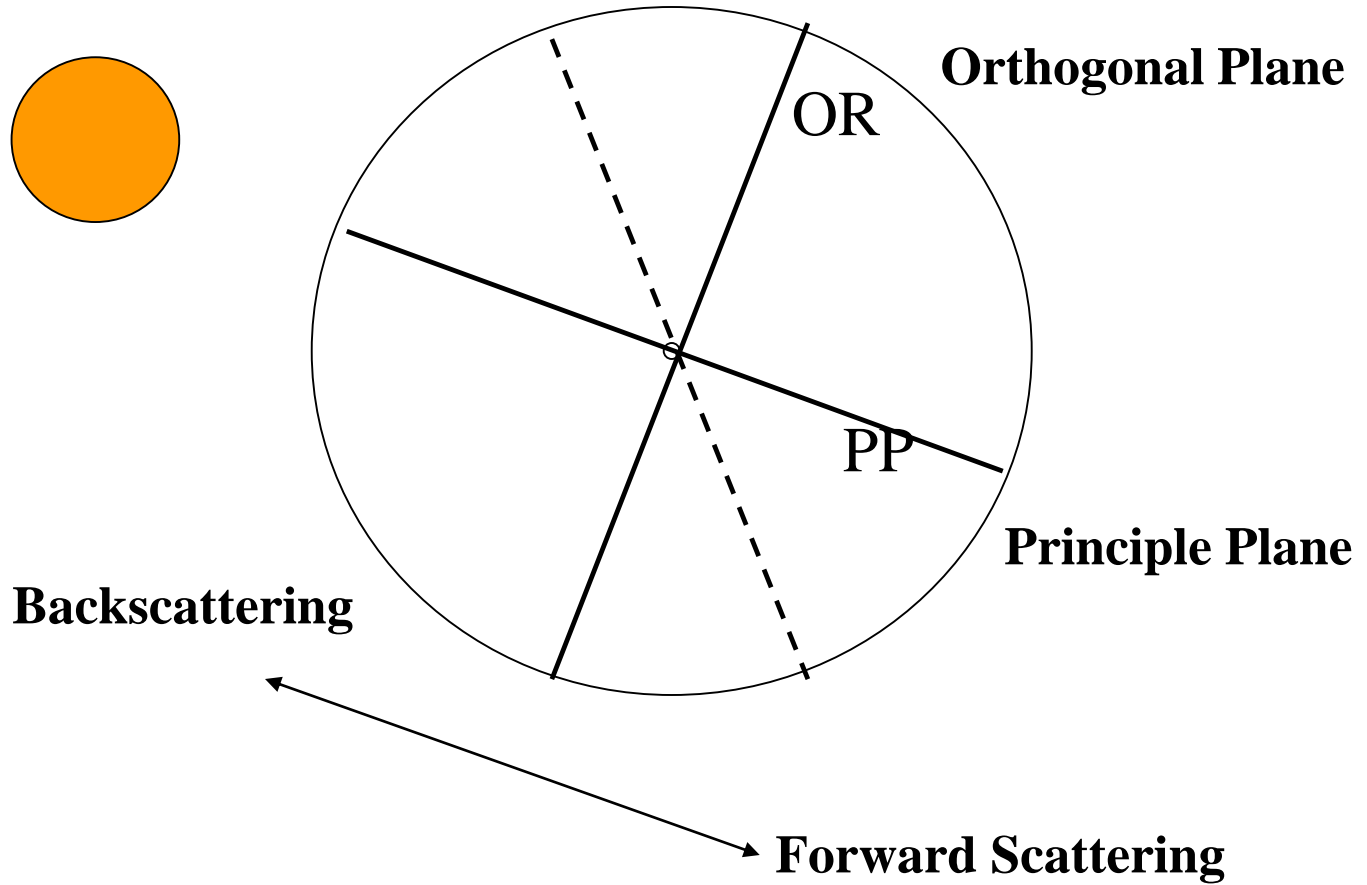
$\phi_v$  = View azimuth angle

Clockwise from North

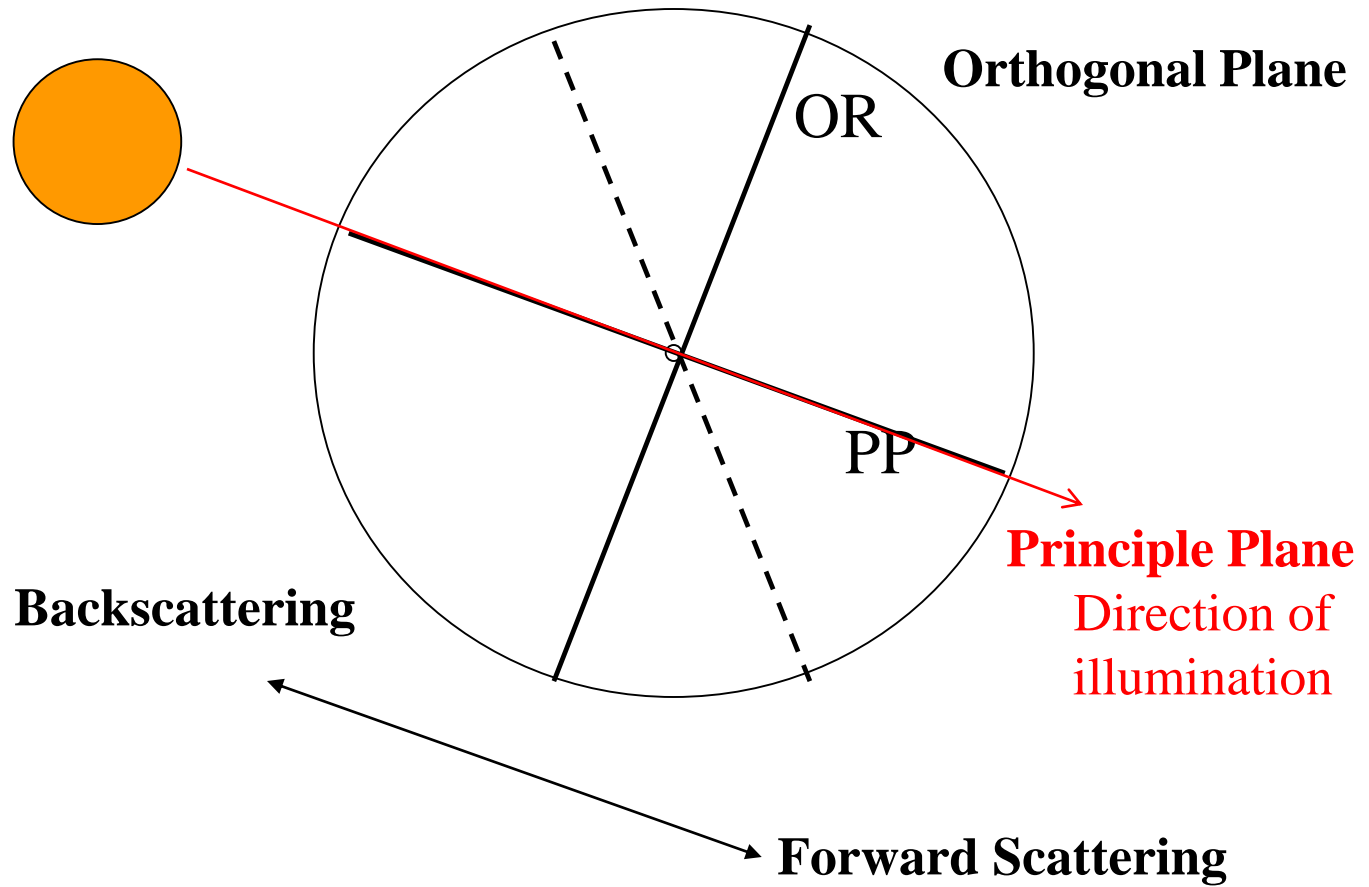
Relative Azimuth ( $\varphi$ ) = Solar Azimuth-View Azimuth



# Top View

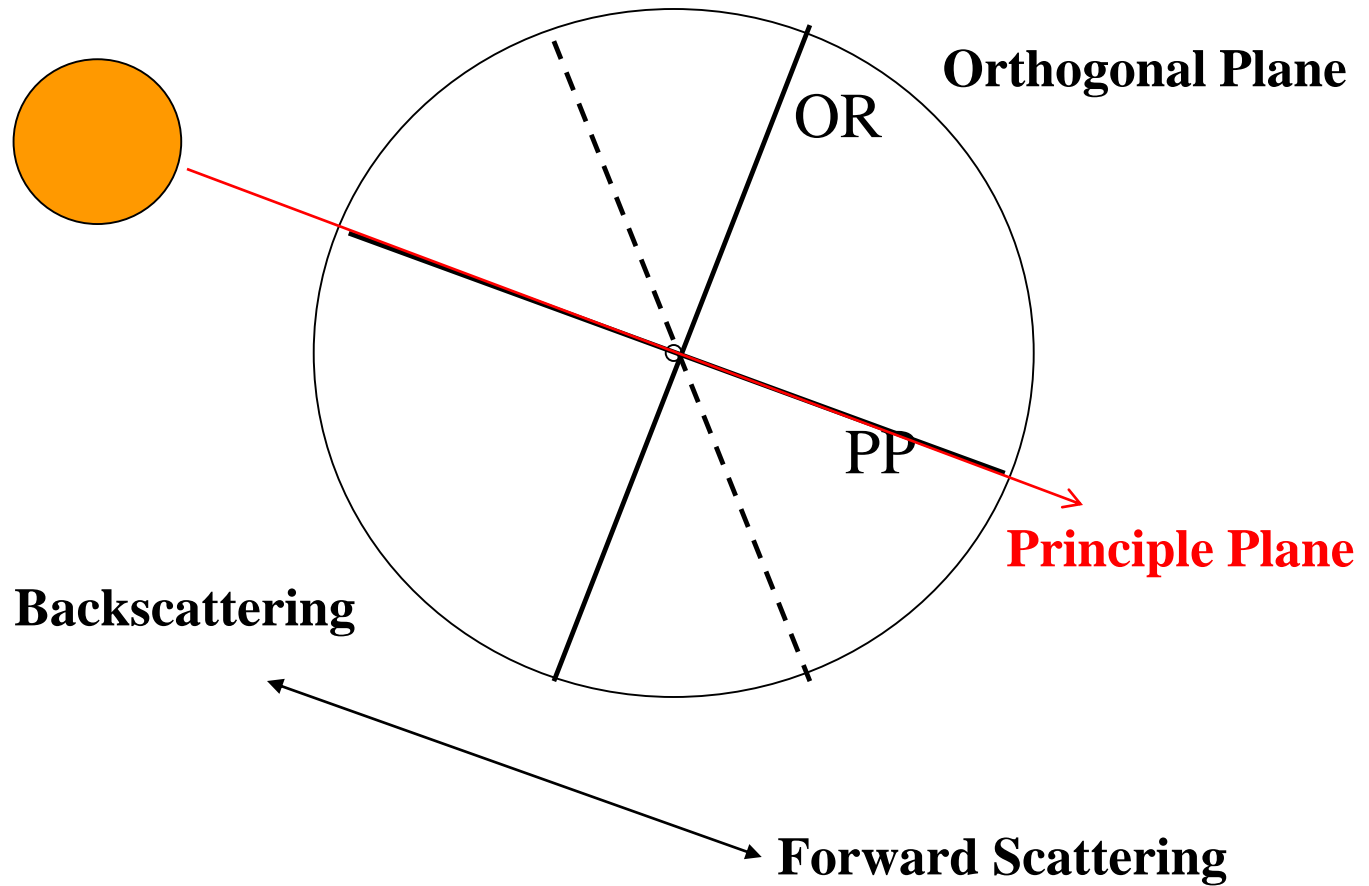


# Top View

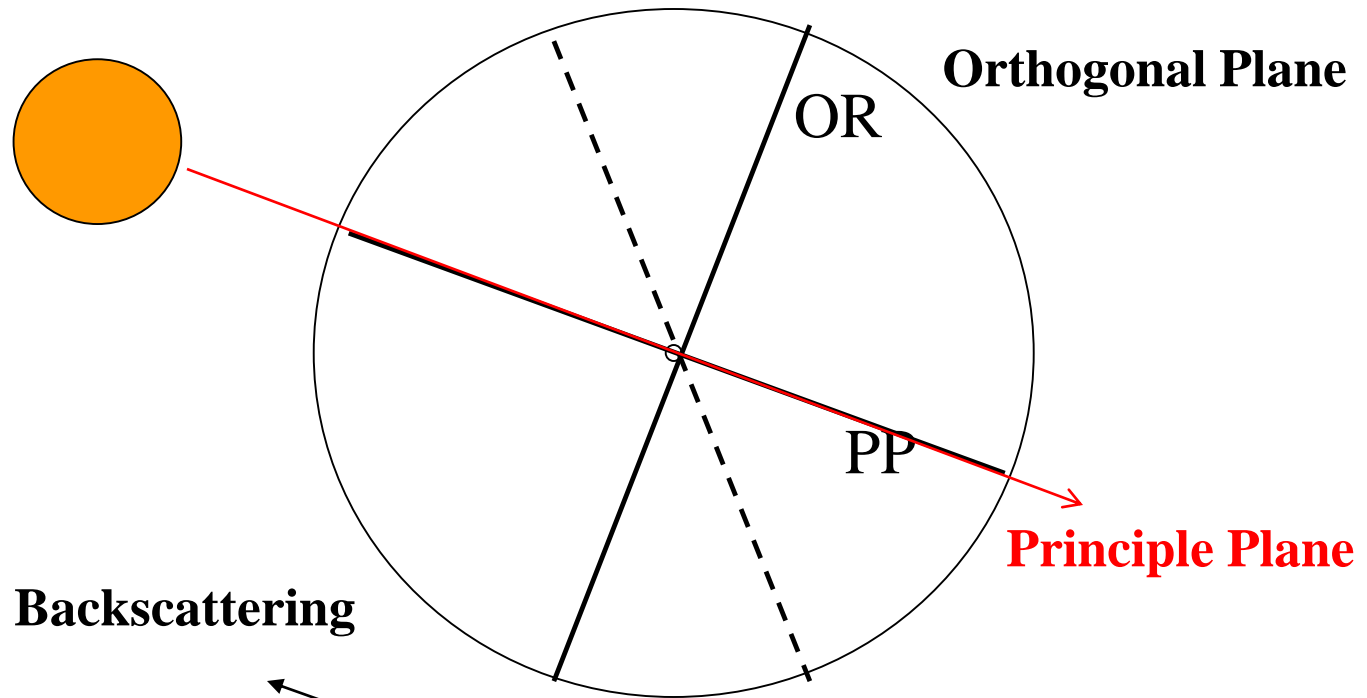


# Top View

If relative azimuth is  $180^\circ$  then sensor is in principle plane

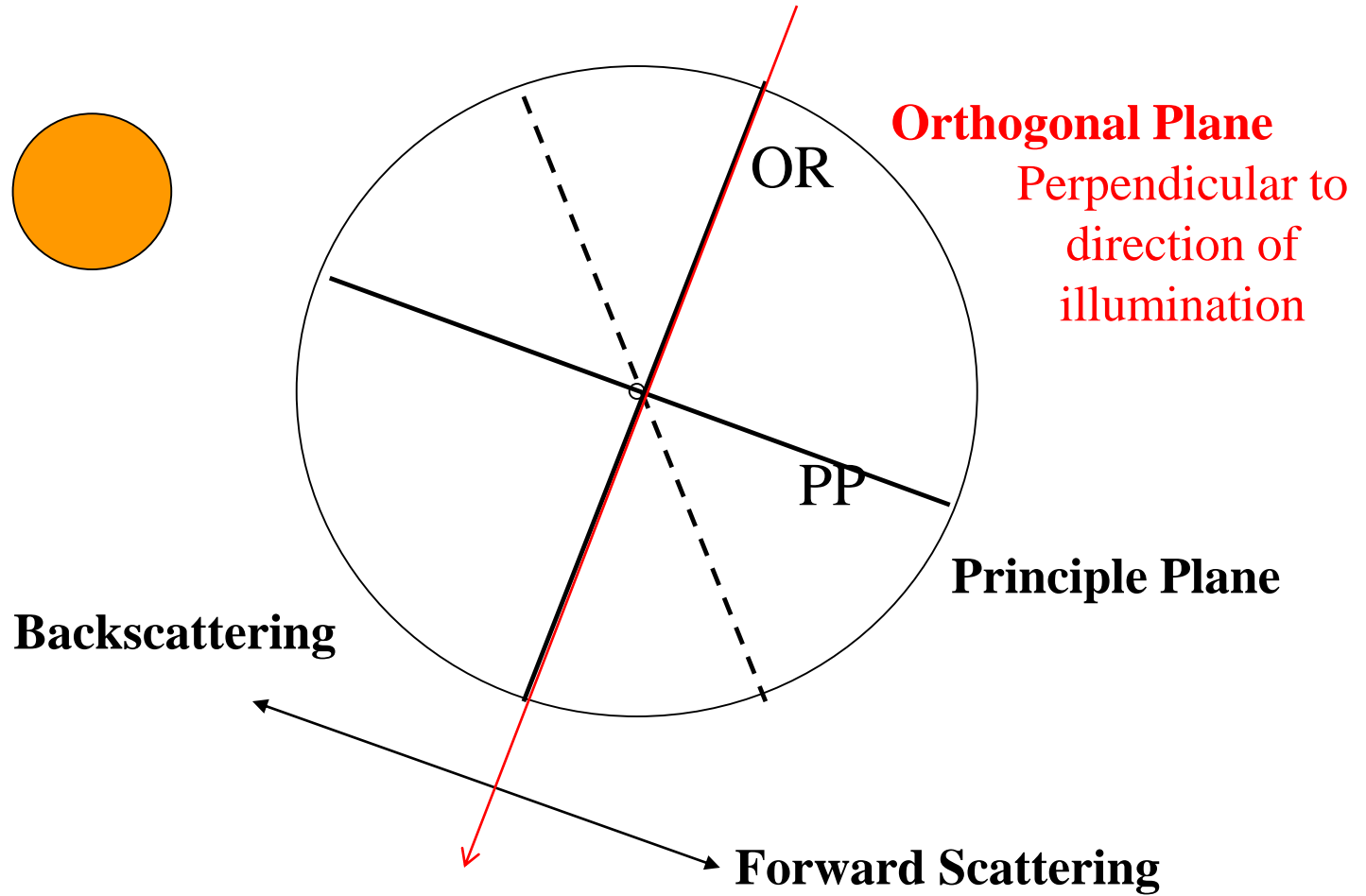


# Top View

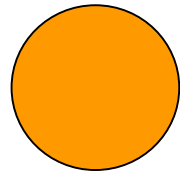


If relative azimuth is  $0^\circ$  then sensor and sun are on same side (direction) and in principle plane

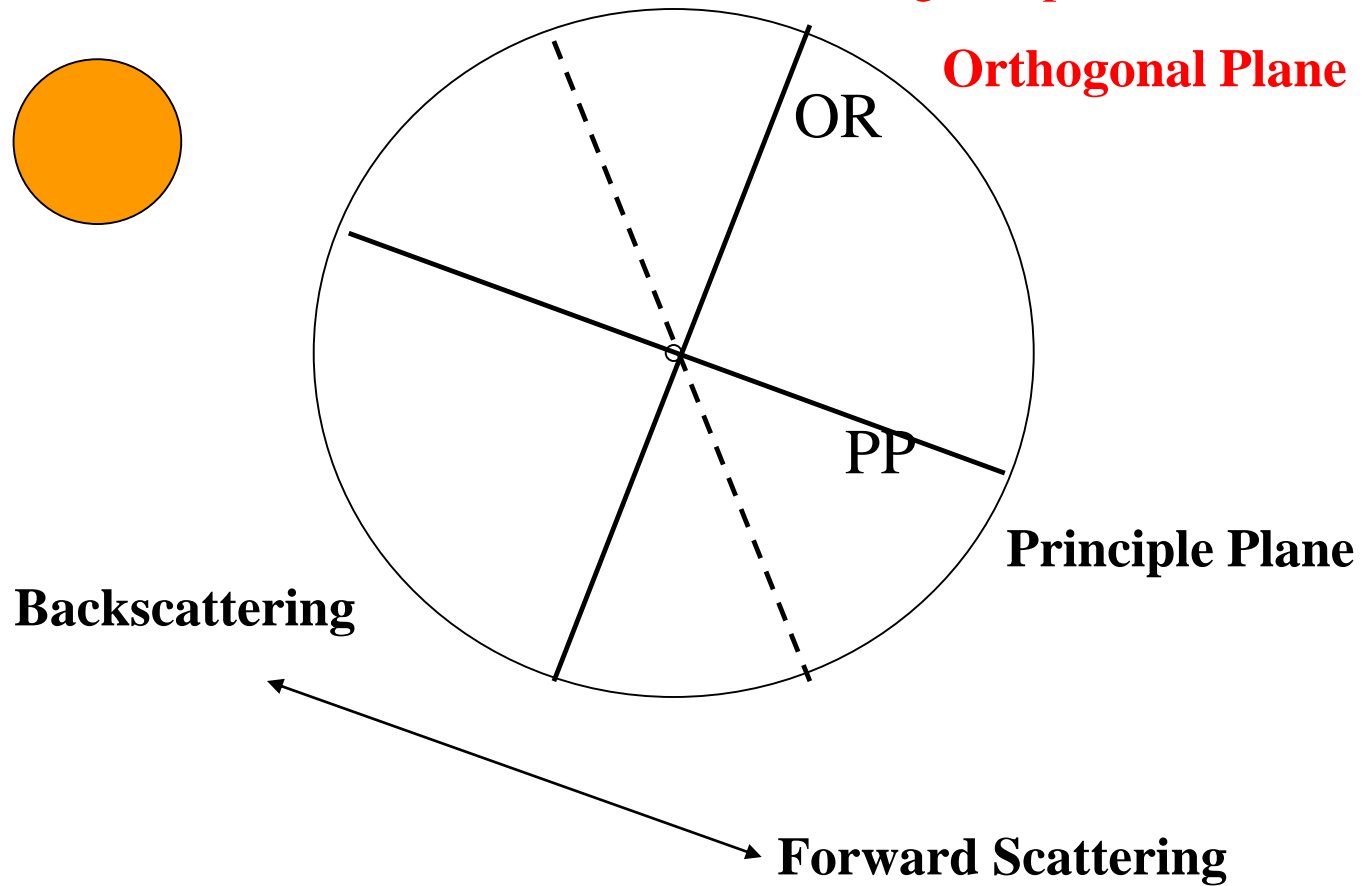
# Top View



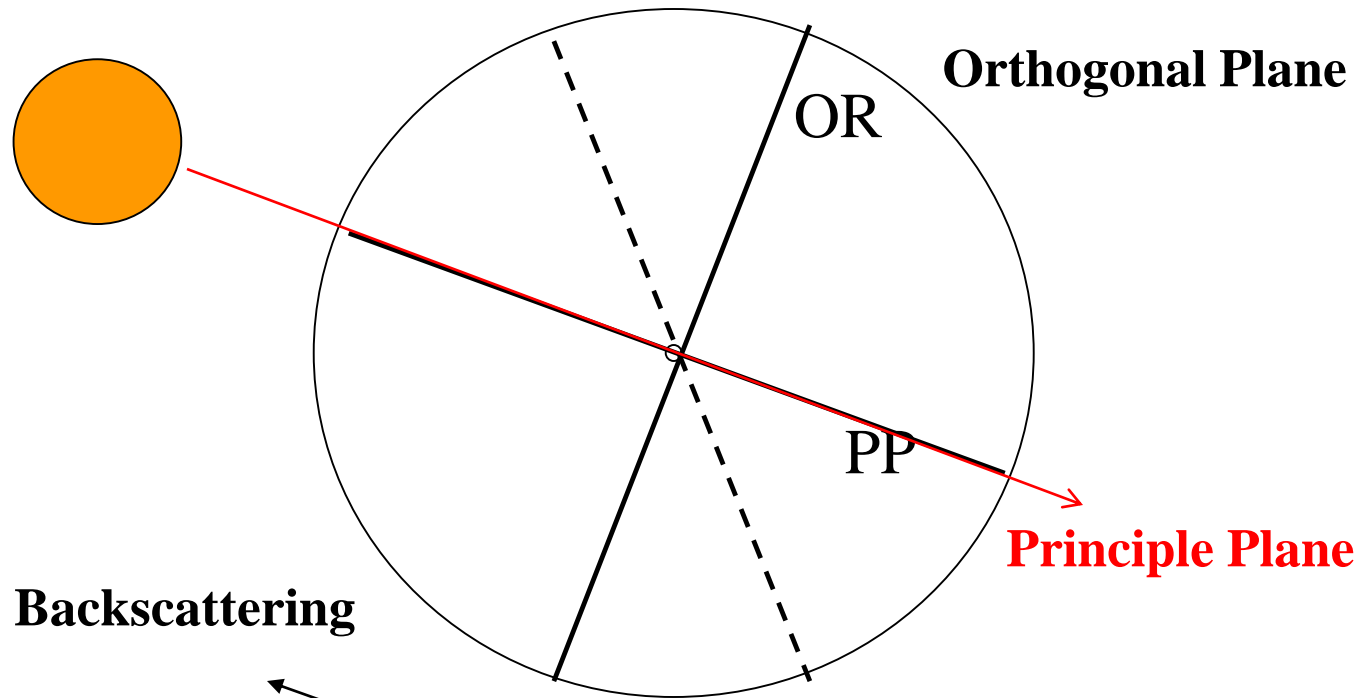
# Top View



If relative azimuth is  $90^\circ$  then sun and sensor are at adj. directions and in orthogonal plane



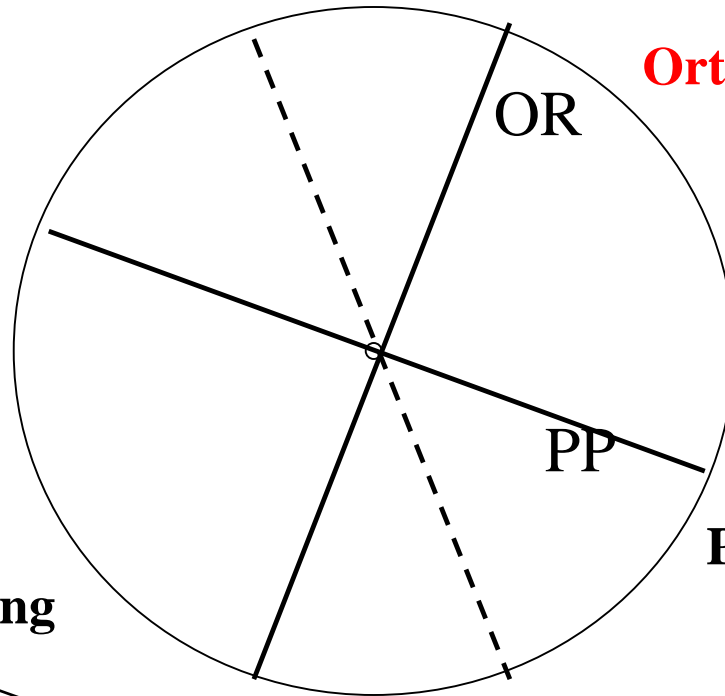
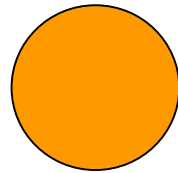
# Top View



You will see a lot of shadow variation in PP as you move from one direction to another

# Top View

You will see little shadow variation as you move from one direction to another in OR



**Orthogonal Plane**

**Principle Plane**

**Backscattering**

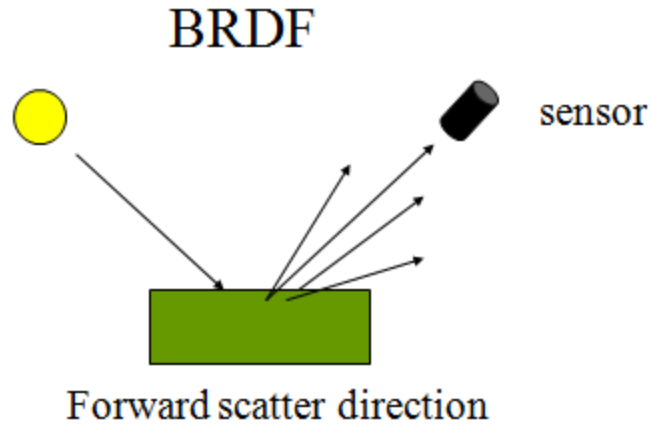
**Forward Scattering**



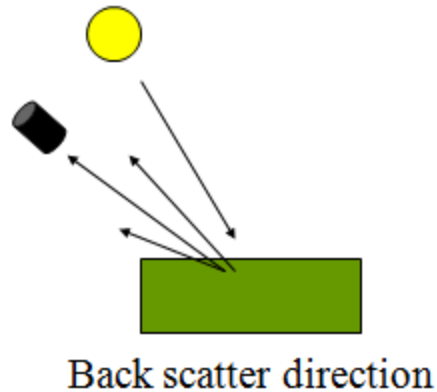
# More terminology

- **Phase angle**: angle between sensor and illumination source
- **Hotspot**: when phase angle equals 0
  - Sensor between sun and target
  - Zenith angles are equal
  - Rel. Azimuth is 0
  - No shadows, highest reflectance

Solar radiation scattered away from the sun

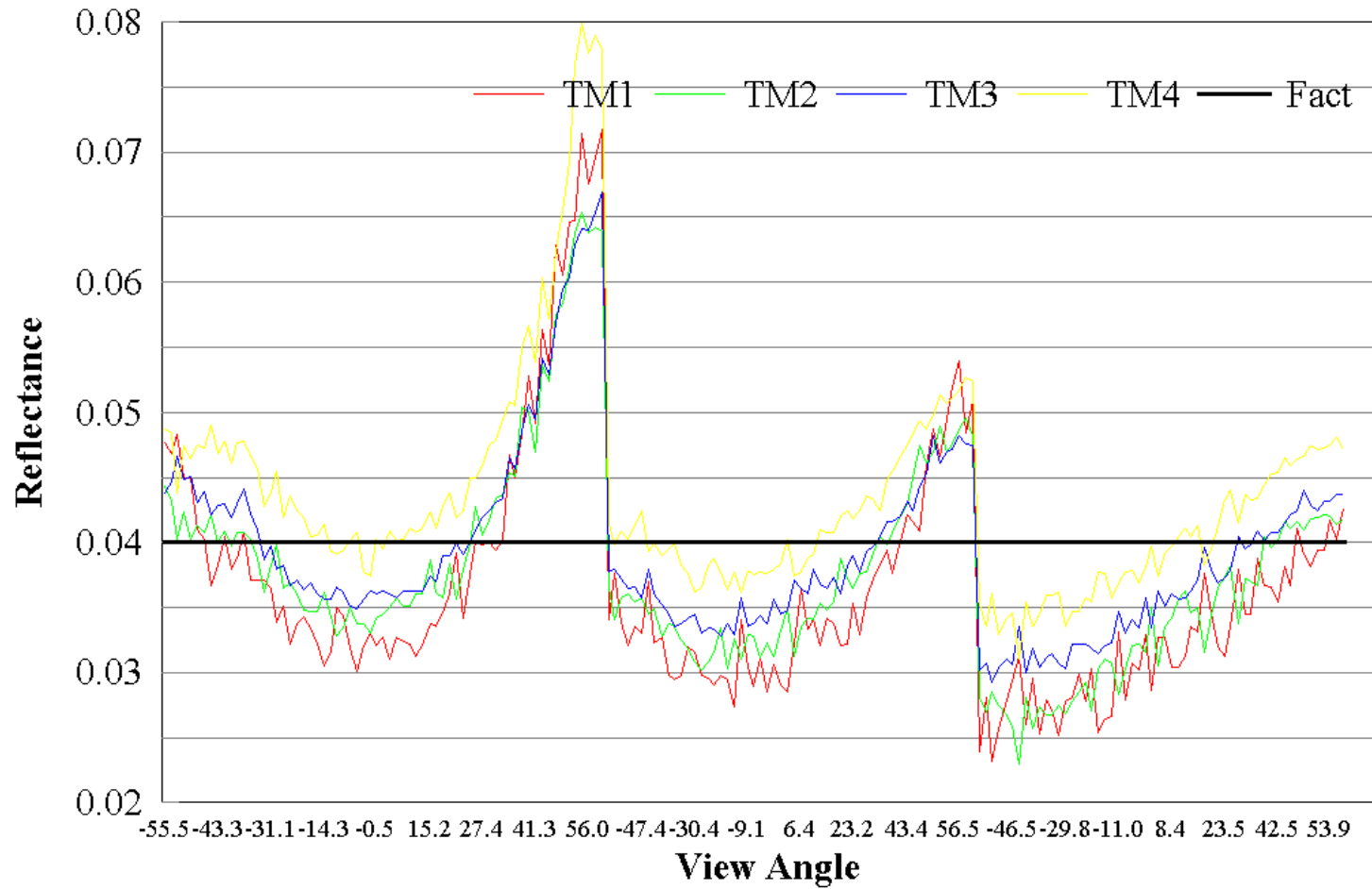


Solar radiation scattered back towards the sun



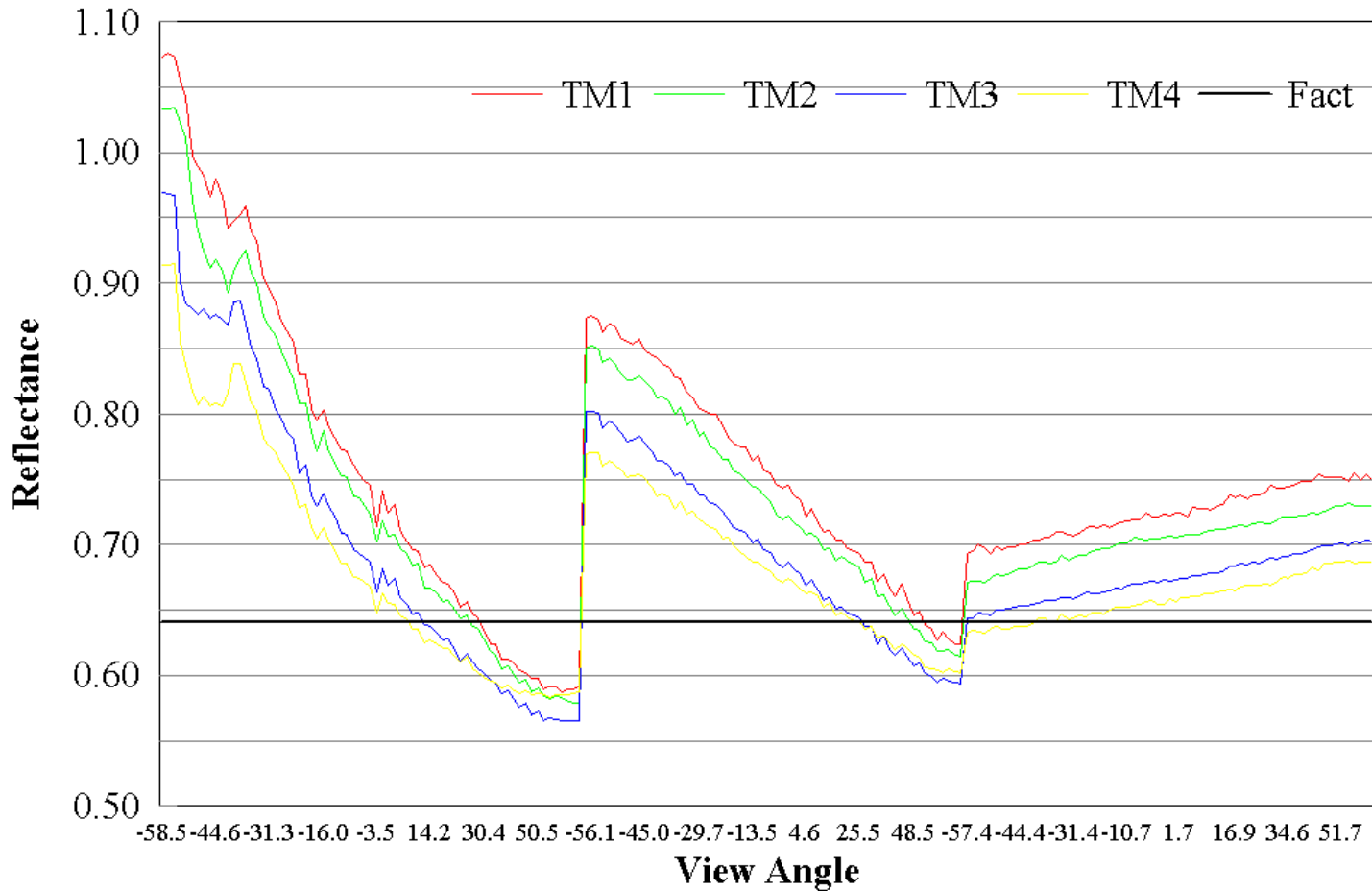
# Artificial tarps at 4% reflectance

## Run 1 8-4%

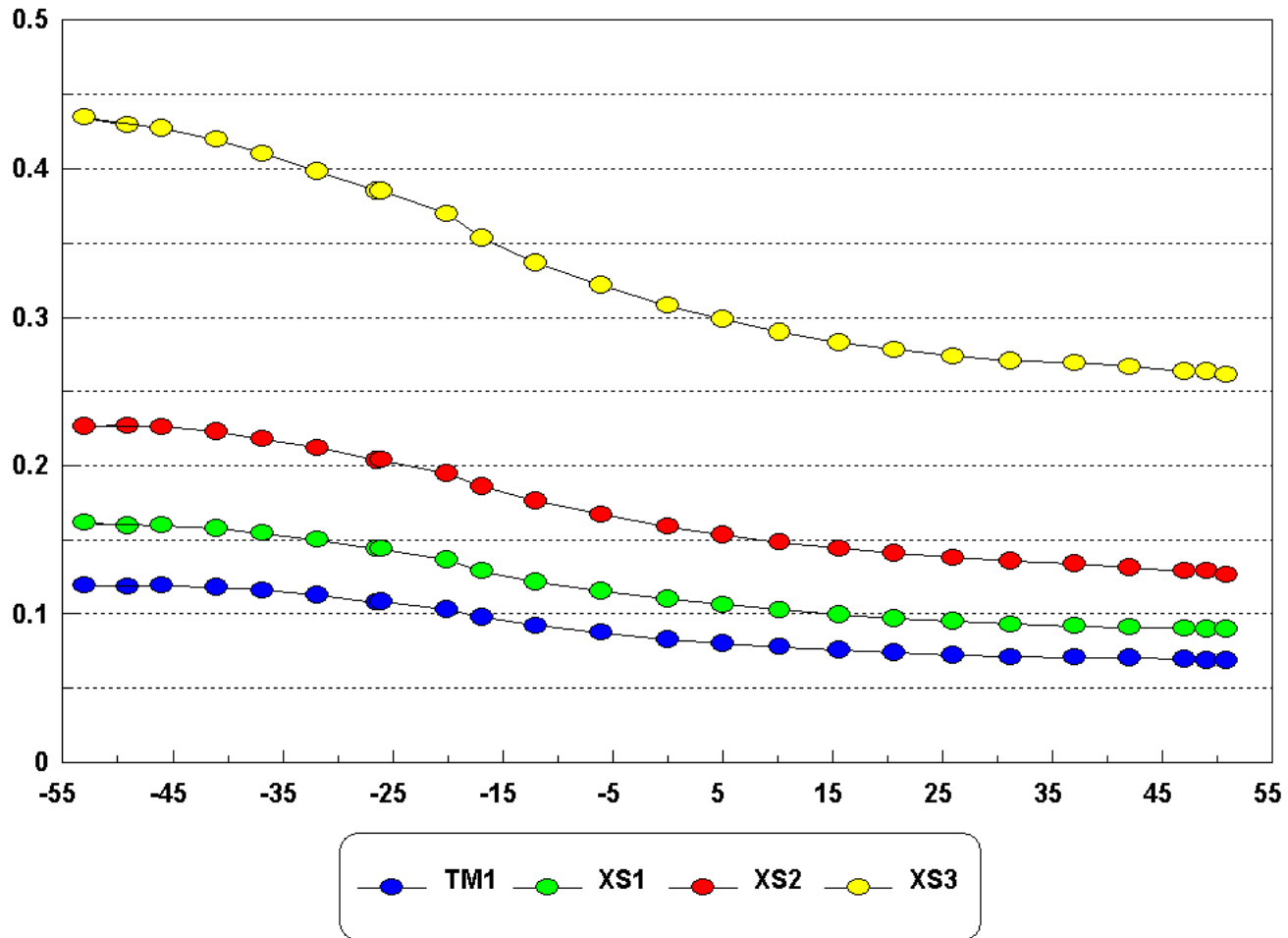


# Artificial tarps at 64% reflectance

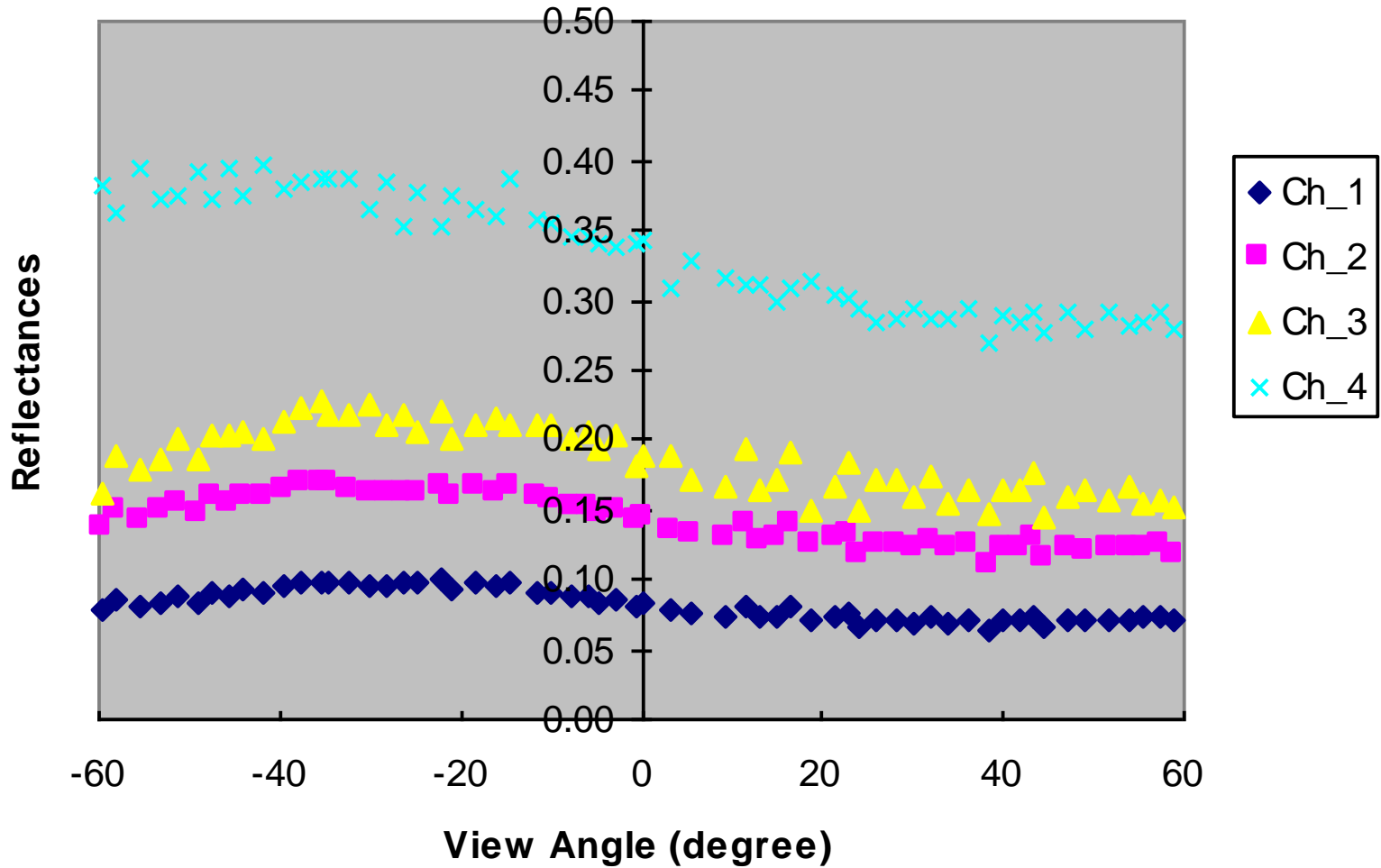
## Run 1 5-64%



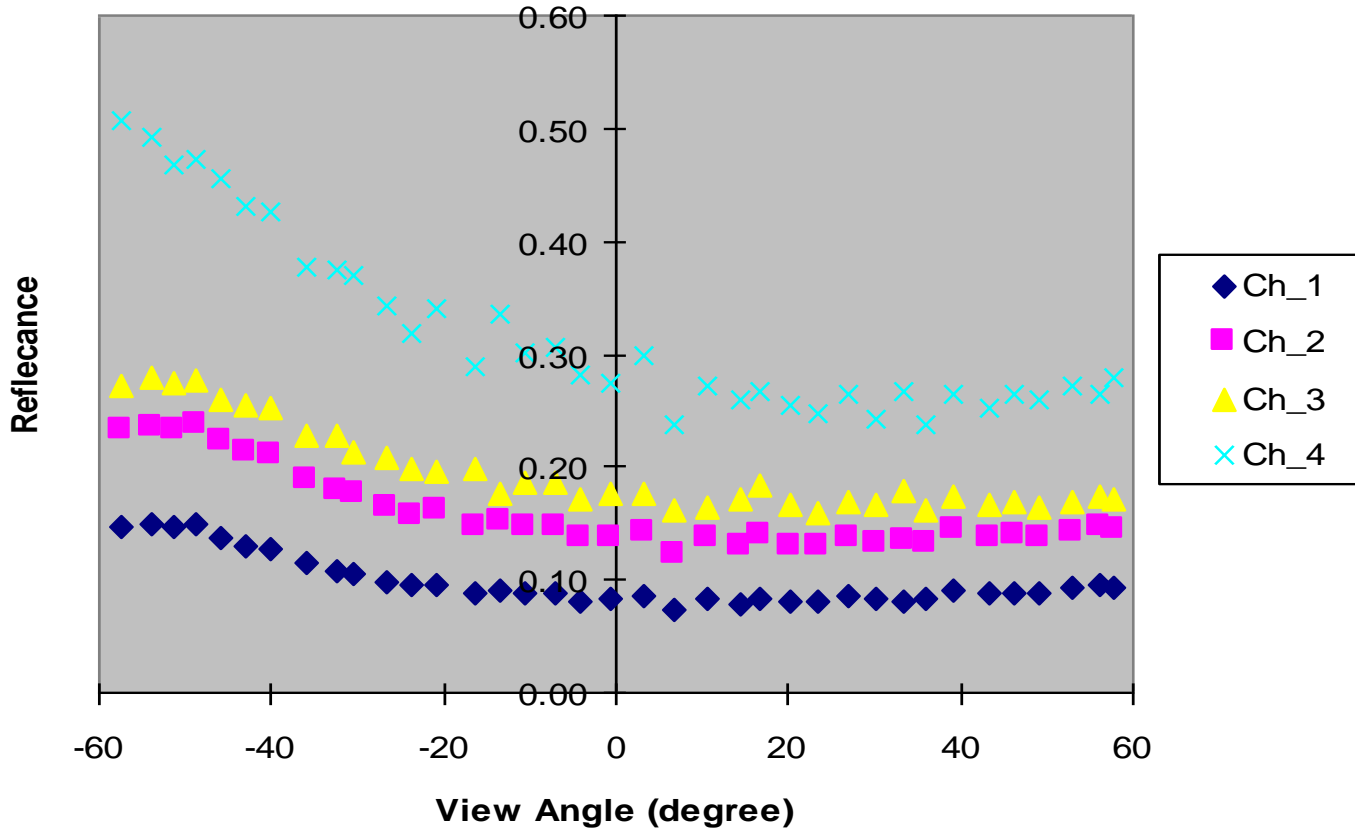
# Young alfalfa canopy



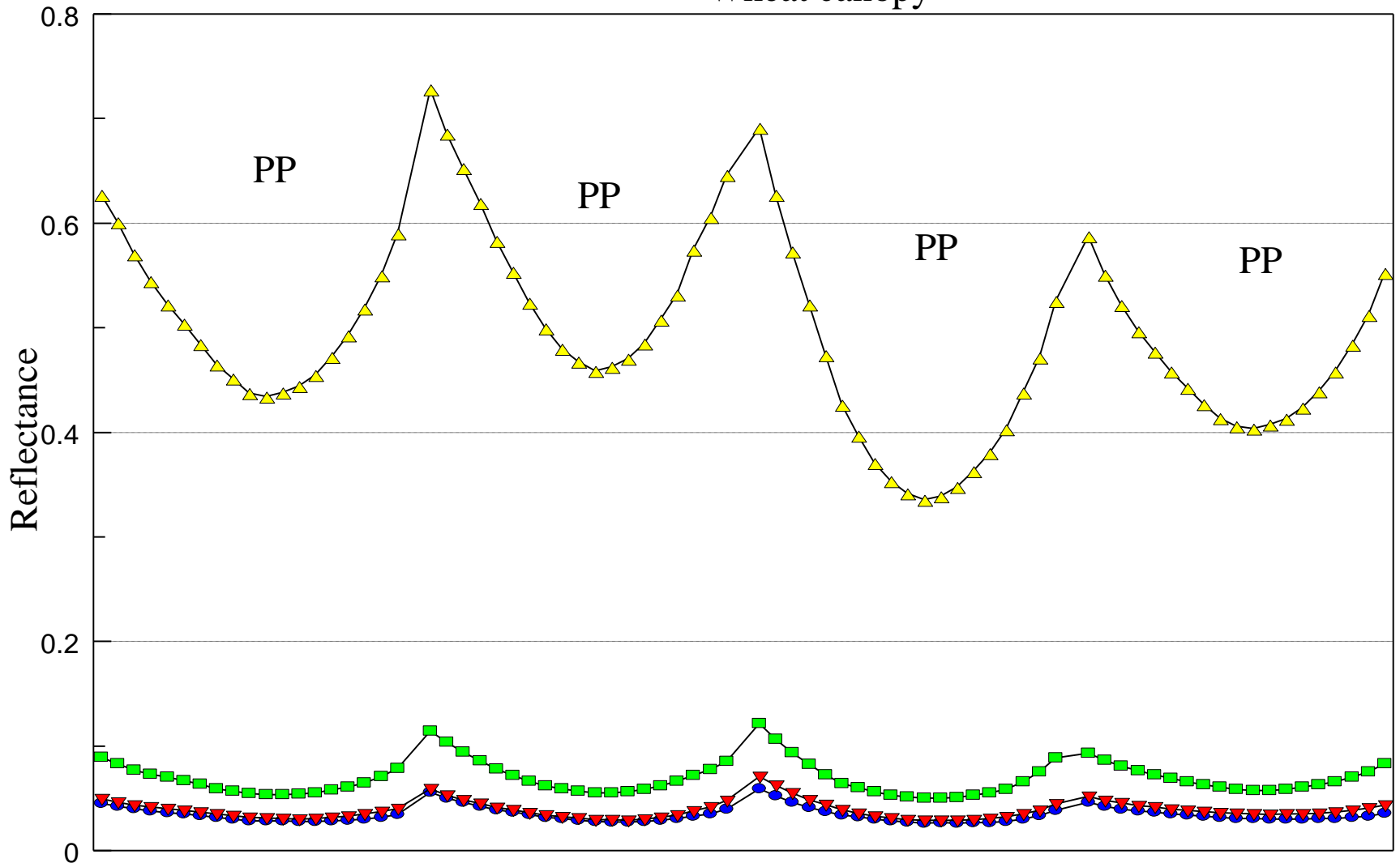
**Plot 153 (Cotton: High H2O and N5) PP**  
**Solar Zenith: 27 degree**



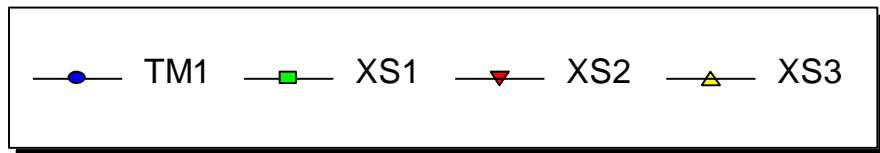
**Plot 322 (Cotton: Low H2O, N4), PP**  
**Solar Zenith: 57**



4th run  
Wheat canopy



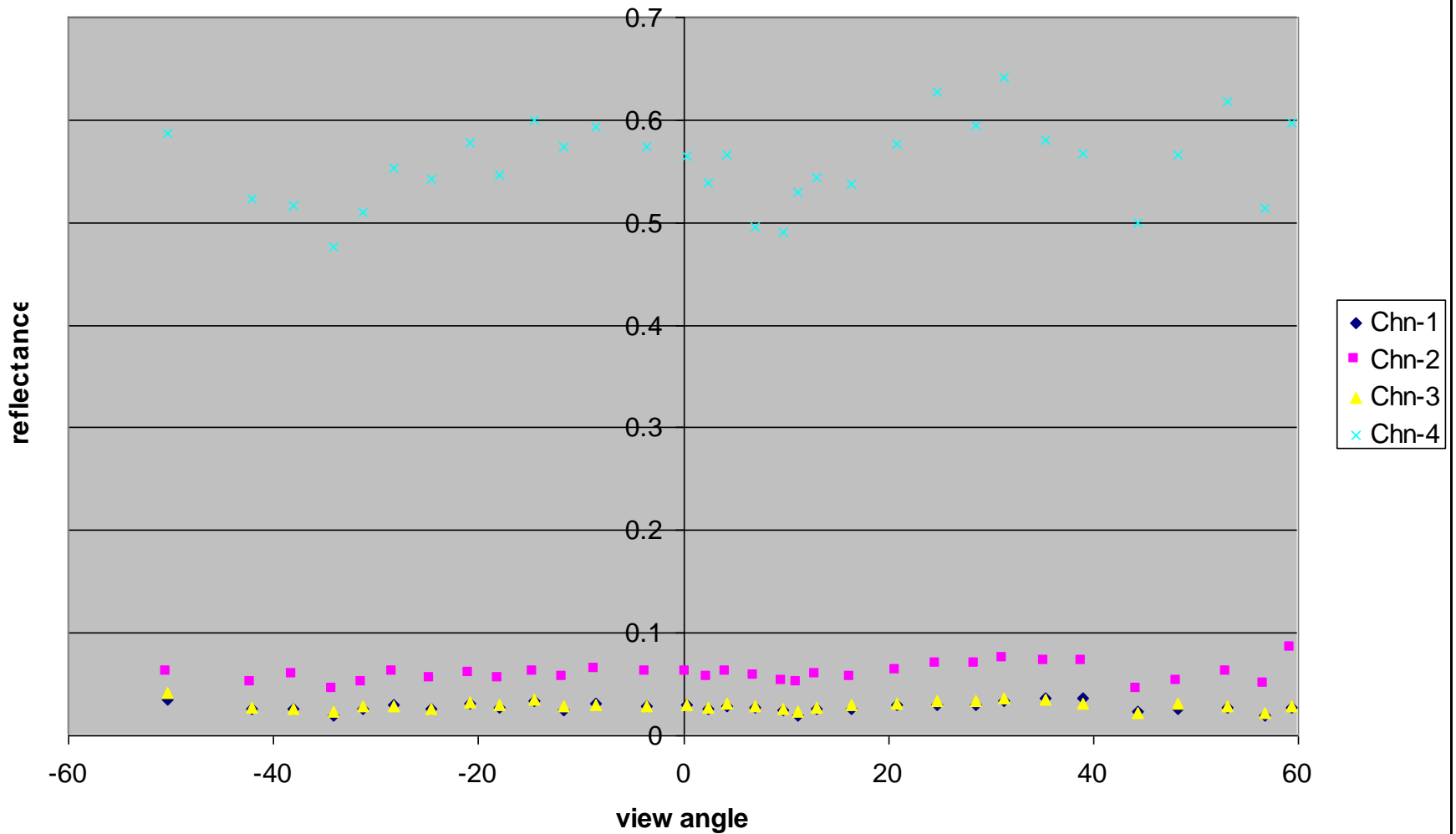
View angles varied from -40 to +40 for each curve

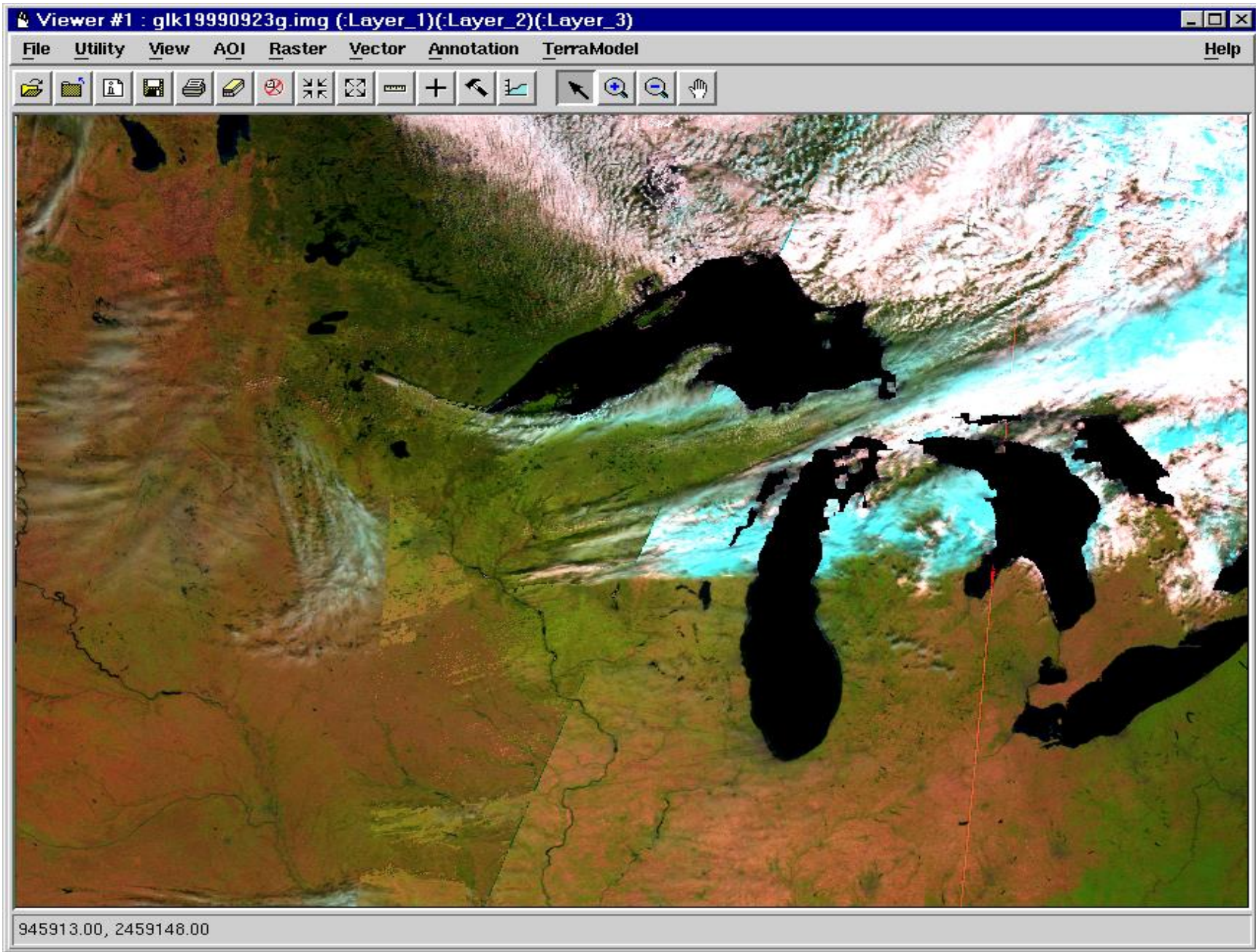


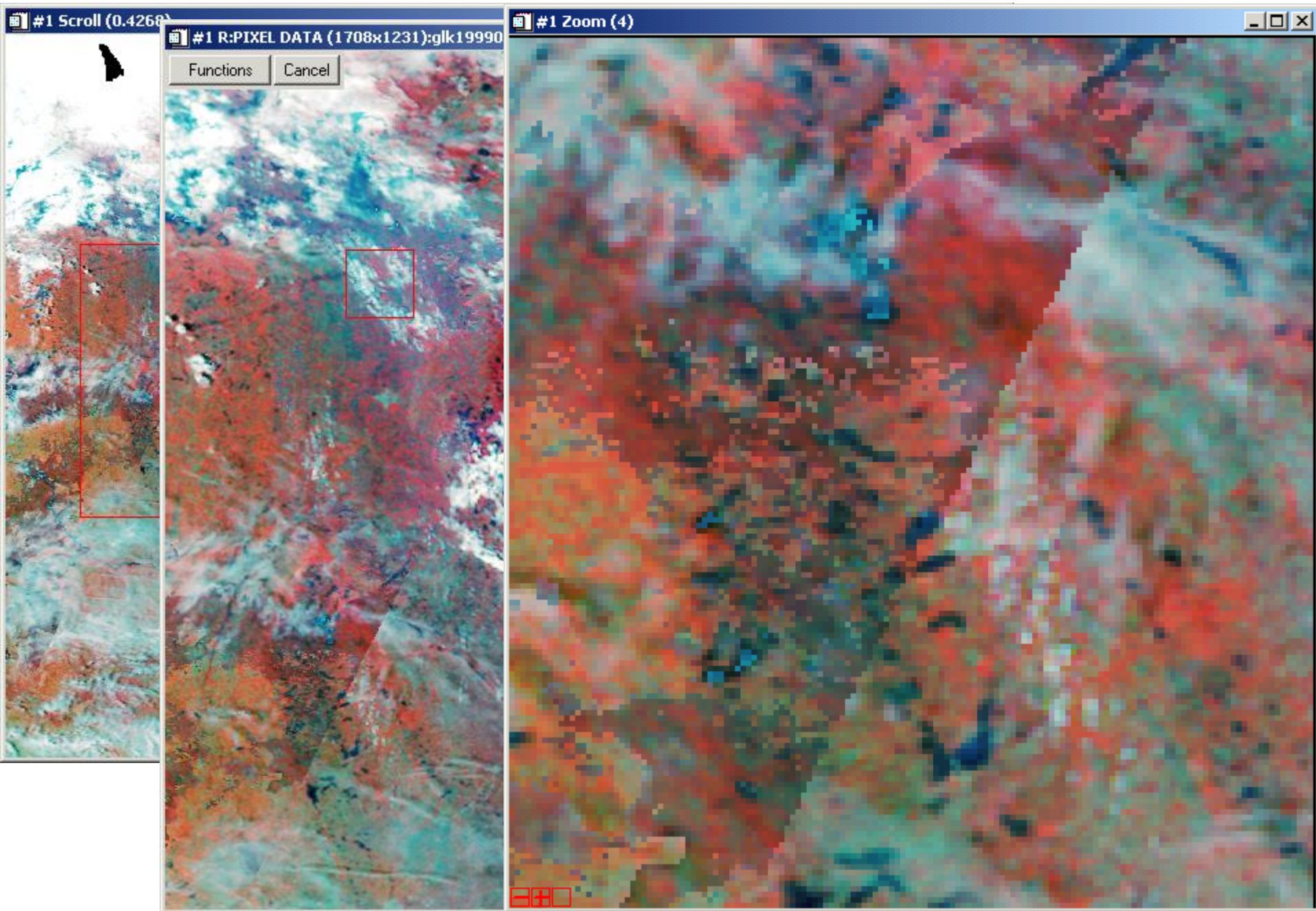


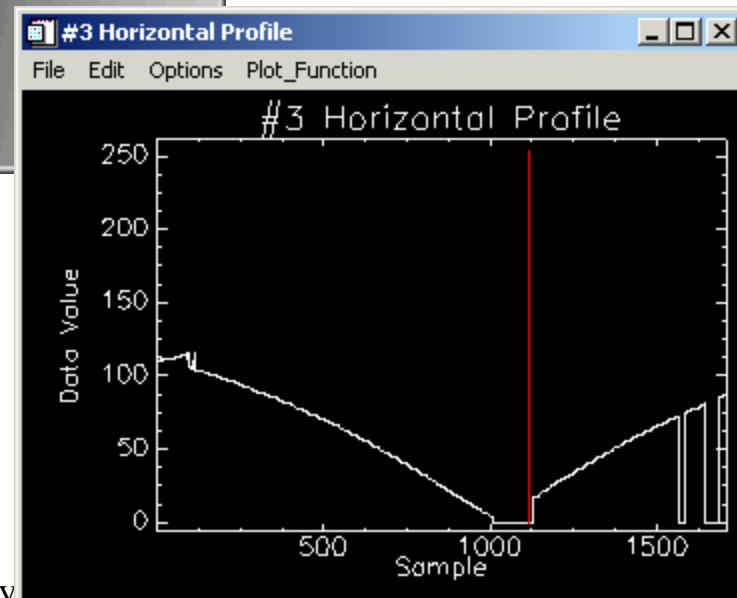
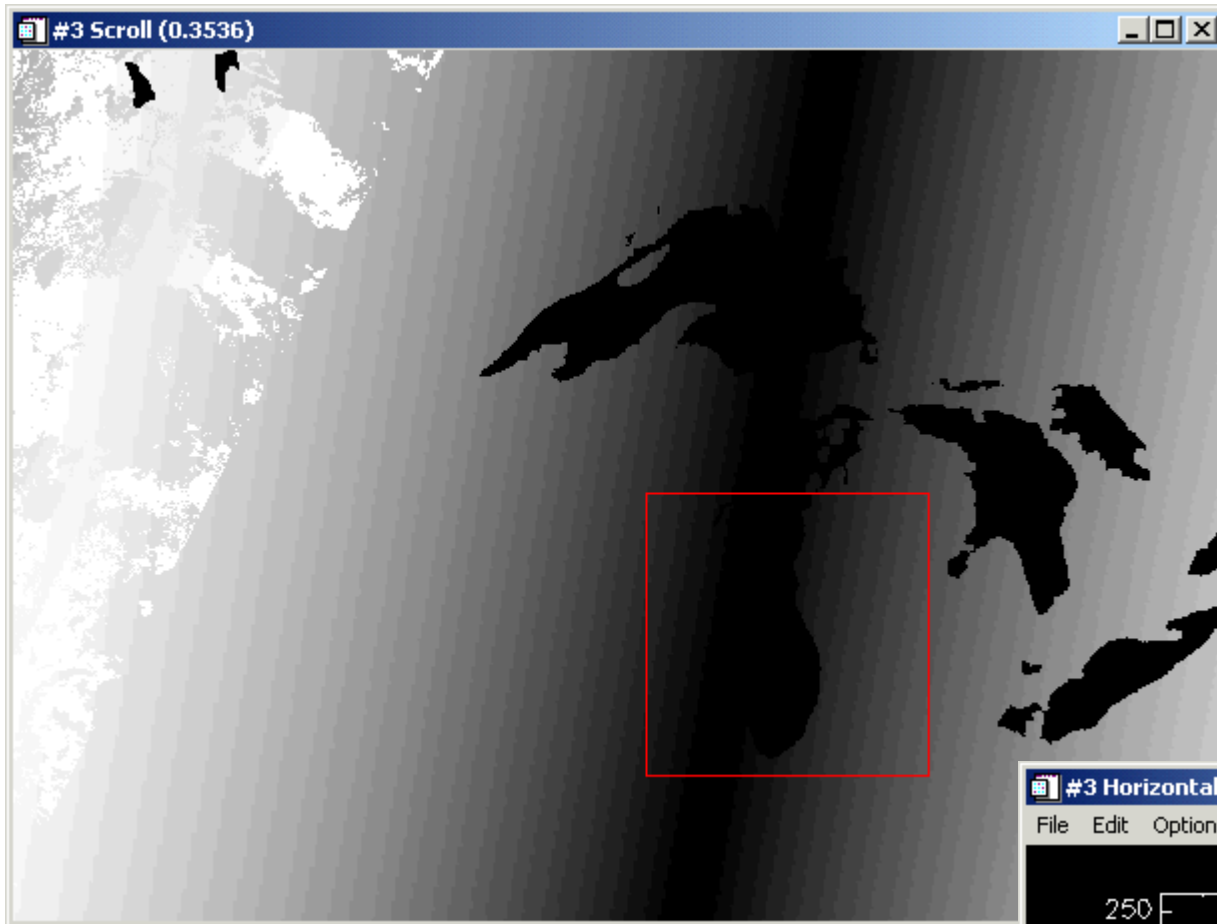
# BRDF Example 3 - Alfalfa

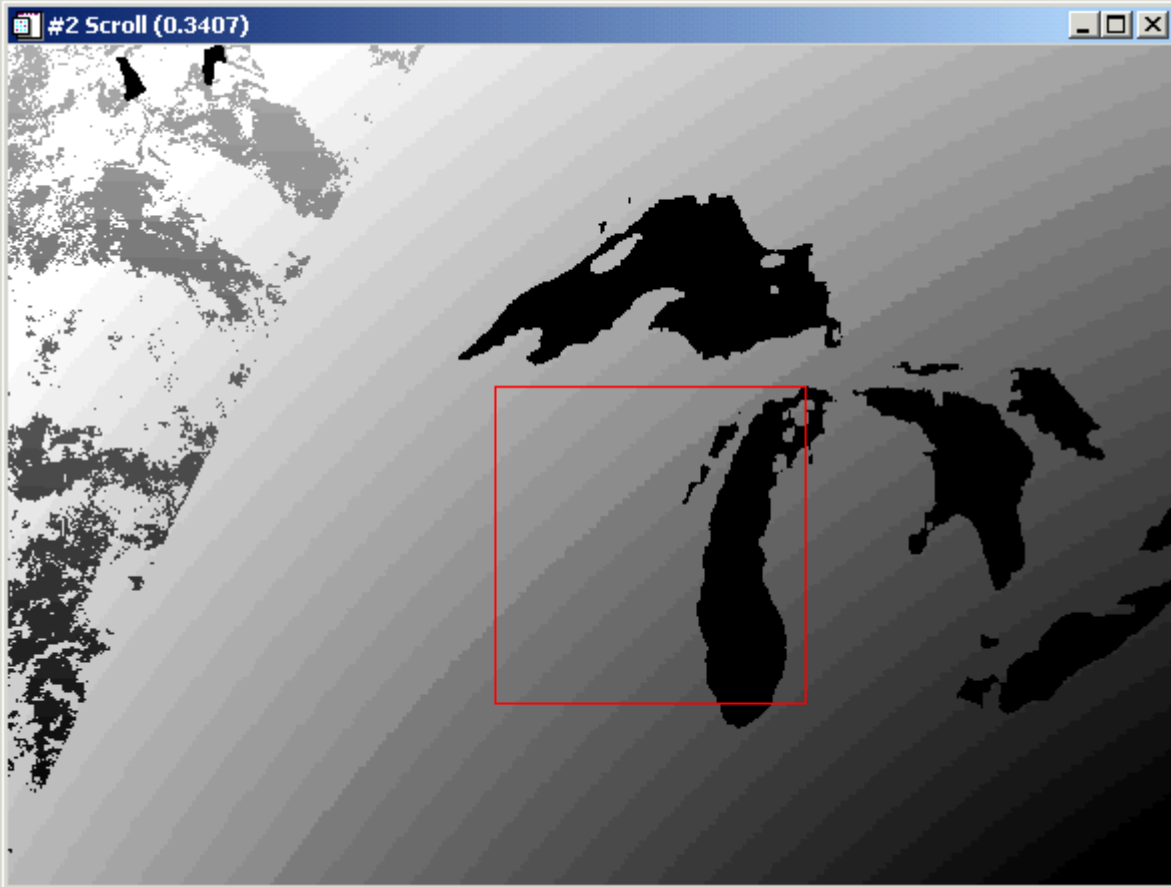
### coth0838, 90deg











# Issues

- Measurements at different view angles and directions can be substantially different;
- No standard viewing geometry, and sun elevation for remote sensing data acquisitions;
- Each sensor from different direction sees different thing;
- How can images acquired with varying geometric configuration be compared?
- Comparison across geographic location is difficult, due to sun angle difference;
- Measurements made at different time of a day are also different. When is an optimal time?
- Should measurements be normalized to a single viewing geometry? If so, how?

# Bidirectional Correction

- **Models must be established**
- Normalization standard must be determined
  - i. e., a set of sensor-target-sun geometry must be determined before correction is made
- Models vary with surface type
  - Ideally, different models (or same model but different coefficients) should be used for different surface types
- Many BRDF models exist and readily available
  - Challenges: Find appropriate model parameters for your crop type; even the same type crop, model parameters may vary depending on growth stage; select a model that best for your study



# Modeling BRDF

- Empirical models:
  - Use empirical functions to simulate the shape of BRDF
  - For example, Shibayama and Wiegand (1985)
- Semi-empirical models
  - Radiative transfer schemes, but with empirical approximation
  - For example Roujean et al. (1992),
- Geometric models
  - For example, Li and Strahler (1985)
- Theoretical models
  - Canopy radiative transfer modeling
  - For example, Ross's model, SAIL, Myneni et al., Hapke, etc..
- Kernel Driven models:
  - Wanner et al., (1995)
  - MODIS product

# Shibayama and Weigand Model

$$\rho = \rho_0 \left\{ 1 + \left( \beta_0 + \beta_1 \sin\left(\frac{\varphi}{2}\right) + \frac{\beta_2}{\cos \theta_s} \right) \sin \theta_v \right\}$$

Where  $\rho_0$  is reflectance at nadir view,  $\beta_0$ ,  $\beta_1$ , and  $\beta_2$  are coefficients empirically derived.

# Walthall Model 2001

$$r(q_s, q_v, f) = a_0 + a_1 q_s q_v \cos(f) + a_2 q_s^2 q_v^2 + a_3 (q_s^2 + q_v^2)$$

# Boreal and Gerstl, 1994 and Gilabert et al., 2000

$$R(\lambda) = f_v R_v(\lambda) + f_{is} R_{is}(\lambda) + f_{ss} R_{ss}(\lambda)$$

$$R_v(\lambda) = R_\infty(\lambda) + [\rho_s(\lambda) - R_\infty(\lambda)]e^{-C \times LAI}$$

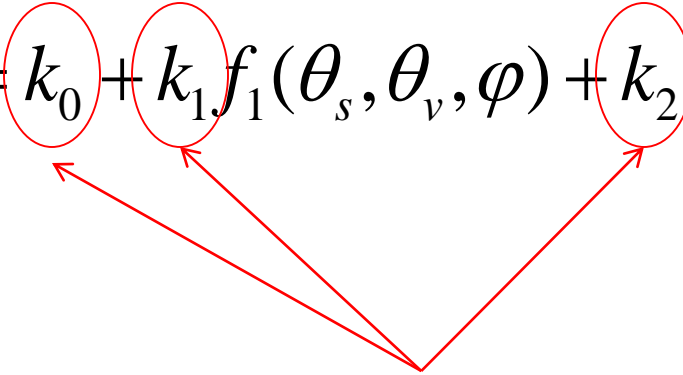
# Roujean et al., 1992

*Semi-empirical*

$$\rho(\theta_s, \theta_v, \varphi) = k_0 + k_1 f_1(\theta_s, \theta_v, \varphi) + k_2 f_2(\theta_s, \theta_v, \varphi)$$

# Roujean et al., 1992

*Semi-empirical*

$$\rho(\theta_s, \theta_v, \varphi) = k_0 + k_1 f_1(\theta_s, \theta_v, \varphi) + k_2 f_2(\theta_s, \theta_v, \varphi)$$


These coefficients should be different for each band and each biome

# Roujean et al., 1992

*Semi-empirical*

$$\rho(\theta_s, \theta_v, \varphi) = k_0 + k_1 f_1(\theta_s, \theta_v, \varphi) + k_2 f_2(\theta_s, \theta_v, \varphi)$$

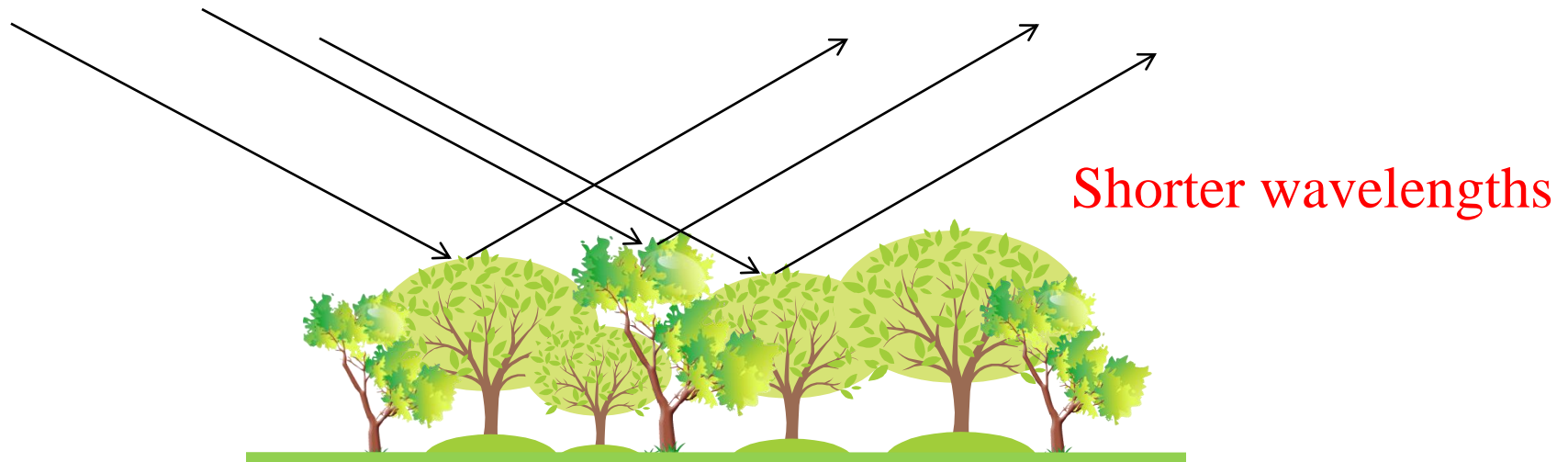
Related to albedo

# Roujean et al., 1992

*Semi-empirical*

$$\rho(\theta_s, \theta_v, \varphi) = k_0 + k_1 f_1(\theta_s, \theta_v, \varphi) + k_2 f_2(\theta_s, \theta_v, \varphi)$$

Represents 1<sup>st</sup> Order Scattering



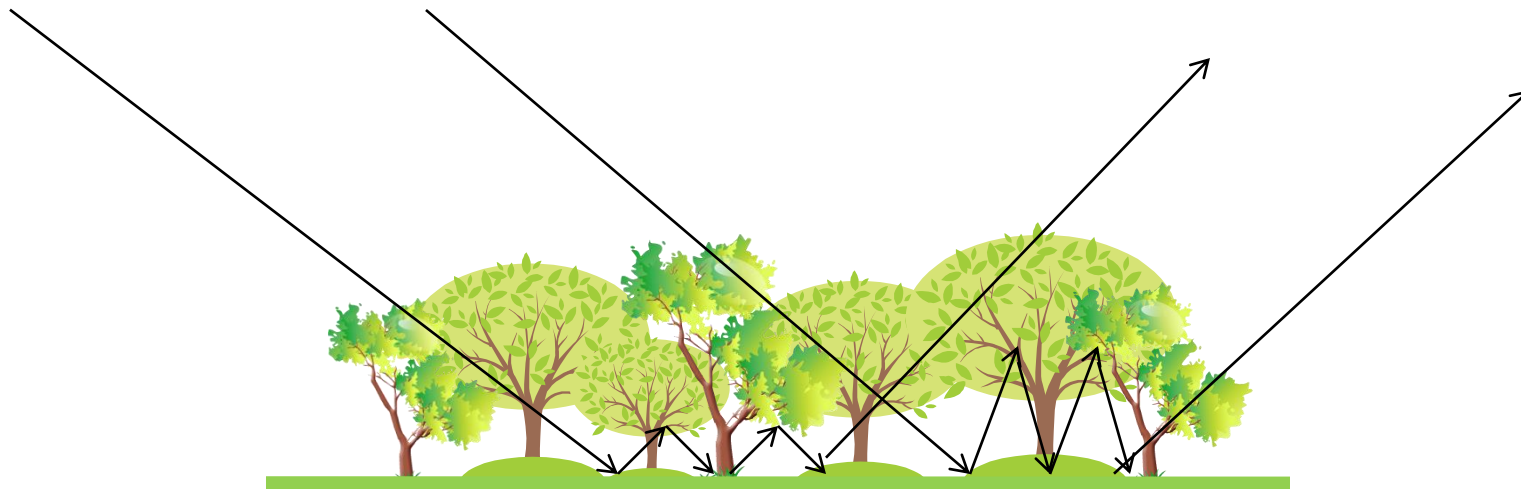


# Roujean et al., 1992

*Semi-empirical*

$$\rho(\theta_s, \theta_v, \varphi) = k_0 + k_1 f_1(\theta_s, \theta_v, \varphi) + k_2 f_2(\theta_s, \theta_v, \varphi)$$

Represents Volumetric Scattering



Longer wavelengths

# Roujean et al., 1992

*Semi-empirical*

$$\rho(\theta_s, \theta_v, \varphi) = k_0 + k_1 f_1(\theta_s, \theta_v, \varphi) + k_2 f_2(\theta_s, \theta_v, \varphi)$$

$$f_1(\theta_s, \theta_v, \varphi) = \frac{1}{2\pi} ((\pi - \varphi) \cos \varphi + \sin \varphi) \tan \theta_s \tan \theta_v - \frac{\tan \theta_s + \tan \theta_v + G}{\pi}$$

# Roujean et al., 1992

*Semi-empirical*

$$\rho(\theta_s, \theta_v, \varphi) = k_0 + k_1 f_1(\theta_s, \theta_v, \varphi) + k_2 f_2(\theta_s, \theta_v, \varphi)$$

$$f_1(\theta_s, \theta_v, \varphi) = \frac{1}{2\pi} \left( (\pi - \varphi) \cos \varphi + \sin \varphi \right) \tan \theta_s \tan \theta_v - \frac{\tan \theta_s + \tan \theta_v + G}{\pi}$$

$$f_2(\theta_s, \theta_v, \varphi) = \frac{4}{3\pi} \frac{1}{\cos \theta_s + \cos \theta_v} \left( \left( \frac{\pi}{2} - \xi \right) \cos \xi + \sin \xi \right) - \frac{1}{3}$$

# Roujean et al., 1992

*Semi-empirical*

$$\rho(\theta_s, \theta_v, \varphi) = k_0 + k_1 f_1(\theta_s, \theta_v, \varphi) + k_2 f_2(\theta_s, \theta_v, \varphi)$$

$$f_1(\theta_s, \theta_v, \varphi) = \frac{1}{2\pi} \left( (\pi - \varphi) \cos \varphi + \sin \varphi \right) \tan \theta_s \tan \theta_v - \frac{\tan \theta_s + \tan \theta_v + G}{\pi}$$

$$f_2(\theta_s, \theta_v, \varphi) = \frac{4}{3\pi} \frac{1}{\cos \theta_s + \cos \theta_v} \left( \left( \frac{\pi}{2} - \xi \right) \cos \xi + \sin \xi \right) - \frac{1}{3}$$

$$\cos \xi = \cos \theta_s \cos \theta_v + \sin \theta_s \sin \theta_v \cos \varphi$$

# Roujean et al., 1992

*Semi-empirical*

$$\rho(\theta_s, \theta_v, \varphi) = k_0 + k_1 f_1(\theta_s, \theta_v, \varphi) + k_2 f_2(\theta_s, \theta_v, \varphi)$$

$$f_1(\theta_s, \theta_v, \varphi) = \frac{1}{2\pi} \left( (\pi - \varphi) \cos \varphi + \sin \varphi \right) \tan \theta_s \tan \theta_v - \frac{\tan \theta_s + \tan \theta_v + G}{\pi}$$

$$f_2(\theta_s, \theta_v, \varphi) = \frac{4}{3\pi} \frac{1}{\cos \theta_s + \cos \theta_v} \left( \left( \frac{\pi}{2} - \xi \right) \cos \xi + \sin \xi \right) - \frac{1}{3}$$

$$\cos \xi = \cos \theta_s \cos \theta_v + \sin \theta_s \sin \theta_v \cos \varphi$$

$$G = \sqrt{\tan^2 \theta_s + \tan^2 \theta_v - 2 \tan \theta_s \tan \theta_v \cos \varphi}$$

# Roujean et al., 1992

## Solar Zenith

$$\rho(\theta_s, \theta_v, \varphi) = k_0 + k_1 f_1(\theta_s, \theta_v, \varphi) + k_2 f_2(\theta_s, \theta_v, \varphi)$$

$$f_1(\theta_s, \theta_v, \varphi) = \frac{1}{2\pi} \left( (\pi - \varphi) \cos \varphi + \sin \varphi \right) \tan \theta_s \tan \theta_v - \frac{\tan \theta_s + \tan \theta_v + G}{\pi}$$

$$f_2(\theta_s, \theta_v, \varphi) = \frac{4}{3\pi} \frac{1}{\cos \theta_s + \cos \theta_v} \left( \left( \frac{\pi}{2} - \xi \right) \cos \xi + \sin \xi \right) - \frac{1}{3}$$

$$\cos \xi = \cos \theta_s \cos \theta_v + \sin \theta_s \sin \theta_v \cos \varphi$$

$$G = \sqrt{\tan^2 \theta_s + \tan^2 \theta_v - 2 \tan \theta_s \tan \theta_v \cos \varphi}$$

# Roujean et al., 1992

View Zenith

$$\rho(\theta_s, \theta_v, \varphi) = k_0 + k_1 f_1(\theta_s, \theta_v, \varphi) + k_2 f_2(\theta_s, \theta_v, \varphi)$$

$$f_1(\theta_s, \theta_v, \varphi) = \frac{1}{2\pi} ((\pi - \varphi) \cos \varphi + \sin \varphi) \tan \theta_s \tan \theta_v - \frac{\tan \theta_s + \tan \theta_v + G}{\pi}$$

$$f_2(\theta_s, \theta_v, \varphi) = \frac{4}{3\pi} \frac{1}{\cos \theta_s + \cos \theta_v} \left( \left( \frac{\pi}{2} - \xi \right) \cos \xi + \sin \xi \right) - \frac{1}{3}$$

$$\cos \xi = \cos \theta_s \cos \theta_v + \sin \theta_s \sin \theta_v \cos \varphi$$

$$G = \sqrt{\tan^2 \theta_s + \tan^2 \theta_v - 2 \tan \theta_s \tan \theta_v \cos \varphi}$$

# Roujean et al., 1992

## Relative Azimuth

$$\rho(\theta_s, \theta_v, \varphi) = k_0 + k_1 f_1(\theta_s, \theta_v, \varphi) + k_2 f_2(\theta_s, \theta_v, \varphi)$$

$$f_1(\theta_s, \theta_v, \varphi) = \frac{1}{2\pi} ((\pi - \varphi) \cos \varphi + \sin \varphi) \tan \theta_s \tan \theta_v - \frac{\tan \theta_s + \tan \theta_v + G}{\pi}$$

$$f_2(\theta_s, \theta_v, \varphi) = \frac{4}{3\pi} \frac{1}{\cos \theta_s + \cos \theta_v} \left( \left( \frac{\pi}{2} - \xi \right) \cos \xi + \sin \xi \right) - \frac{1}{3}$$

$$\cos \xi = \cos \theta_s \cos \theta_v + \sin \theta_s \sin \theta_v \cos \varphi$$

$$G = \sqrt{\tan^2 \theta_s + \tan^2 \theta_v - 2 \tan \theta_s \tan \theta_v \cos \varphi}$$



# wak Model, 2001

$$\rho(\theta_s, \theta_v, \varphi) = S(H + H_i H_e - 1)$$

$$S = \frac{w \cos \theta_s}{4(\cos \theta_s + \cos \theta_v)}$$

$$H_i = \frac{1 + 2 \cos \theta_s}{1 + 2 \cos \theta_s \sqrt{1 - w}}$$

$$H = \frac{8}{3\pi} (\alpha + (\pi - \alpha) e^{-k\xi})$$

$$H_e = \frac{1 + 2 \cos \theta_v}{1 + 2 \cos \theta_v \sqrt{1 - w}}$$

$$\cos \xi = \cos \theta_s \cos \theta_v + \sin \theta_s \sin \theta_v \cos \varphi$$

# Rahman et al., 1993

$$\rho(\theta_s, \theta_v, \varphi) = \rho_0 \frac{(\cos \theta_s \cos \theta_v)^{k-1}}{(\cos \theta_s + \cos \theta_v)^{1-k}} \frac{1 - \Theta^2}{[1 + \Theta^2 - 2\Theta \cos(\pi - \xi)]^{3/2}} \left( 1 + \frac{1 - \rho_0}{1 + G} \right)$$

$$\cos \xi = \cos \theta_s \cos \theta_v + \sin \theta_s \sin \theta_v \cos \varphi$$

$$G = \sqrt{\tan^2 \theta_s + \tan^2 \theta_v - 2 \tan \theta_s \tan \theta_v \cos \varphi}$$

# Kuusk and Nilson, 2000

$$\rho(r_1, r_2) = \frac{I}{Q} \rho_1(r_1, r_2) + \frac{D}{Q} \rho_D(r_2)$$

$$\rho_D(r_2) = \frac{\int_{2\pi} d(r_1) \rho_I(r_1, r_2) \mu_1 dr_1}{D} \approx$$

$$\frac{\int_0^{2\pi} d(\theta_1, \phi - \frac{\pi}{2}) \rho_I(\theta_1, \theta_2, \phi - \frac{\pi}{2}) \mu_1 d\theta_1}{D}$$

$$I(r_1, r_2) = \frac{I_0(r_1) \mu_L \Gamma(r_1, r_2)}{\pi} \int_V p(x, y, z, s_1, s_2, \alpha) dx dy dz$$

# SAIL Model, Verhoef, 1984

$$dE_s/dx = kE_s$$

$$dE_-/dx = -s E_s + a E_- - E_+$$

$$dE_+/dx = s' E_s + E_- - a E_+$$

$$dE_o/dx = w E_s + vE_- + u E_+ - KE_o$$

where  $E_s$  is direct solar flux,  $E_-$  and  $E_+$  are diffuse downward and upward flux,  $E_o$  is total solar irradiance,  $K$  is extinction coefficient, and  $k$ ,  $s$ ,  $s'$ ,  $a$ , are coefficients related to surface properties.

MS-DOS F:\SAIL\SAIL.EXE

**Set Default Para**  
 Set Output LAI  
 Input data/Option  
 Canopy Composition  
 Default Leaf Distn  
 Run SAIL model  
 ViewFile/SetDIR  
 Quit!

**SAIL MODEL INPUT PARAMETERS**

FRACTION SPEC. FLUX: 1.00  
 SOLAR DECLINATION: 0.00°  
 LATITUDE: 10.00°  
 VIEW AZIMUTH ANGLE: 0.00°  
 VIEW ZENITH ANGLE: 0.00°  
 Time of the Day: 11:00  
 Calculate APAR: Yes

MS-DOS F:\SAIL\SAIL.EXE

Set Default Para  
 Set Output LAI  
**Input data/Option**  
 Canopy Composition  
 Default Leaf Distn  
 Run SAIL model  
 ViewFile/SetDIR  
 Quit!

**INPUT DATA/OPTIONS**

Number of Canopy Layer(s): 1  
 Number of Component(s): 2  
 Data source: **Files**  
 Rf & Tr<Comp# 1>: SOYBEAN.DAT  
 Rf & Tr<Comp# 2>: HEMLOCK.DAT  
 Background Refl.: BACKGDRF.DAT  
 Number of Wavelength(s): 31

MS-DOS F:\SAIL\SAIL.EXE

Set Default Para  
 Set Output LAI  
 Input data/Option  
 Canopy Composition  
**Default Leaf Distn**  
 Run SAIL model  
 ViewFile/SetDIR  
 Quit!

**LEAF ANGLE DISTRBUTN**

	angles	Percent
1	5.0°	22.05
2	15.0°	20.73
3	25.0°	18.25
4	35.0°	14.91
5	45.0°	11.11
6	55.0°	7.32
7	65.0°	3.97
8	75.0°	1.49
9	85.0°	0.17
		100.00

MS-DOS F:\SAIL\SAIL.EXE

Set Default Para  
**Set Output LAI**  
 Input data/Option  
 Canopy Composition  
 Default Leaf Distn  
 Run SAIL model  
 ViewFile/SetDIR  
 Quit!

#	LAI
1	0.01
2	0.25
3	0.50
4	0.75
5	1.00
6	1.25
7	1.50
8	2.50
9	4.00

MS-DOS F:\SAIL\SAIL.EXE

Input data

Solar Zenith Angle = 17.96°

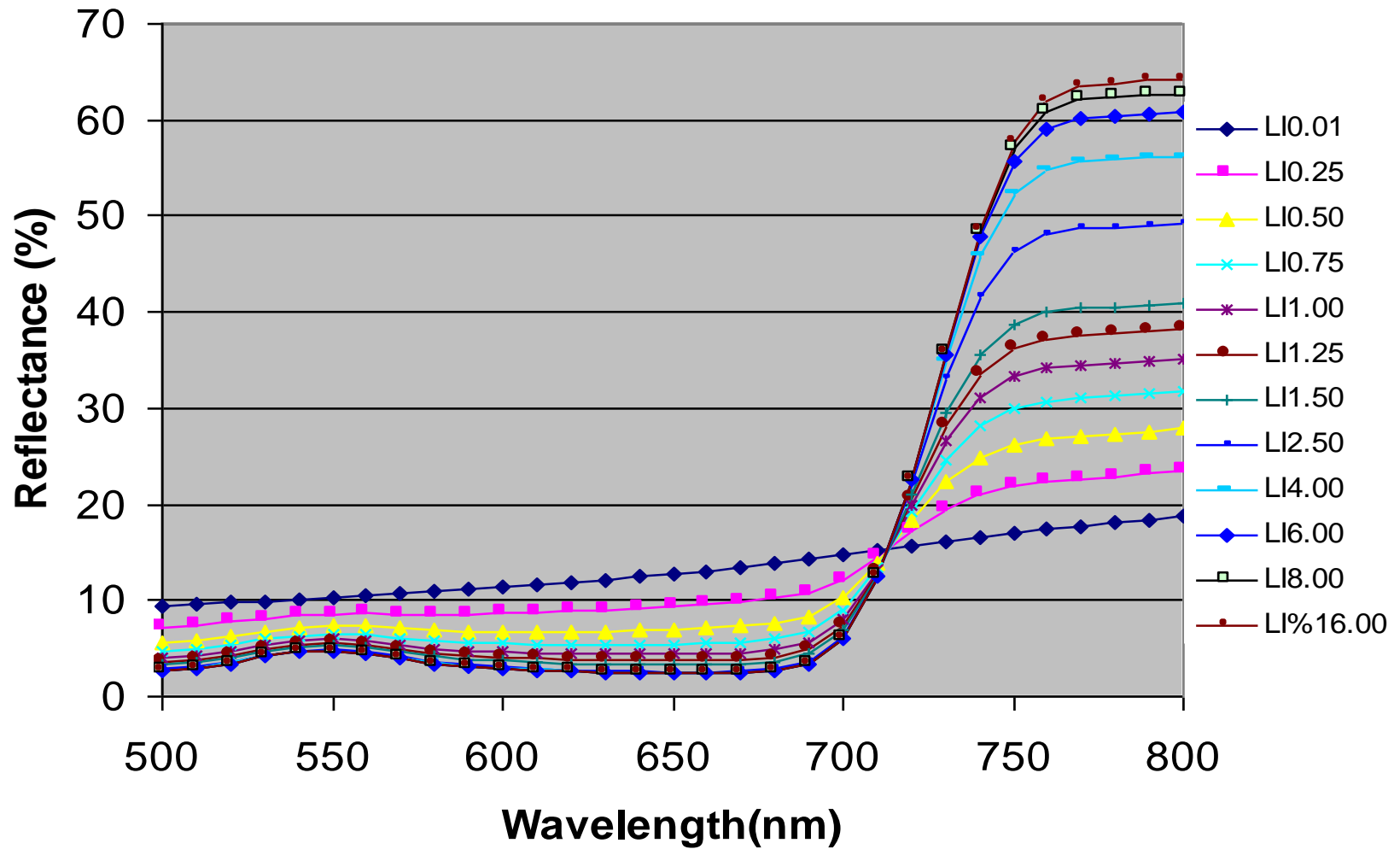
Current Wavelength = 800.00

Background (Refl.) = 18.47

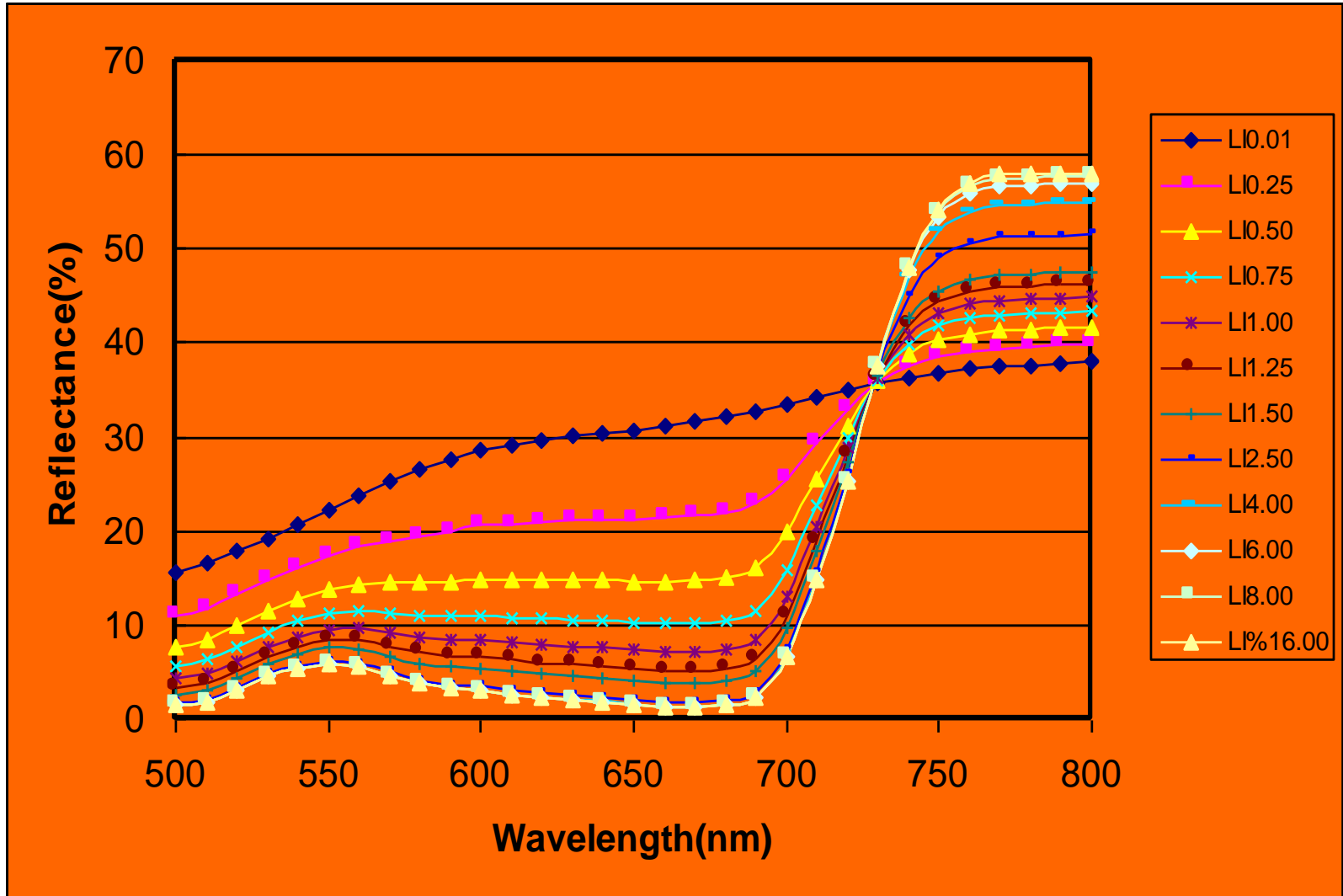
#	CompFileName	Refl.	Trans.
1	SOYBEAN.DAT	48.03	48.02
2	HEMLOCK.DAT	48.31	43.62

LAI	Refl.	Tran.
0.01	18.677	99.938
0.25	23.311	98.459
0.50	27.512	96.942
0.75	31.177	95.448
1.00	34.385	93.979
1.25	37.201	92.535
1.50	39.676	91.120
2.50	46.952	85.780
4.00	52.837	78.901
6.00	56.158	71.946
8.00	57.381	67.193
%16.	58.087	60.092

# One Layer Soybean Simulation



# SAIL model





# Model Summary

1. Model performance is very similar in many cases

2. Selection criteria:

Simple

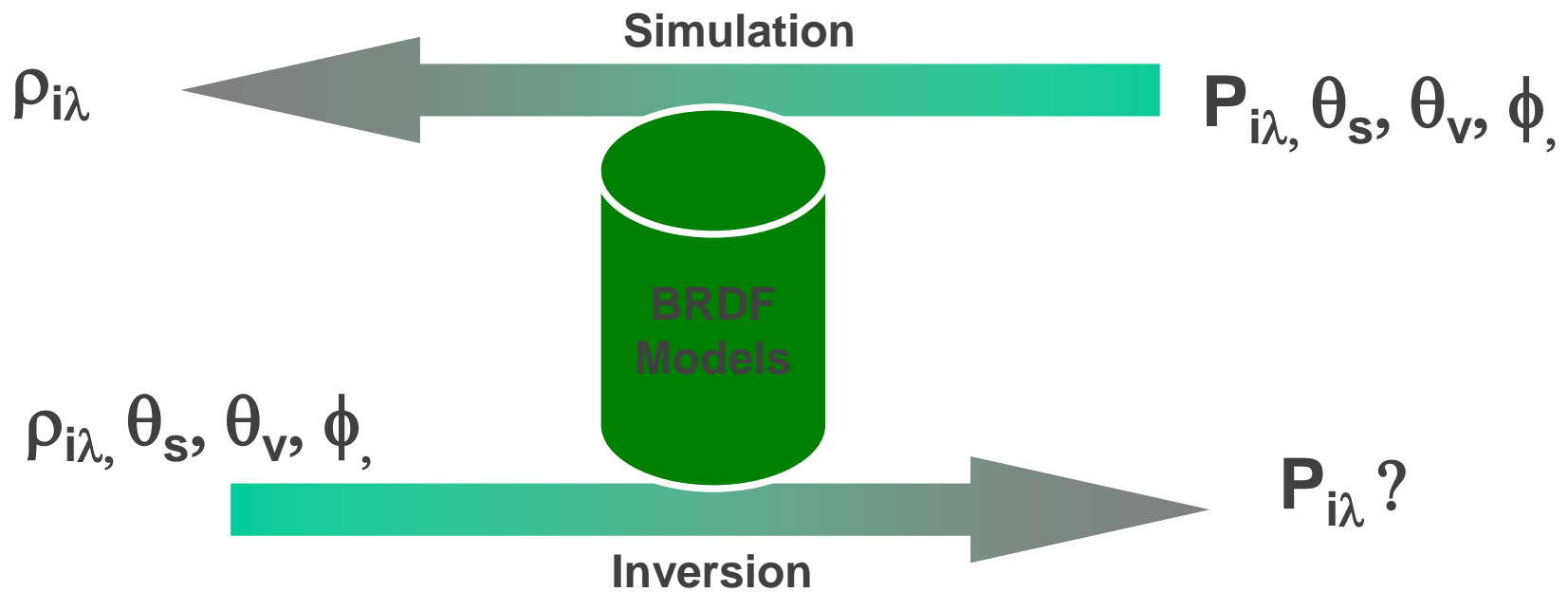
Fewer model parameters

Multiplicative forms preferred

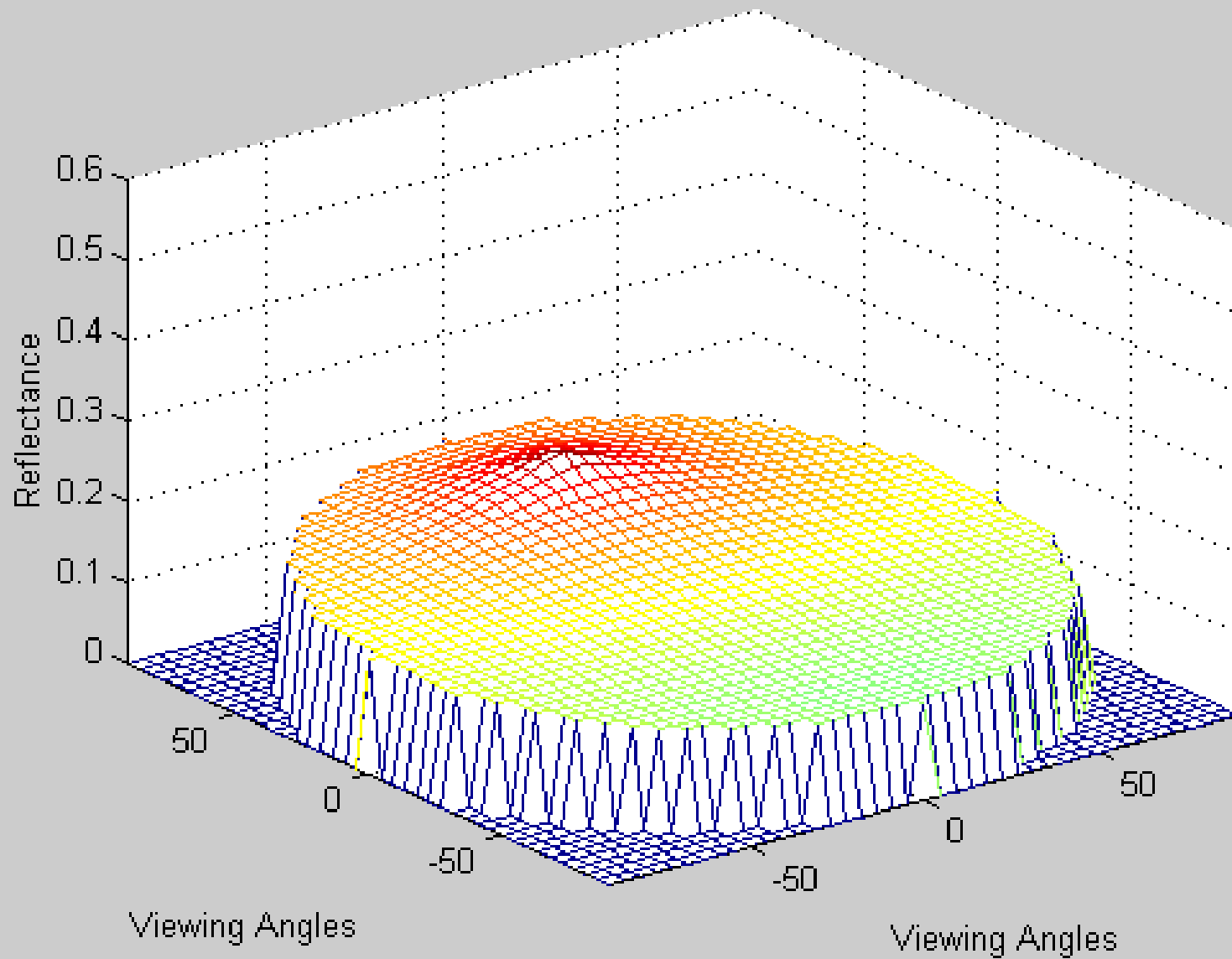
Computation time

# Simulation and Inversion

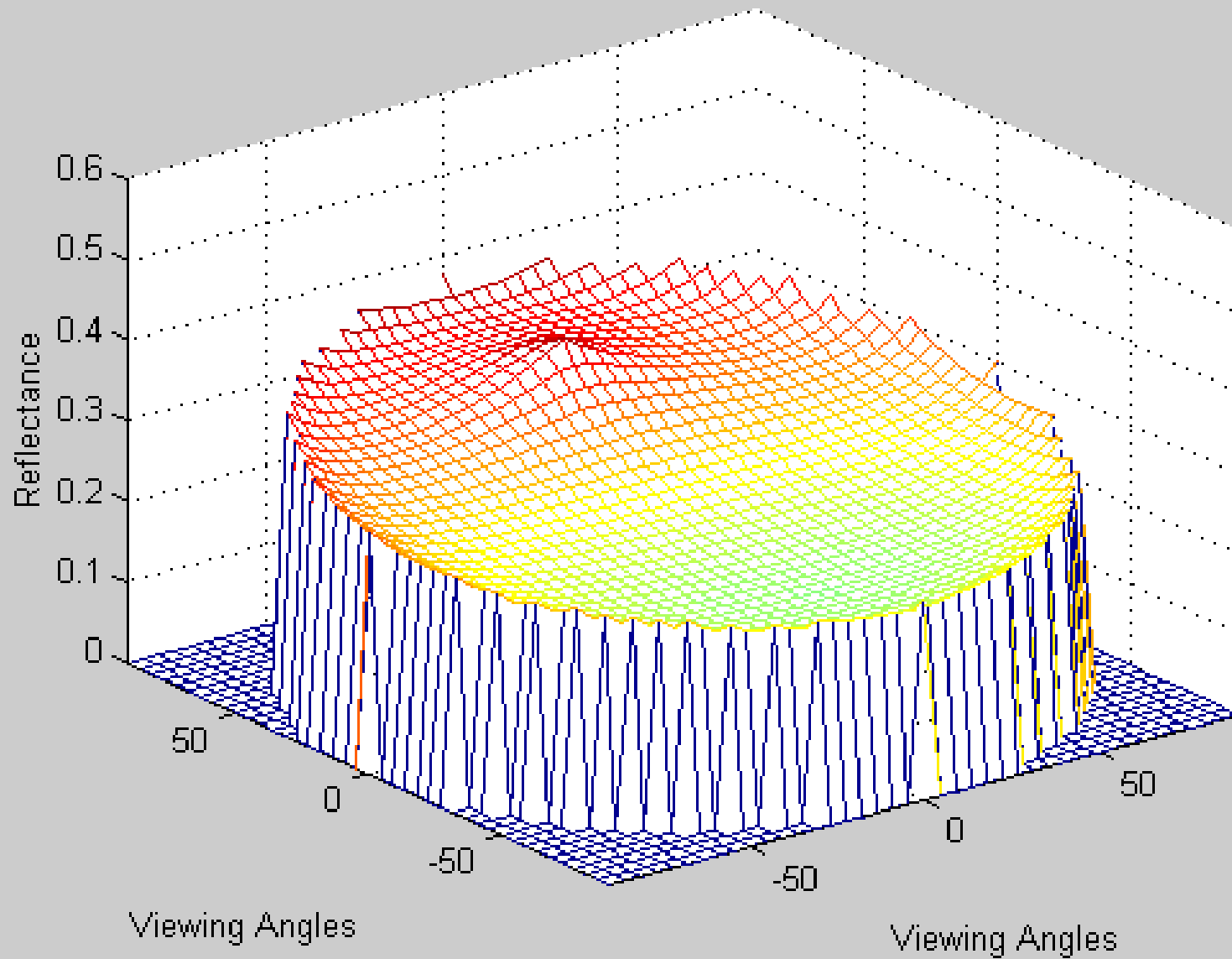
$$\rho = f(P, \theta_s, \theta_v, \phi)$$



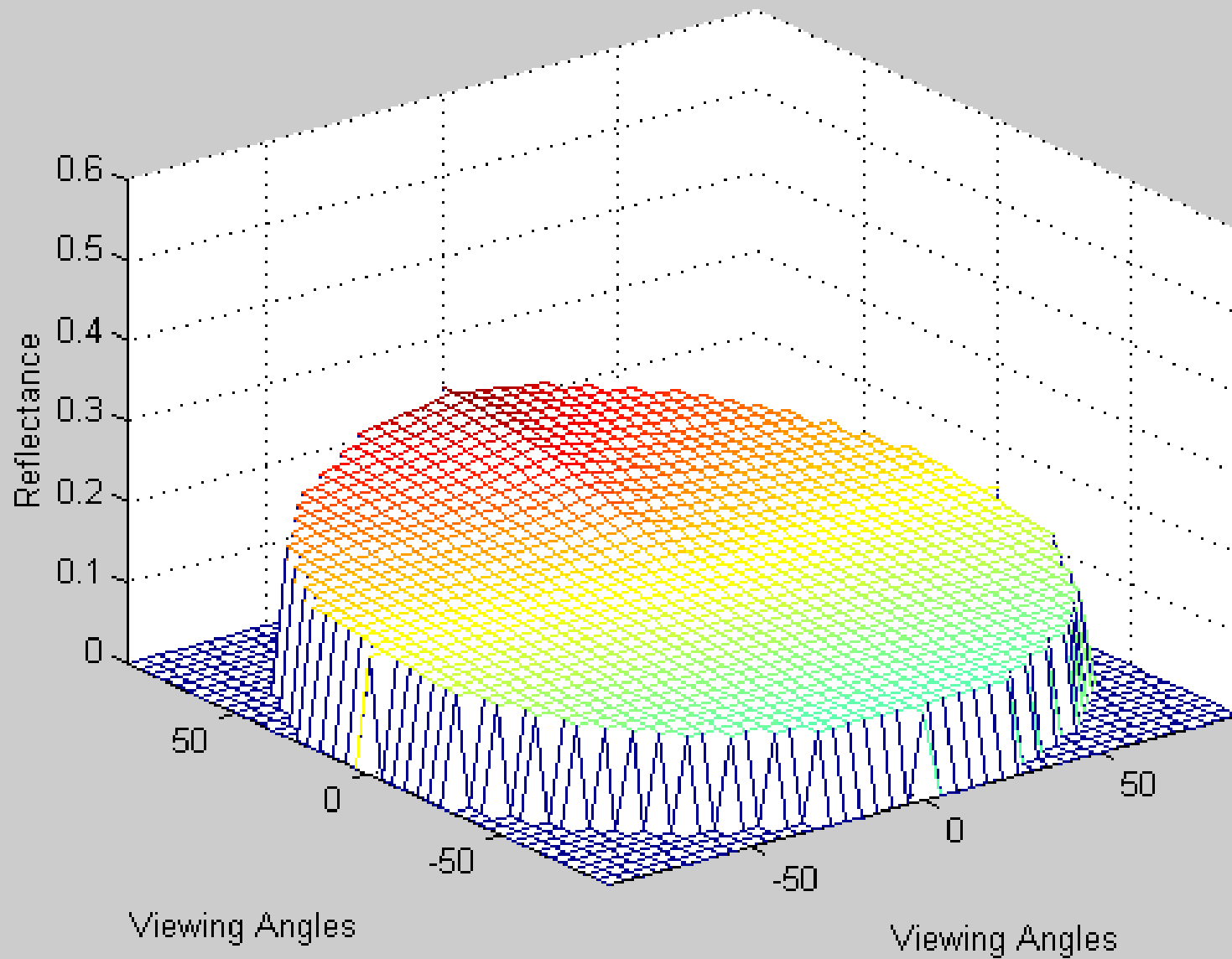
Rahman et al. Model (Red)



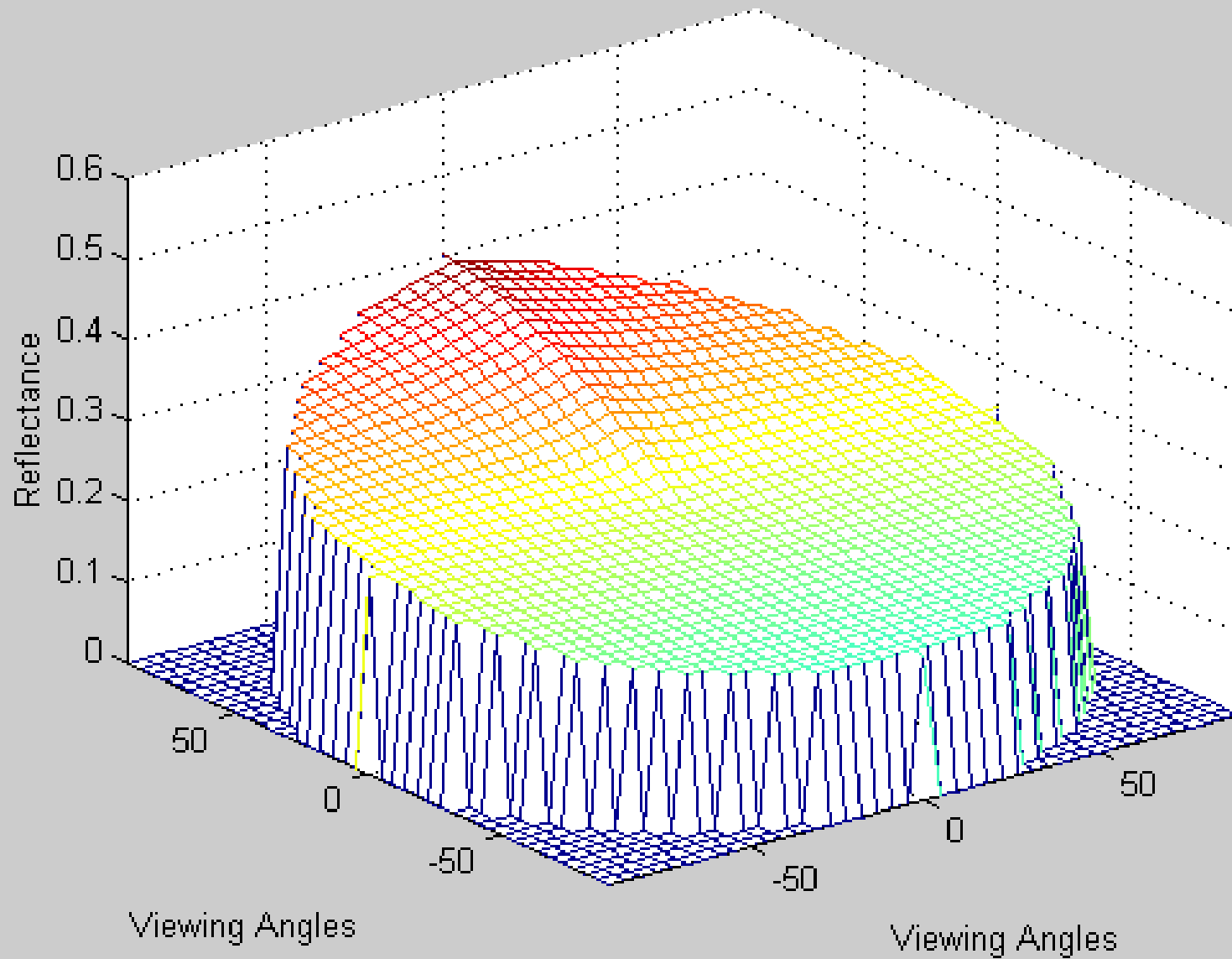
Rahman et al. Model (NIR)



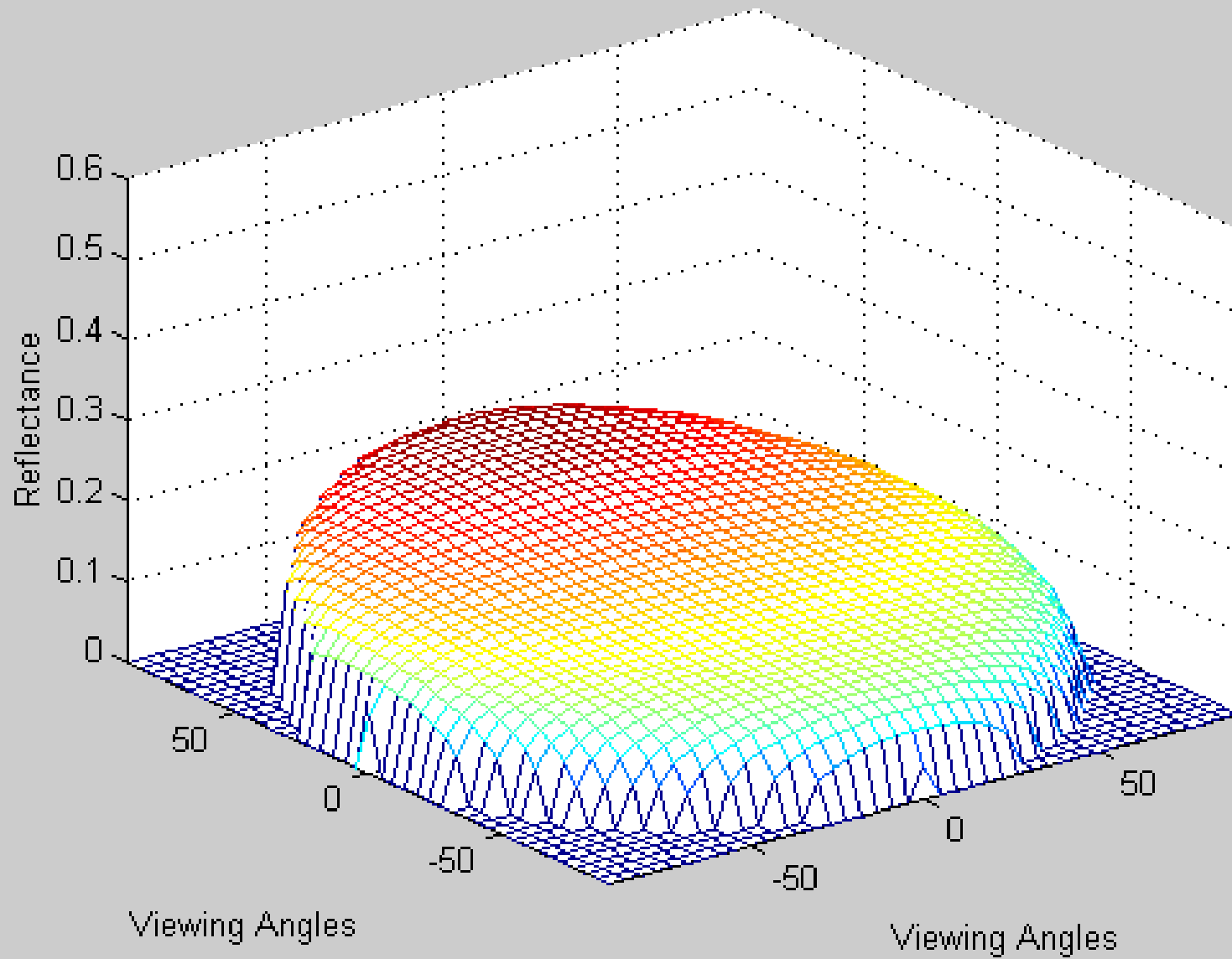
Shibayama and Weigand Model (Red)



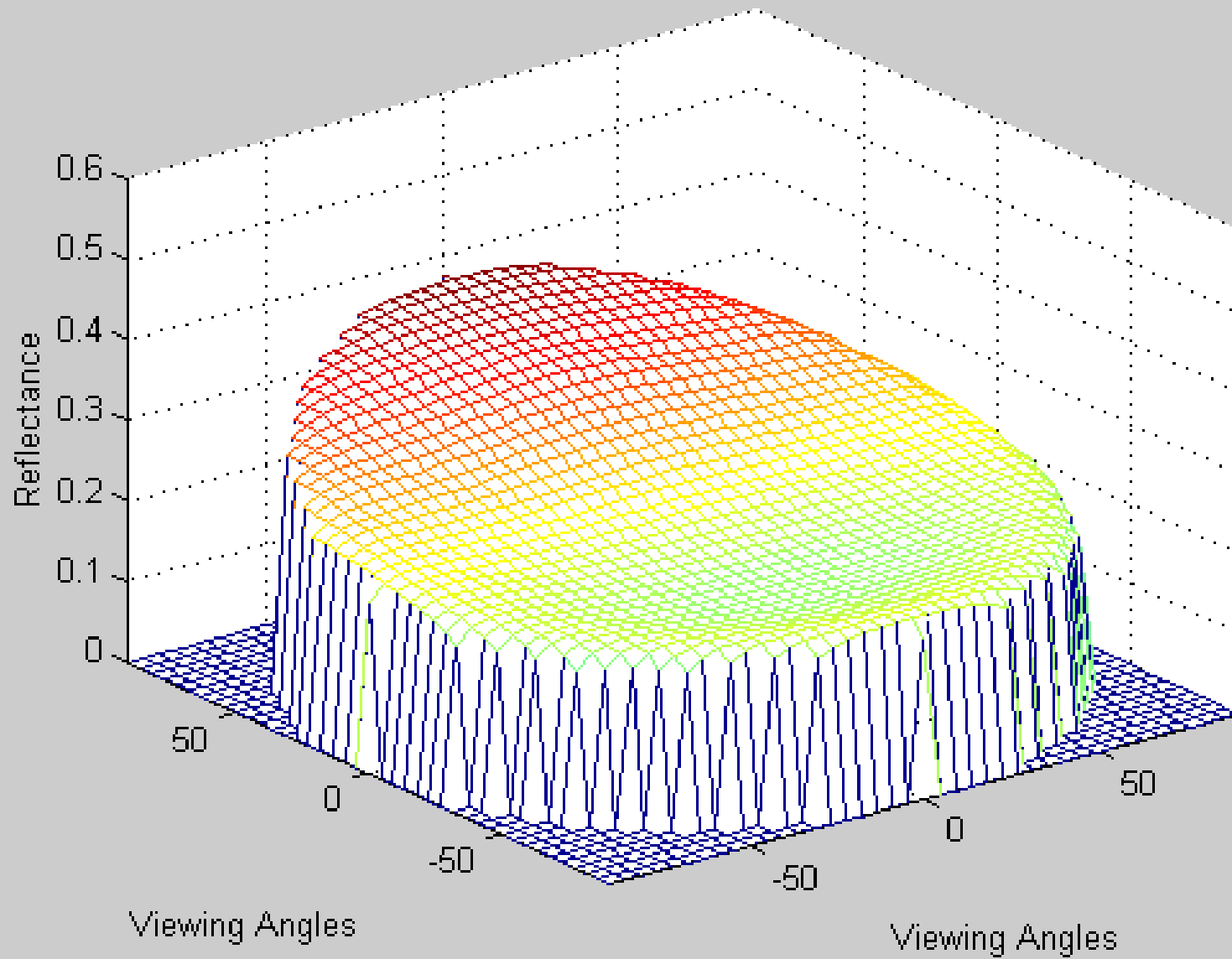
Shibayama and Weigand Model (NIR)



Roujean Model (Red)

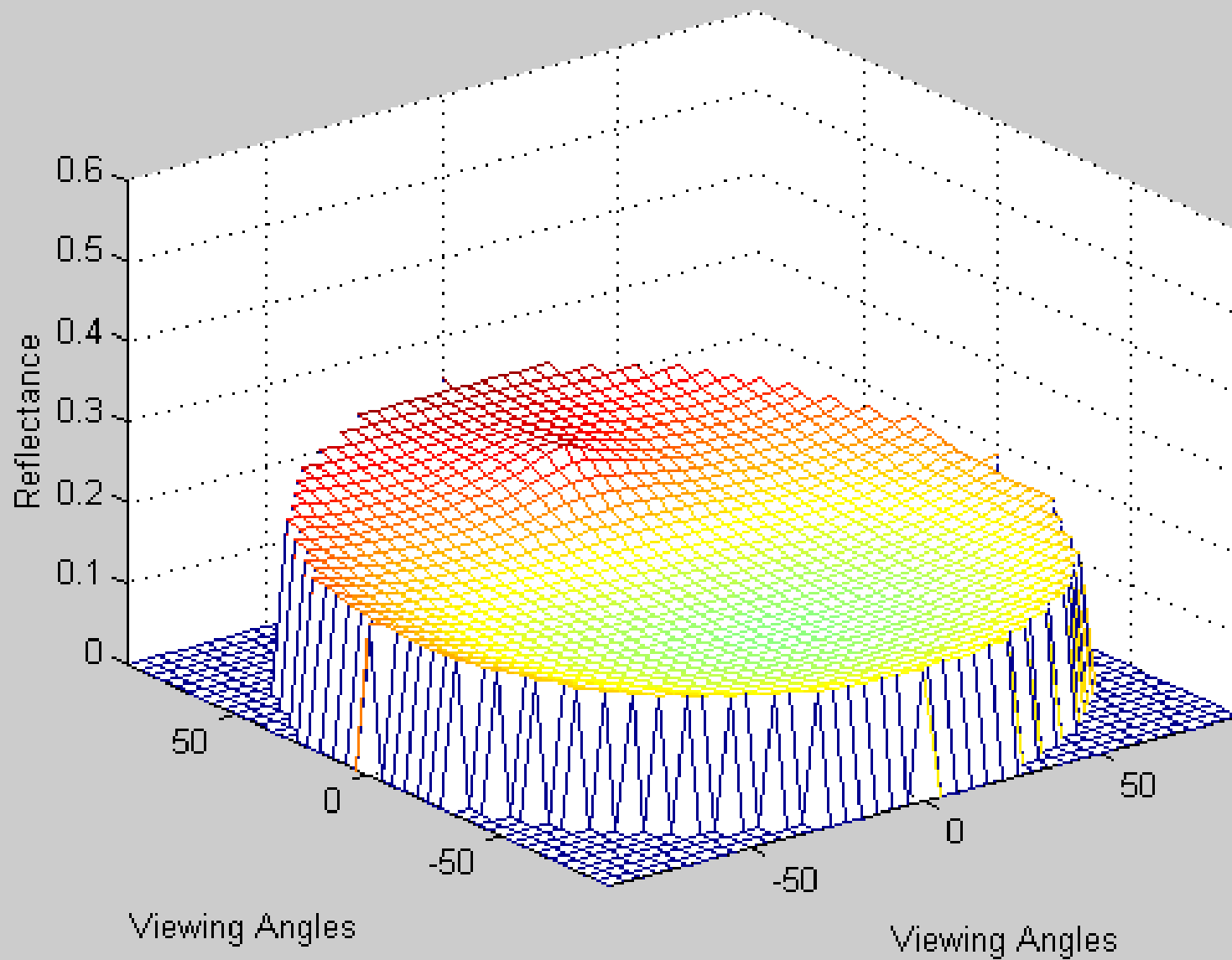


Roujean Model (NIR)

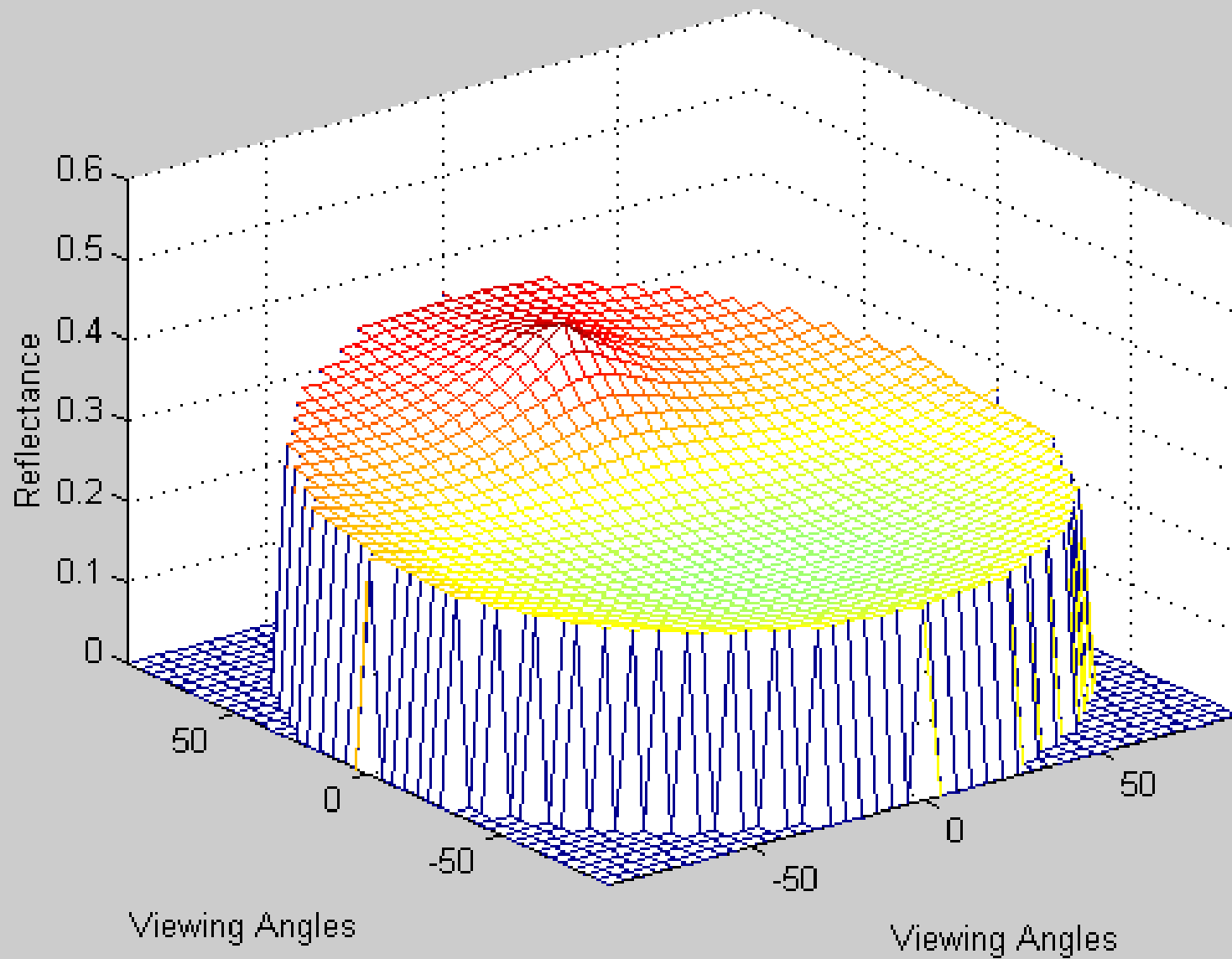




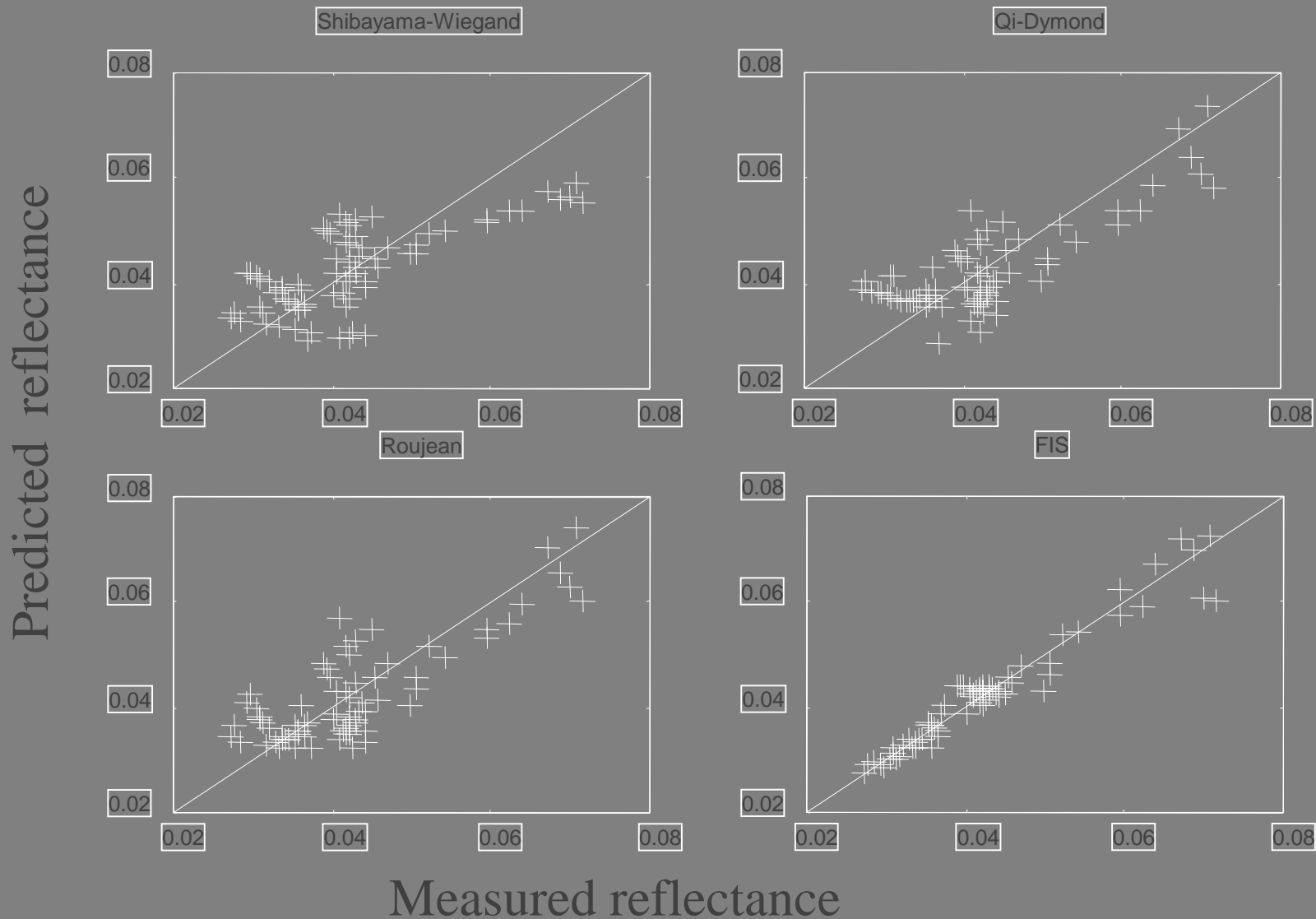
WAK Model (Red)



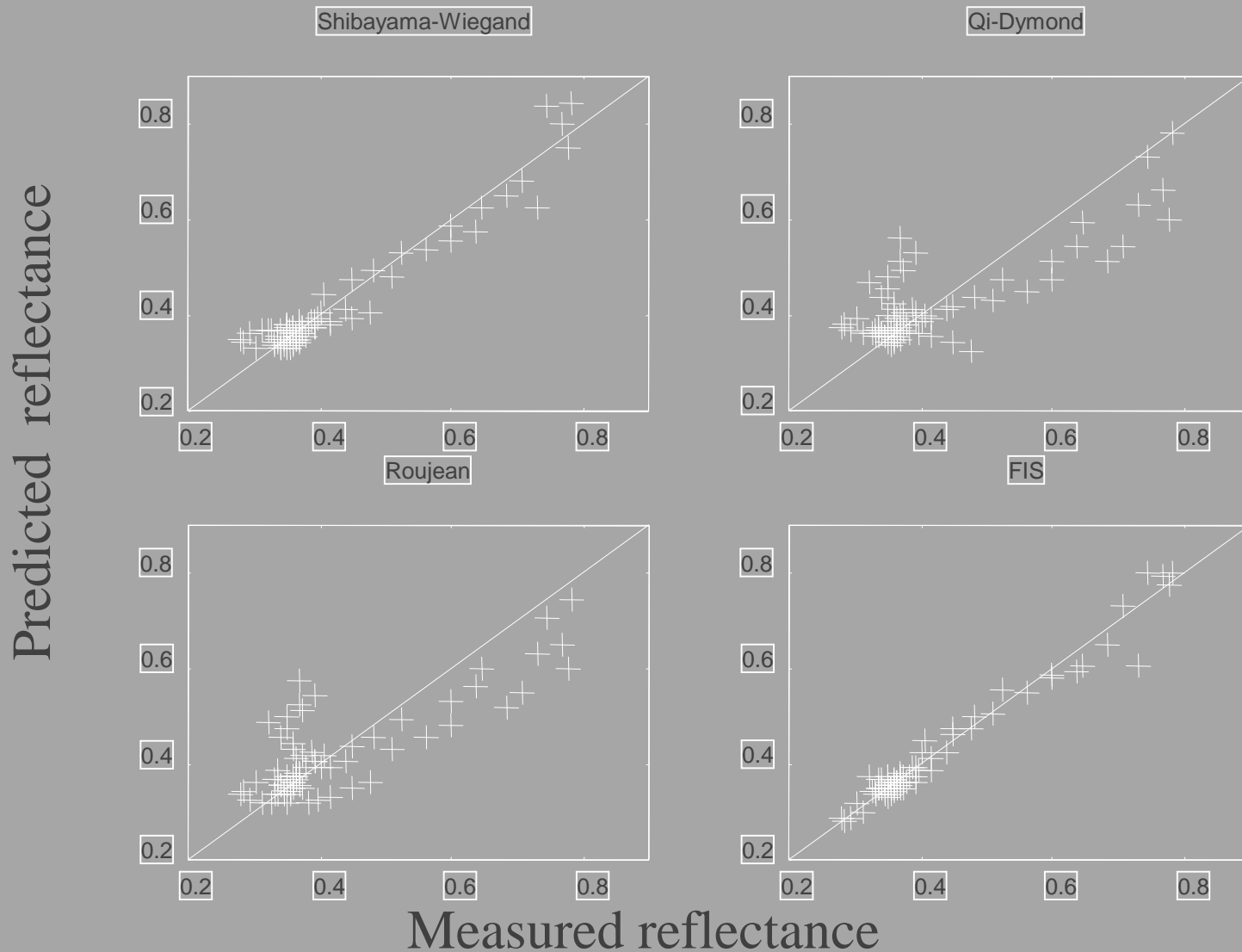
WAK Model (NIR)



# Comparison with other models (TM Band 3)



# Comparison with other models (TM Band 3)



# BRDF Correction

$$\rho = \rho_0 \left\{ 1 + \left( \beta_0 + \beta_1 \sin\left(\frac{\varphi}{2}\right) + \frac{\beta_2}{\cos \theta_s} \right) \sin \theta_v \right\}$$

Two ways of using models:

1) Given  $\rho_0$ ,  $\beta_0$ ,  $\beta_1$ ,  $\beta_2$  one can simulate canopy reflectance and compute correction factors

2). Given canopy reflectance measurements, one can run the model in reverse model to obtain  $\rho_0$ ,  $\beta_0$ ,  $\beta_1$ , and  $\beta_2$  parameters and then compute correction factors

# BRDF Correction

Once  $\rho_0$ ,  $\beta_0$ ,  $\beta_1$ ,  $\beta_2$  are known, one can calculate correction factors:

$$f = \left\{ 1 + \left( \beta_0 + \beta_1 \sin\left(\frac{\varphi}{2}\right) + \frac{\beta_2}{\cos \theta_s} \right) \sin \theta_v \right\}$$

Note:  $\rho_0$  is related to the magnitude of surface reflectances while  $f$  is related to the BRDF shape.

# BRDF Correction

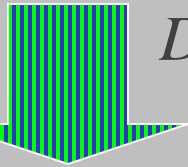
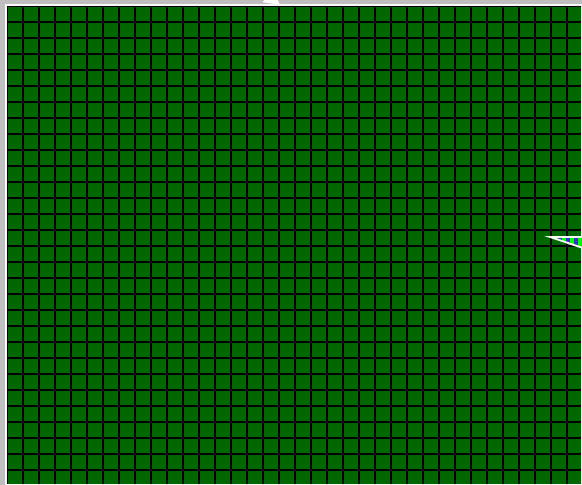
If a model can not be explicitly expressed as a function “correction factor”  $f$ , one can compute expected reflectance and the standardized reflectance

$$\rho(\theta_s, \theta_v, \varphi) = k_0 + k_1 f_1(\theta_s, \theta_v, \varphi) + k_2 f_2(\theta_s, \theta_v, \varphi)$$

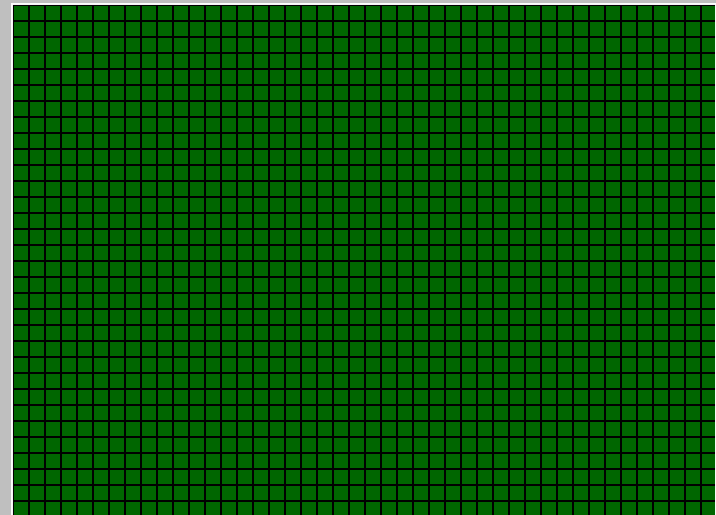
$$\rho(\theta_s, \theta_v, \varphi) = \rho_0 \frac{(\cos \theta_s \cos \theta_v)^{k-1}}{(\cos \theta_s + \cos \theta_v)^{1-k}} \frac{1 - \Theta^2}{[1 + \Theta^2 - 2\Theta \cos(\pi - \xi)]^{3/2}} \left( 1 + \frac{1 - \rho_0}{1 + G} \right)$$

# Correction Technique

(i,j) For each pixel, compute  $f(i,j) = \rho_o(i,j) / \rho(i,j)$

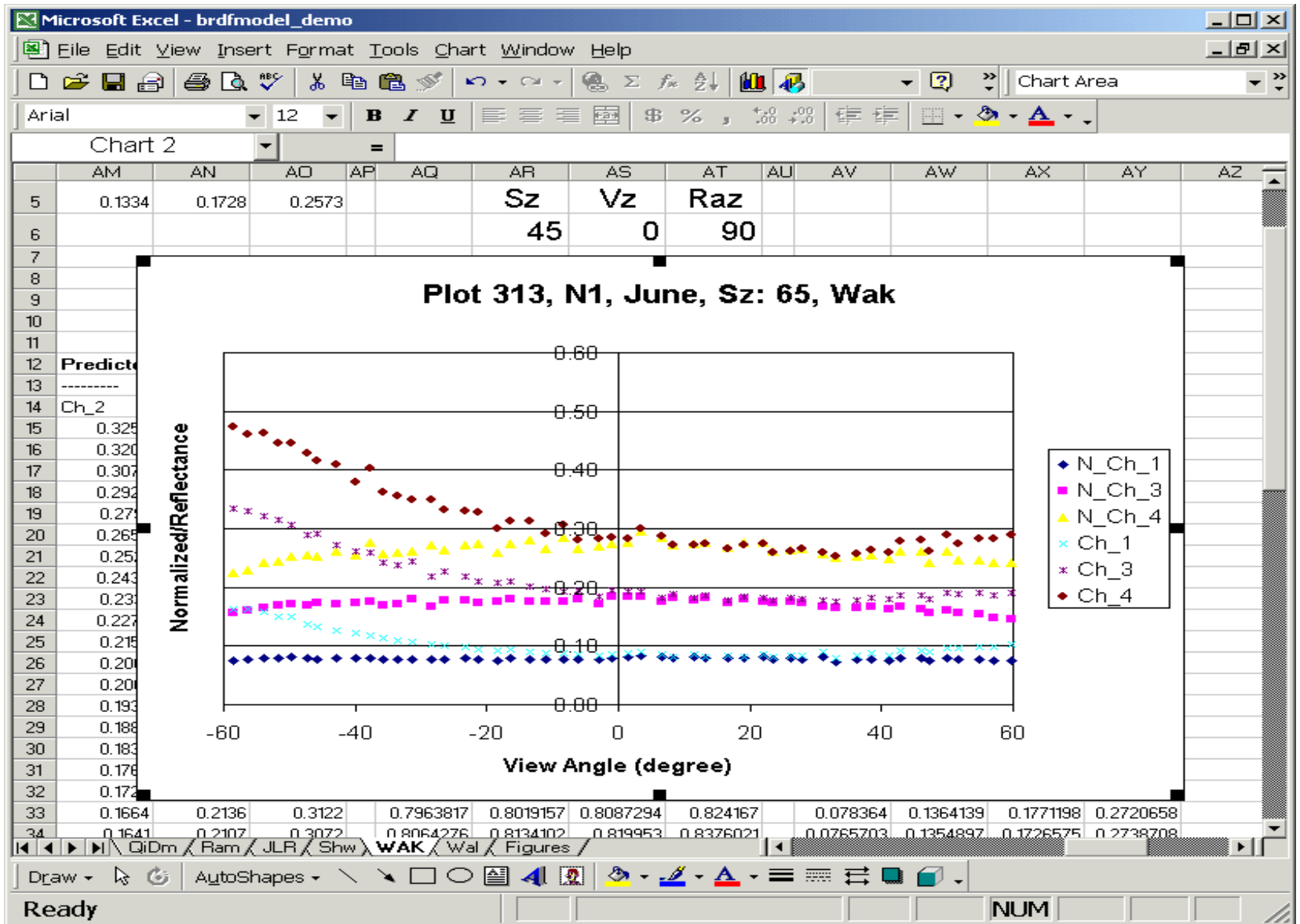


$$DN_{new}(i,j) = DN(i,j) * \rho_o(i,j) / \rho(i,j)$$

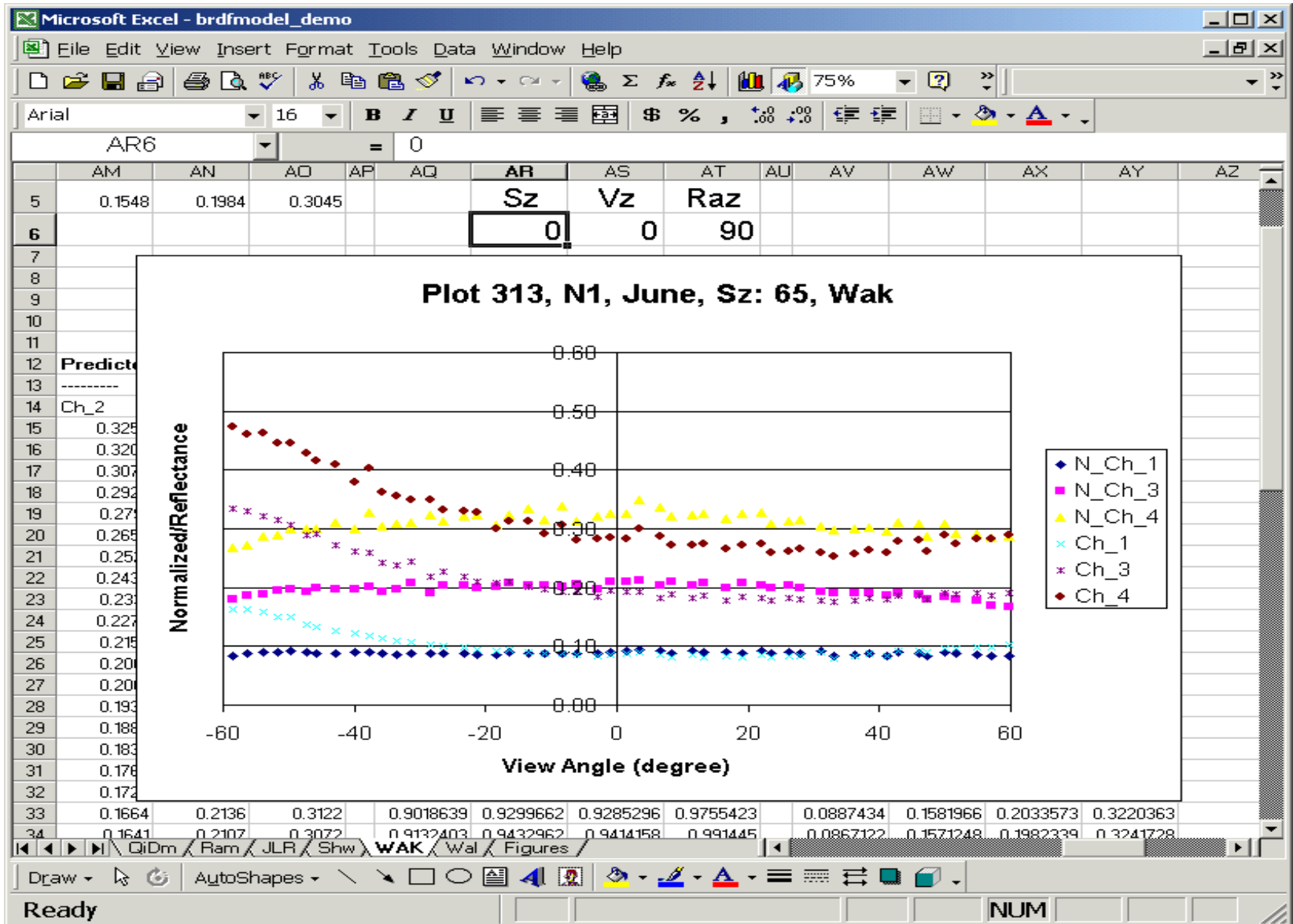




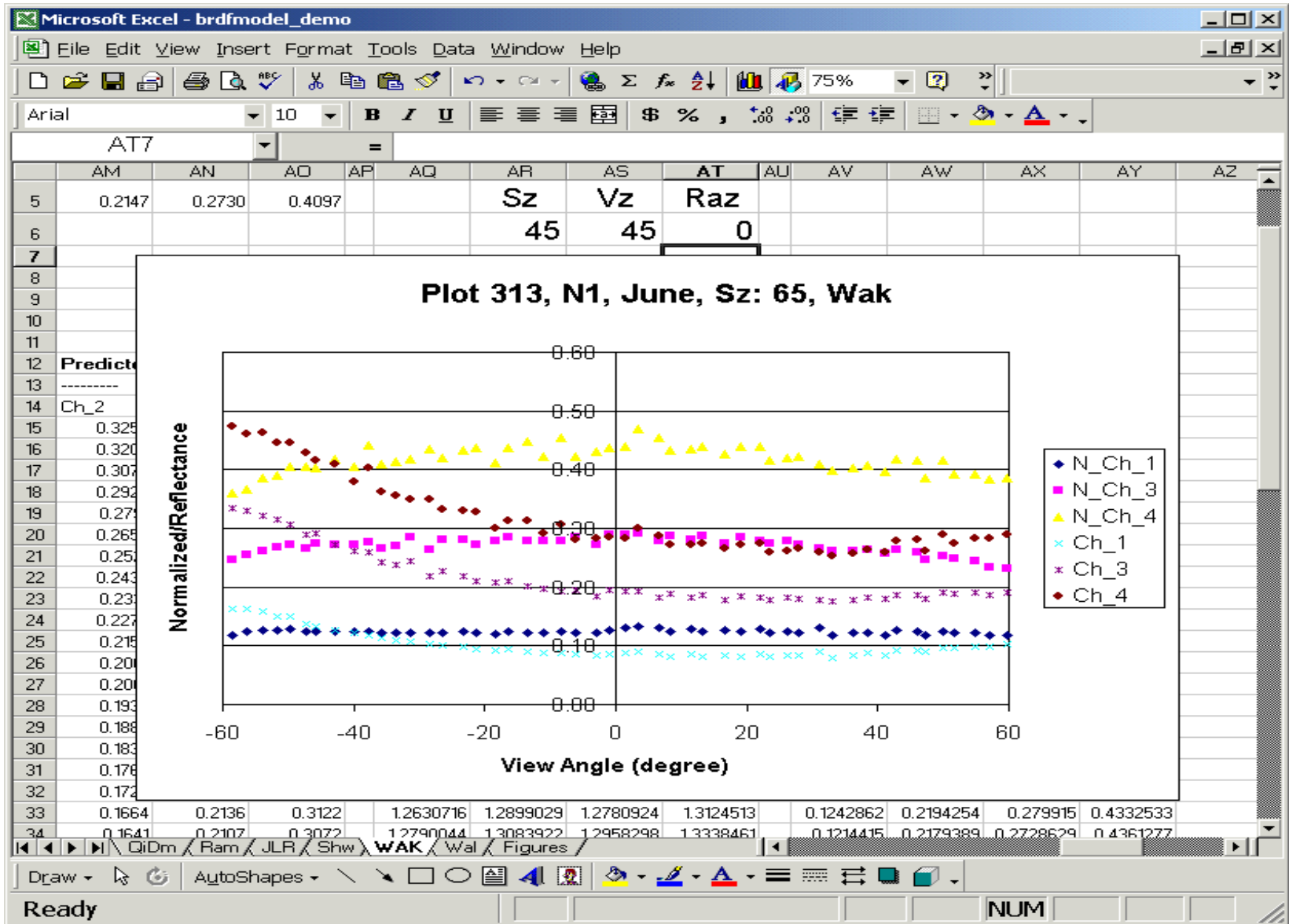
# BRDF Correction Example



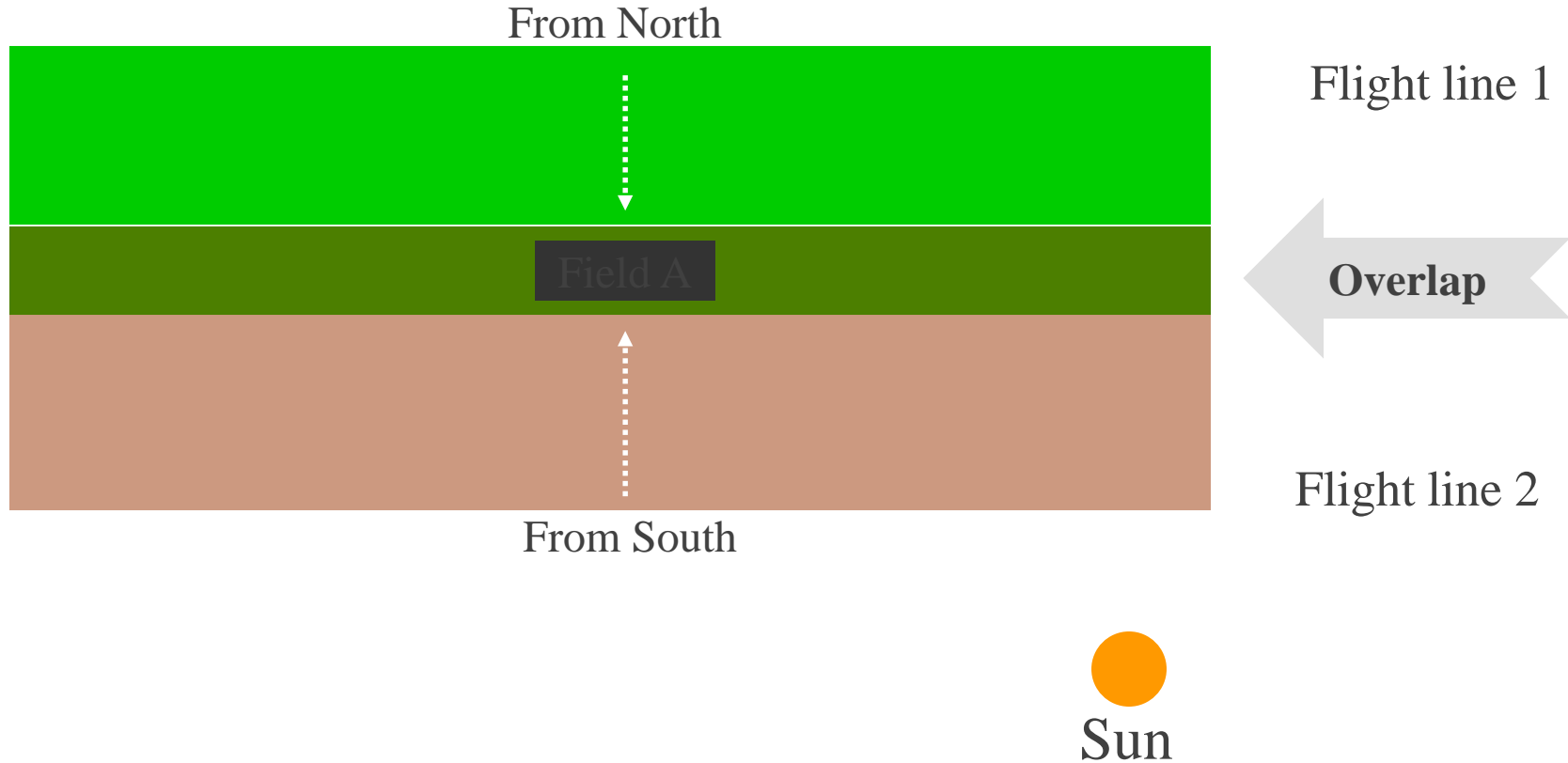
# BRDF Correction Example



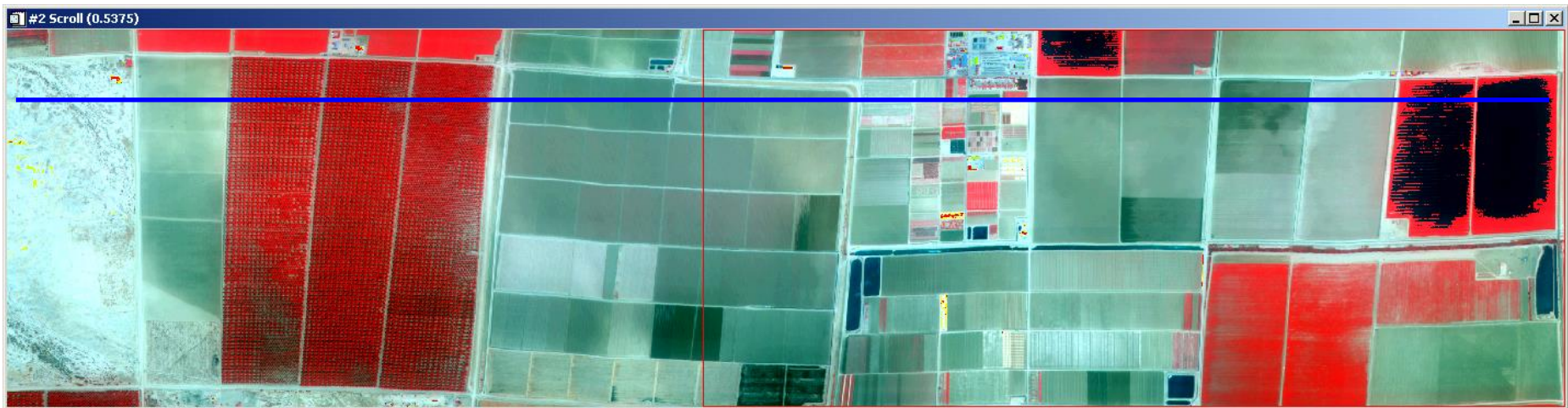
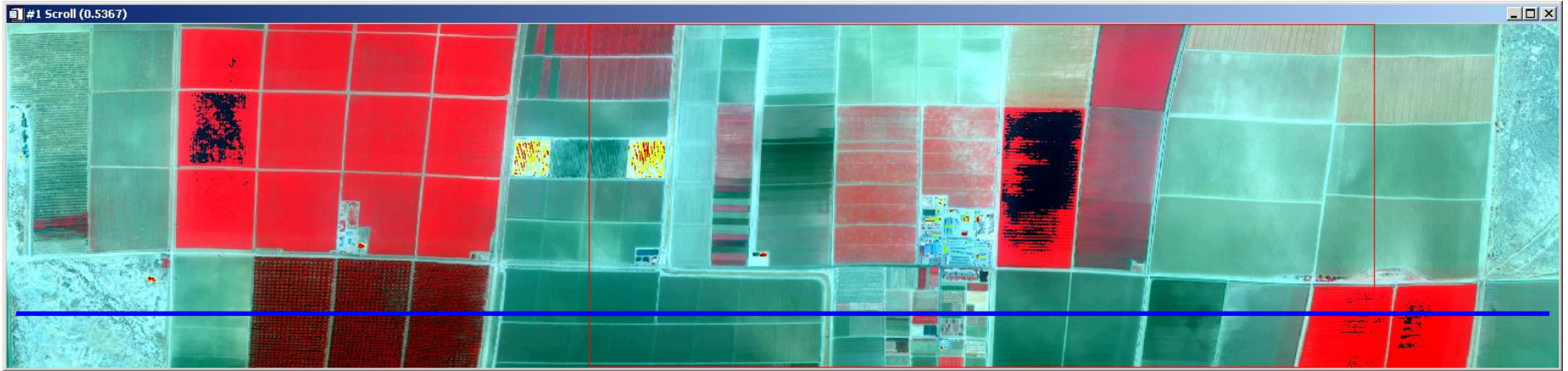
# BRDF Correction Example

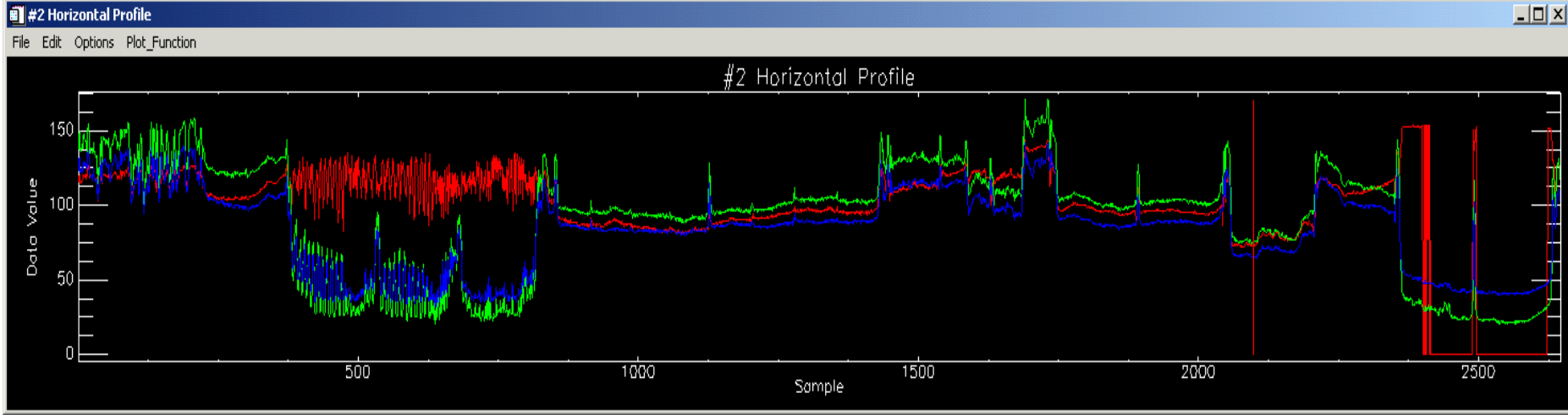
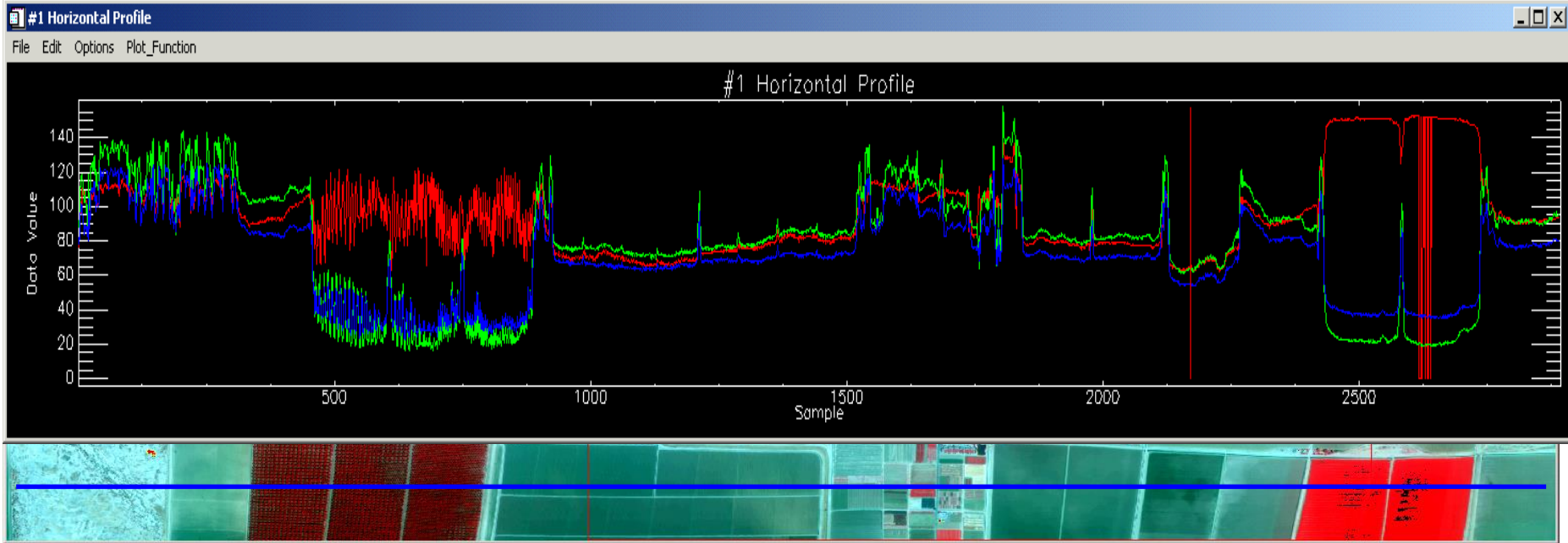


# An Example

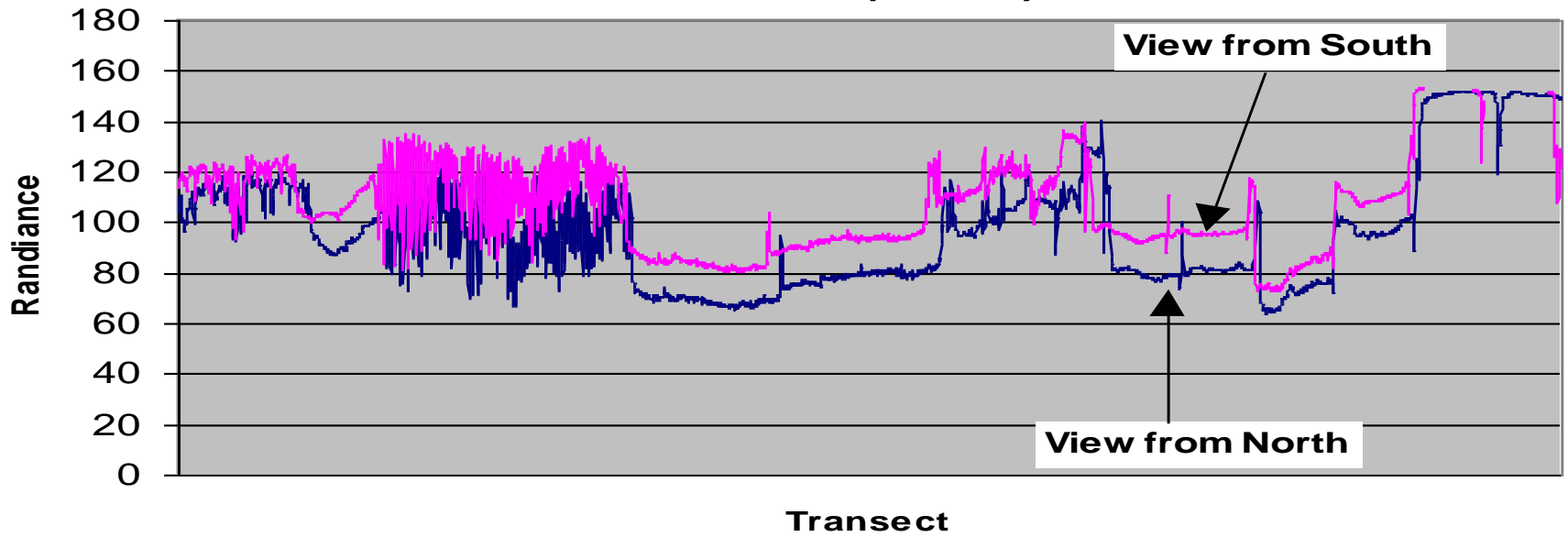


Field A is imaged twice: one from north and one from south

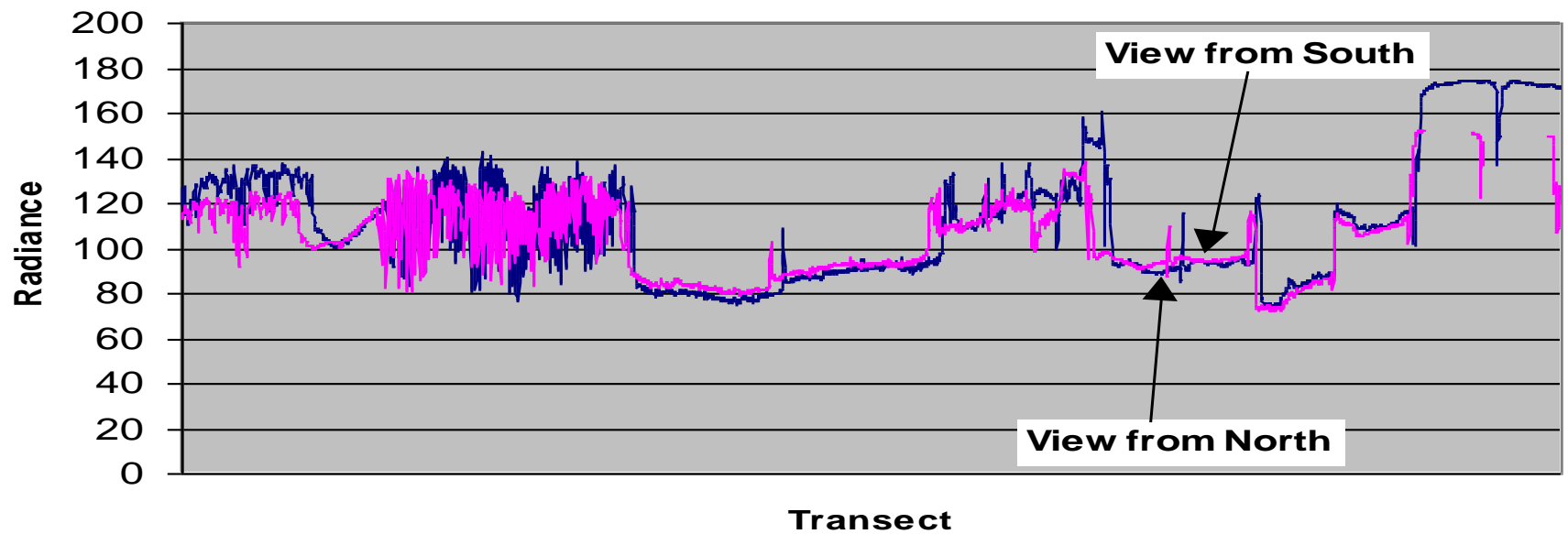




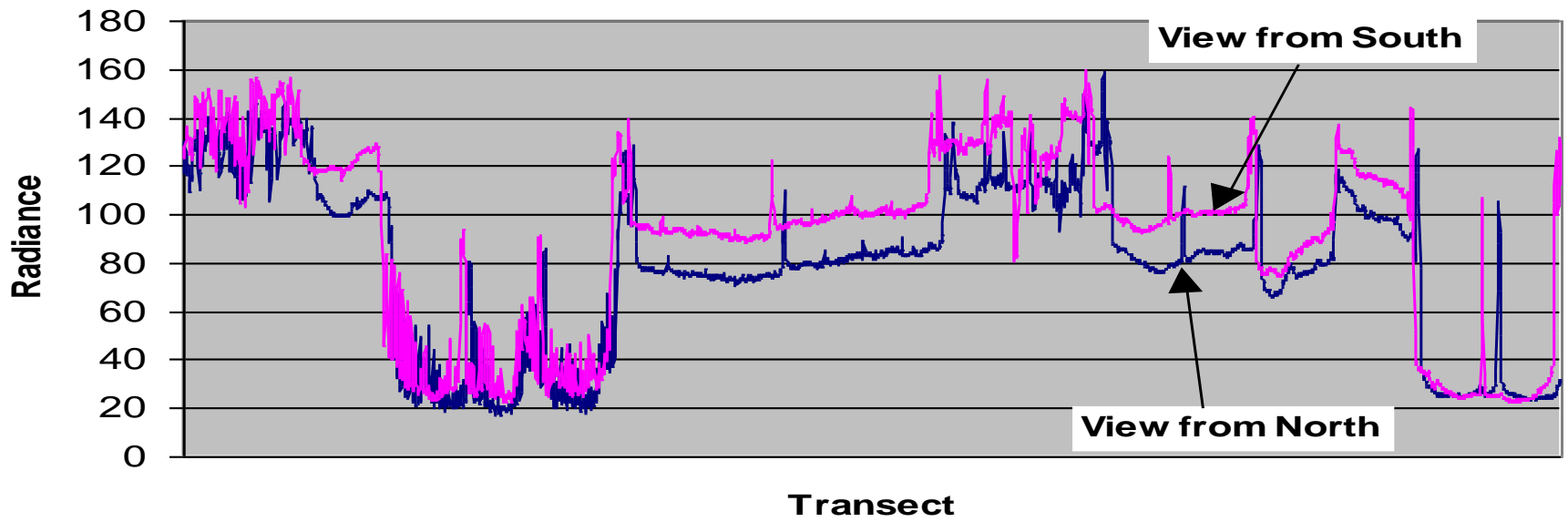
### ATLAS Band 2(Green)



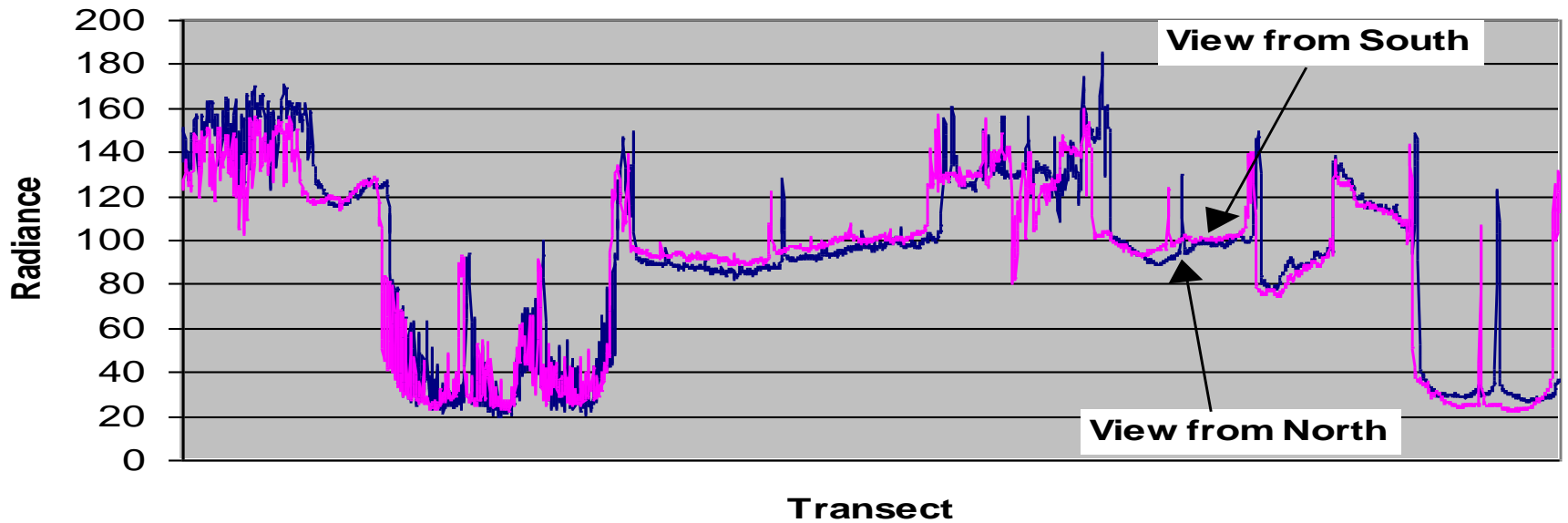
### ATLAS Band 2(Green)



### ATLAS Band 4(Red)



### ATLAS Band 4(Red)

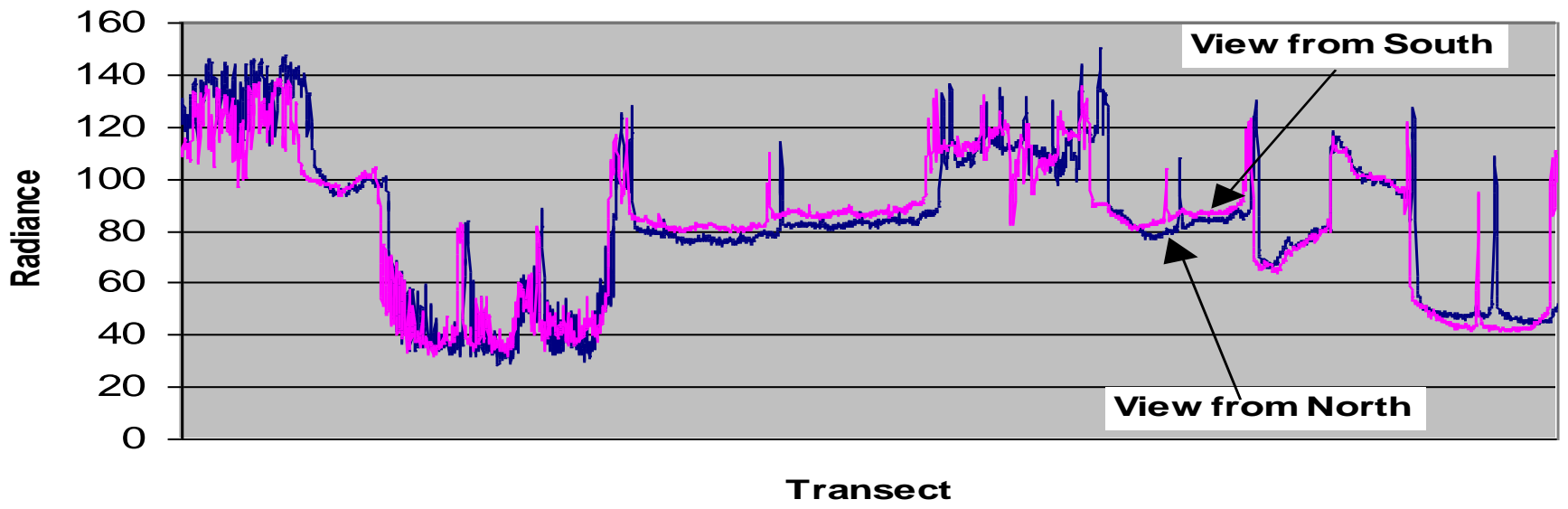




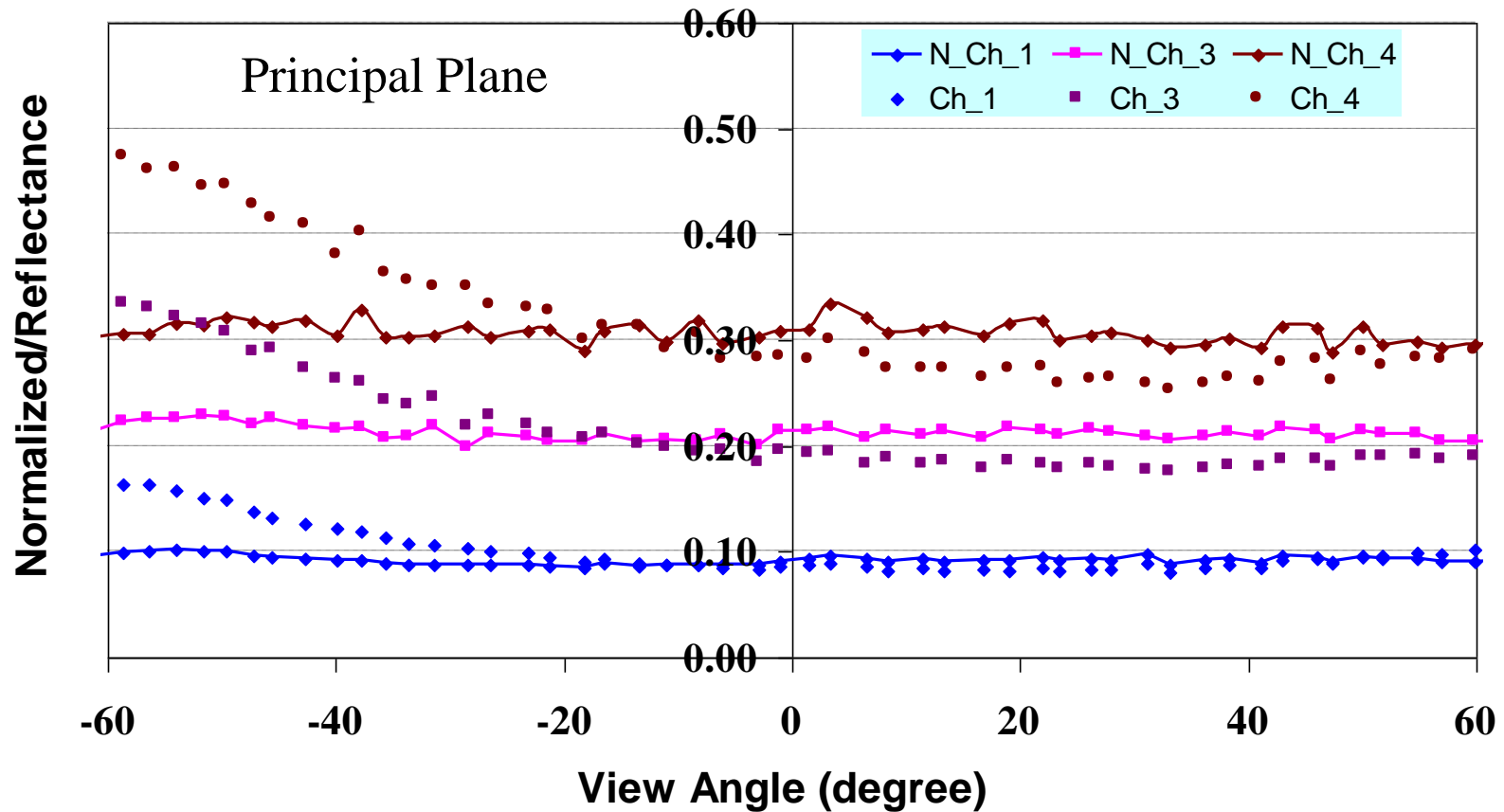
### ATLAS Band 6(NIR)



### ATLAS Band 6(NIR)



# Cotton BRDF Correction, An Example



# SUMMARY

- Bidirectional effect on remote sensing images can be significant, depending on:
  - Spectral bands;
  - Crop type
  - Stage
  - Sensor-target-sun geometry
  - Surface heterogeneity
  - May be as high as 40% or even high

# SUMMARY (*continued*)

- Bidirectional reflectance distribution function (BRDF) models exist and can be used to reduce such effect
  - Empirical models are simple and easy to use, but may have limitations
  - Physical models are preferred, but may require more model parameters
  - Semi-empirical models seem to be sufficient and easy to use
  - Neural network prove to be an easy way for non-modelers, but its accuracy depending on the training data sets
  - Their accuracy is often dictated by the inversion process, i.e., how representative your training data set is!

# SUMMARY (*continued*)

- Bidirectional effect can be “reduced” or “normalized”
  - Select a model that works for your surface type (if necessary, classification may be needed)
  - Obtain model input parameters (often by inversion processes)
  - Determine your “standard” geometric configuration
  - Compute the correction factor for each pixel
  - Use LUT when necessary
  - Examine “effectiveness”
  - Try different models, if possible
  - May need to determine a correction limit (upper or lower limits), e. g., correction factor  $f$  should be  $0.8 < f < 1.2$

# SUMMARY (*continued*)

- For operational applications
  - A “generic” model or a “generic” set of model parameters may be sufficient
  - Make sure the sensor-target-sun geometry is correctly computed

# Inverse Problems

- Obtain set of bidirectional measurements (can be field measurements, or satellite reflectance)
- Run the model in a reverse model using an optimization procedure
- Check the simulated versus the modeled results
- Make an assessment of accuracy by looking at the statistical agreement between the measured and simulated data
- Inversion may always converge!!
- How would you know if an inversion converged, i, e, inversion quality?

$$\rho(\theta_s, \theta_v, \varphi) = k_0 + k_1 f_1(\theta_s, \theta_v, \varphi) + k_2 f_2(\theta_s, \theta_v, \varphi)$$

$$\delta = \sum (\rho_o - \rho_m)^2$$